

# Propagation of Reaction Front in Porous Media with Natural Convection



Khalfi Oussama, Karam Allali

**Abstract:** This paper examines the influence of convective instability on the reaction front propagation in porous media. The model includes heat and concentration equations and motion equations under Boussinesq approximation. The non-stationary Darcy equation is adopted and the fluid is supposed to be incompressible. Numerical results are performed via the dispersion relation. The simulations show that the propagating reaction front loses stability as Vadasz number increase, it shows also more stability is gained when Zeldovich number increased.

**Key words:** Boussinesq approximation, convection, Darcy law, linear stability analysis, Vadasz number.

## I. INTRODUCTION

The reaction front propagation in porous media presents much important interest in many technological and scientific fields like biology, ecology, groundwater, hydrology, oil recovery to name just a few (see for instance (Murphy, 2000, Linninger, 2008, Stevens, 2009, Nield, 2006, Gaikwad, 2015, Faradonbeh, 2015); and references therein). In order to describe the flow dynamics in porous media, one can use the quasi-stationary or the non-stationary Darcy equation combined to reaction-diffusion equations. In porous media, the reaction front propagation under convective effect has been studied by (Allali et al., 2007, Allali, 2014); the authors have used the reaction-diffusion equations coupled with a quasi-stationary Darcy equation. In an other work, the authors in (Khalfi.O, 2016) use non-stationary Darcy equation and they study the influence of the reaction front by depicting the evolution of Zeldovich number versus wave number and versus Vadasz number highlight the influence of Vadasz number on convective instability. In this work, an extension of this last study will be done to the same model which describes the reaction front propagation with non-stationary Darcy equation; that model will be considered and delivered to linear stability analysis. For this objective, the porous media is considered to be filled by an incompressible fluid, moreover the reaction front propagates in opposite sense of gravity.

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\* Correspondence Author

**Khalfi Oussama\***, Department of Mathematics, Faculty of Science and Technology, University Hassan II, PO-Box 146, Mohammedia, Morocco

**Karam Allali**, Department of Mathematics, Faculty of Science and Technology, University Hassan II, PO-Box 146, Mohammedia, Morocco

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To perform the linear stability analysis, the Zeldovich-Frank-Kamenetskii method is used. The interface problem is obtained and the stability boundary is found from the derived dispersion relation.

This paper is organized as follows. The next section will be devoted to the governing equations, followed in Section 3 by the linear stability analysis. Numerical simulations are performed in Section 4. last section concludes the work.

## II. GOVERNING EQUATIONS

The propagating reaction front in porous media can be modelled as follows:

$$\frac{\partial T}{\partial t} + v \cdot \nabla T = \kappa \Delta T + qK(T)\phi(\alpha), \quad (1)$$

$$\frac{\partial \alpha}{\partial t} + v \cdot \nabla \alpha = d \Delta \alpha + K(T)\phi(\alpha), \quad (2)$$

$$\frac{\partial v}{\partial t} + \frac{\mu}{\kappa} v + \nabla p = g\beta\rho(T - T_0)\gamma, \quad (3)$$

$$\nabla \cdot v = 0, \quad (4)$$

under the following boundary conditions:

$$T = T_i, \alpha = 1 \text{ and } v = 0 \text{ when } y \rightarrow +\infty, \quad (5)$$

$$T = T_b, \alpha = 0 \text{ and } v = 0 \text{ when } y \rightarrow -\infty, \quad (6)$$

Here  $\beta$  denotes the coefficient of thermal expansion,  $\mu$  the viscosity,  $K_p$  the permeability of the porous media,  $\gamma$  the upward unit vector in the vertical direction,  $T$  the temperature,  $\alpha$  the depth of conversion,  $v$  the velocity,  $p$  the pressure,  $\kappa$  the coefficient of thermal diffusivity,  $d$  the diffusion coefficient,  $q$  the adiabatic heat release,  $g$  the gravity acceleration,  $\rho$  the density. Finally,  $\nabla$  and  $\Delta$  denote the standard differential operators, in addition  $T_0$  is the mean value of the temperature,  $T_i$  is an initial temperature while  $T_b$  is the temperature of the reacted mixture given by  $T_b = T_i + q$ . The function  $K(T)\phi(\alpha)$  is the reaction rate where the temperature dependence is given by the Arrhenius exponential:

$$K(T) = k_0 \exp\left(-\frac{E}{R_0 T}\right), \quad (7)$$

$E$  means the activation energy,  $R_0$  the universal gas constant and  $k_0$  the pre-exponential factor.

### 1) 2.1 THE DIMENSIONLESS MODEL

For the dimensionless model, we introduce the spatial variables  $y' = \frac{yc}{\kappa}$ ,  $x' = \frac{xc}{\kappa}$ , time  $t' = \frac{tc^2}{\kappa}$ , velocity  $v = \frac{v}{c}$  and the pressure  $p' = \frac{p\mu\kappa}{\kappa}$  are introduced.

Denoting  $\theta = \frac{T-T_b}{q}$  and omitting the primes of the new variables, the model becomes:

$$\frac{\partial \theta}{\partial t} + v \cdot \nabla \theta = \Delta \theta + W(\theta) \phi(\alpha), (8)$$

$$\frac{\partial \alpha}{\partial t} + v \cdot \nabla \alpha = \Lambda \Delta \alpha + W(\theta) \phi(\alpha), (9)$$

$$\frac{1}{V_a} \frac{\partial v}{\partial t} + v + \nabla p = R_p(\theta + \theta_0) \gamma, (10)$$

$$\nabla \cdot v = 0, (11)$$

which is supplemented by the following conditions in infinity:

$$\theta = -1, \alpha = 1 \text{ and } v = 0 \text{ when } y \rightarrow +\infty, (12)$$

$$\theta = 0, \alpha = 0 \text{ and } v = 0 \text{ when } y \rightarrow -\infty, (13)$$

Here  $W(\theta) = Z \exp(\frac{\theta}{2^{-1+\delta\theta}})$ , where  $Z = \frac{qE}{R_0 T_b^2}$  is the Zeldovich number,  $\delta = \frac{R_0 T_b}{E}$ ,  $\theta_0 = \frac{T_b - T_0}{q}$ ,  $\Lambda = \frac{d}{k}$  is the inverse of Lewis number,

$R_p = \frac{k_p c^2 p_r^2 R}{\mu^2}$  where  $R$  is the Rayleigh number defined by  $R = \frac{g \beta q k^2}{\mu c^3}$ ,  $P_r$  is the Prandtl number defined by  $P_r = \frac{\mu}{k}$ ,  $V_a = \frac{k \mu}{k_p c^2}$  is the Vadasz number (called also Darcy-Prandtl number;  $V_a$  which is given by  $V_a = \frac{D_a}{P_r}$ , where  $D_a$  is the Darcy number defined by  $D_a = \frac{c^2 k_p}{k^2}$ . In what follows,  $\Lambda = 0$  will be considered, which corresponds to liquid mixture.

### III. LINEAR STABILITY ANALYSIS

#### 1) 3.1 APPROXIMATION OF INFINITELY NARROW REACTION ZONE

By using an analytical study which reduces the problem (8)-(13) to a singular perturbation one, where the reaction zone is assumed to be narrow (which is named the reaction front), the linear stability analysis is performed. The reaction source term is neglected ahead of the reaction front (because the temperature is not sufficiently high) and behind the reaction front (since in this region there are no fresh reactant left). This approach, called Zeldovich-Frank-Kamenetskii approximation, leads to an interface problem by applying a formal asymptotic analysis for large Zeldovich number. In other words, for this asymptotic analysis treatment, let considers  $\epsilon = \frac{1}{Z}$  as a small parameter. And let assume by  $\zeta(t, x)$  the location of the reaction zone, and consider the new independent variable is

$$y_1 = y - \zeta(t, x). (14)$$

taking into account those new statements, the new functions  $\theta_1, \alpha_1, v_1, p_1$  can be written as:

$$\begin{aligned} \theta(t, x, y) &= \theta_1(t, x, y_1), \\ \alpha(t, x, y) &= \alpha_1(t, x, y_1), \\ p(t, x, y) &= p_1(t, x, y_1), \end{aligned} (15)$$

$$v(t, x, y) = v_1(t, x, y_1).$$

by the way, the equations will be re-written in the following form (the index 1 for the dependent variables is omitted):

$$\frac{\partial \theta}{\partial t} - \frac{\partial \theta}{\partial y_1} \frac{\partial \zeta}{\partial t} + v \cdot \nabla \theta = \tilde{\Delta} \theta + W(\theta) \phi(\alpha), (16)$$

$$\frac{\partial \alpha}{\partial t} - \frac{\partial \alpha}{\partial y_1} \frac{\partial \zeta}{\partial t} + v \cdot \nabla \alpha = W(\theta) \phi(\alpha). (17)$$

$$\frac{1}{V_a} \left( \frac{\partial v}{\partial t} - \frac{\partial v}{\partial y_1} \frac{\partial \zeta}{\partial t} \right) + v + \nabla p = R_p(\theta + \theta_0) \gamma, (18)$$

$$\frac{\partial v_x}{\partial x} - \frac{\partial v_x}{\partial y_1} \frac{\partial \zeta}{\partial x} + \frac{\partial v_y}{\partial y_1} = 0, (19)$$

where

$$\tilde{\Delta} = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y_1^2} - 2 \frac{\partial \zeta}{\partial x} \frac{\partial^2}{\partial x \partial y_1} + \left( \frac{\partial \zeta}{\partial x} \right)^2 \frac{\partial^2}{\partial y_1^2} - \frac{\partial^2 \zeta}{\partial x^2} \frac{\partial}{\partial y_1}, (20)$$

$$(11)$$

$$\nabla = \left( \frac{\partial}{\partial x} - \frac{\partial \zeta}{\partial x} \frac{\partial}{\partial y_1}, \frac{\partial}{\partial y_1} \right), (21)$$

to find the jump conditions approximation and solution of the interface problem, the matched asymptotic expansions method is used. To this aim, the outer solution of the problem is sought in the form:

$$\begin{aligned} \theta &= \theta^\delta + \epsilon \theta^I + \dots, \alpha = \alpha^\delta + \epsilon \alpha^I + \dots, \\ v &= v^\delta + \epsilon v^I + \dots, p = p^\delta + \epsilon p^I + \dots \end{aligned} (22)$$

For the inner solution, the stretching coordinate  $\eta = y_1/\epsilon$  is introduced and the inner solution is sought in the following form:

$$\begin{aligned} \theta &= \epsilon \theta^I + \dots, \alpha = \alpha^\delta + \epsilon \alpha^I + \dots, \\ v &= v^\delta + \epsilon v^I + \dots, p = p^\delta + \epsilon p^I + \dots, \\ \zeta &= \zeta^\delta + \epsilon \zeta^I + \dots \end{aligned} (23)$$

substituting these expansions into (16)-(19), it follows:

order  $\epsilon^{-1}$

$$\left( 1 + \left( \frac{\partial \zeta^\delta}{\partial x} \right)^2 \right) \frac{\partial^2 \theta^I}{\partial \eta^2} + \exp\left( \frac{\theta^I}{1 + \delta \theta^I} \right) \phi(\alpha^\delta) = 0, (24)$$

$$-\frac{\partial \alpha^\delta}{\partial \eta} \frac{\partial \alpha^I}{\partial t} - \frac{\partial \alpha^\delta}{\partial \eta} \left( \hat{v}_x^\delta \frac{\partial \zeta^\delta}{\partial x} - \hat{v}_y^\delta \right) = \phi(\alpha^\delta) \exp\left( \frac{\theta^I}{1 + \delta \theta^I} \right), (25)$$

$$-\frac{1}{V_a} \frac{\partial \hat{v}_x^\delta}{\partial \eta} \frac{\partial \zeta^\delta}{\partial t} - \frac{\partial \hat{p}^\delta}{\partial \eta} \frac{\partial \zeta^\delta}{\partial x} = 0, (26)$$

$$-\frac{1}{V_a} \frac{\partial \hat{v}_y^\delta}{\partial \eta} \frac{\partial \zeta^\delta}{\partial t} - \frac{\partial \hat{p}^\delta}{\partial \eta} = 0, (27)$$

$$-\frac{\partial \hat{v}_x^\delta}{\partial \eta} \frac{\partial \zeta^\delta}{\partial x} + \frac{\partial \hat{v}_y^\delta}{\partial \eta} = 0, (28)$$

order  $\epsilon^0$

$$\frac{1}{V_a} \left( \frac{\partial v_x^0}{\partial t} - \frac{\partial v_x^1}{\partial \eta} \frac{\partial \zeta^0}{\partial t} - \frac{\partial \zeta^1}{\partial t} \frac{\partial v_x^0}{\partial \eta} \right) + \frac{\partial p^0}{\partial x} - \frac{\partial p^1}{\partial \eta} \frac{\partial \zeta^1}{\partial x} - \frac{\partial p^1}{\partial \eta} \frac{\partial \zeta^0}{\partial x} + v_x^0 = R_p \theta_0, (29)$$

$$\frac{1}{V_a} \left( \frac{\partial v_y^0}{\partial t} - \frac{\partial v_y^1}{\partial \eta} \frac{\partial \zeta^0}{\partial t} - \frac{\partial \zeta^1}{\partial t} \frac{\partial v_y^0}{\partial \eta} \right) + \frac{\partial p^1}{\partial \eta} + v_y^0 = R_p \theta_0, (30)$$

order  $\epsilon^1$

$$\begin{aligned} \frac{1}{V_a} \left( \frac{\partial \hat{v}_x^0}{\partial t} - \frac{\partial \hat{v}_x^0}{\partial \eta} \frac{\partial \zeta^2}{\partial t} - \frac{\partial \zeta^1}{\partial \eta} \frac{\partial \hat{v}_x^1}{\partial t} - \frac{\partial \zeta^2}{\partial \eta} \frac{\partial \hat{v}_x^0}{\partial t} \right) \\ + \frac{\partial \hat{p}^1}{\partial x} - \frac{\partial \hat{p}^0}{\partial \eta} \frac{\partial \zeta^2}{\partial x} - \frac{\partial \hat{p}^1}{\partial \eta} \frac{\partial \zeta^1}{\partial x} - \frac{\partial \hat{p}^2}{\partial \eta} \frac{\partial \zeta^0}{\partial x} \\ + v_x^1 = R_p \theta^I, \end{aligned} (31)$$

$$\frac{1}{V_a} \left( \frac{\partial \tilde{v}_y^0}{\partial t} - \frac{\partial \tilde{v}_y^0}{\partial \eta} \frac{\partial \zeta^2}{\partial t} - \frac{\partial \zeta^1}{\partial \eta} \frac{\partial \tilde{v}_y^1}{\partial t} - \frac{\partial \zeta^2}{\partial \eta} \frac{\partial \tilde{v}_y^0}{\partial t} \right) + \frac{\partial \theta^2}{\partial \eta} + v_y^1 = R_p \theta^1 \quad (32)$$

order  $\epsilon^2$

$$\frac{\partial \tilde{v}_x^2}{\partial x} - \frac{\partial \tilde{v}_x^2}{\partial \eta} \frac{\partial \zeta^0}{\partial x} - \frac{\partial \tilde{v}_x^2}{\partial \eta} \frac{\partial \zeta^1}{\partial x} - \frac{\partial \tilde{v}_x^1}{\partial \eta} \frac{\partial \zeta^2}{\partial x} - \frac{\partial \tilde{v}_x^0}{\partial \eta} \frac{\partial \zeta^3}{\partial x} + \frac{\partial \tilde{v}_y^3}{\partial \eta} = 0 \quad (33)$$

the matching conditions as  $\eta \rightarrow \pm\infty$  are

$$\tilde{v}^0 \sim v^0|_{y_1=\pm 0} \quad (34)$$

$$\tilde{v}^1 \sim \left( \frac{\partial v^0}{\partial y_1} |_{y_1=\pm 0} \right) \eta + v^1|_{y_1=\pm 0} \quad (35)$$

$$\tilde{v}^2 \sim \frac{1}{2} \left( \frac{\partial^2 v^0}{\partial y_1^2} |_{y_1=\pm 0} \right) \eta^2 + \left( \frac{\partial v^1}{\partial y_1} |_{y_1=\pm 0} \right) \eta + v^2|_{y_1=\pm 0} \quad (36)$$

$$\tilde{v}^3 \sim \frac{1}{6} \left( \frac{\partial^3 v^0}{\partial y_1^3} |_{y_1=\pm 0} \right) + \frac{1}{2} \left( \frac{\partial^2 v^1}{\partial y_1^2} |_{y_1=\pm 0} \right) \eta^2 + \left( \frac{\partial v^2}{\partial y_1} |_{y_1=\pm 0} \right) \eta + v^3|_{y_1=\pm 0} \quad (37)$$

Let us consider both the outer and the inner expansion of the temperature (the same technique for the variables  $\alpha$  and  $v$  is used) and recall that

$$\eta = y_1/\epsilon: \theta(x, y_1) = \theta^0(x, y_1) + \epsilon \theta^1(x, y_1) + \epsilon^2 \theta^2(x, y_1) + \dots$$

$$\theta(x, \epsilon \eta) = \epsilon \theta^1(x, \eta) + \epsilon^2 \theta^2(x, \eta) + \dots$$

Writing the outer solution in terms of the inner variable  $\eta$  and using the Taylor expansion:

$$\theta(x, y_1) = \theta^0(x, 0) + \epsilon \left( \frac{\partial \theta^0}{\partial \eta}(x, 0) \eta + \theta^1(x, 0) \right) + \epsilon^2 \left( \frac{1}{2} \frac{\partial^2 \theta^0}{\partial \eta^2}(x, 0) \eta^2 + \frac{\partial \theta^1}{\partial \eta}(x, 0) \eta + \theta^2(x, 0) \right) + \dots \quad (46)$$

The zero order terms with respect to  $\epsilon$  correspond to the stationary solution. Taking into account that  $\frac{\partial \theta^0}{\partial \eta}(x, 0^-) = 0$  and using the matching principle (Nayfeh, 2008), it follows the matching conditions:

$$\eta \rightarrow +\infty: \theta^1 \sim \theta^1|_{y_1=0^+} + \eta \frac{\partial \theta^0}{\partial y_1} |_{y_1=0^+}, \quad \tilde{\alpha}^0 \rightarrow 0, v^0 \rightarrow v^0|_{y_1=0^+} \quad (38)$$

$$\eta \rightarrow -\infty: \theta^1 \rightarrow \theta^1|_{y_1=0^-}, \tilde{\alpha}^0 \rightarrow 1, \quad v^0 \rightarrow v^0|_{y_1=0^-} \quad (39)$$

Denoting by  $s$  the quantity

$$s = \tilde{v}_x^0 \frac{\partial \zeta^0}{\partial x} - \tilde{v}_y^0 \quad (40)$$

Relation (28) gives that the parameter  $s$  does not depend on  $\eta$ . The jump conditions are derived from (24), in the same way as it is usually done for combustion problems. From (25), it follows that  $\tilde{\alpha}^0$  is a monotone function of  $\eta$  and  $0 < \tilde{\alpha}^0 < 1$ . Since zero-order reaction is considered, it results  $\phi(\tilde{\alpha}^0) \equiv 1$ .

Using (24), one concludes that  $\frac{\partial^2 \theta^1}{\partial \eta^2} \leq 0$ . when  $\eta \rightarrow -\infty$  and taking into account (39), one has  $\frac{\partial \theta^1}{\partial \eta} = 0$ . Then  $\frac{\partial \theta^1}{\partial \eta} \leq 0$  and  $\theta^1$  is a monotone function.

Multiplying (24) by  $\frac{\partial \theta^1}{\partial \eta}$  and integrating with respect to  $\eta$  from  $-\infty$  to  $+\infty$  taking into account (38), (39) ( $\theta^1$  changes from  $\theta^1|_{y_1=0^-}$  to  $-\infty$  when  $\eta$  changes from  $-\infty$  to  $+\infty$ ):

$$\left( \frac{\partial \theta^1}{\partial \eta} \right)^2 |_{\eta=+\infty} - \left( \frac{\partial \theta^1}{\partial \eta} \right)^2 |_{\eta=-\infty} = \frac{1}{A} \int_{-\infty}^{\theta^1|_{y_1=0^-}} \exp\left(\frac{\tau}{1+\delta\tau}\right) d\tau \quad (41)$$

where

$$A = 1 + \left( \frac{\partial \zeta^0}{\partial x} \right)^2 \quad (42)$$

By adding (24) and (25) and integrating, (34)

one obtains:

$$\frac{\partial \theta^1}{\partial \eta} |_{\eta=+\infty} - \frac{\partial \theta^1}{\partial \eta} |_{\eta=-\infty} = -\frac{1}{A} \left( \frac{\partial \zeta^0}{\partial x} + s \right) \quad (43)$$

Truncating the outer expansion (22), it follows that  $\theta \approx \theta^0, \zeta^0 \approx \zeta, v \approx v^0$ . From the inner expansion (23), one obtains  $Z\theta \approx \theta^1$ , and from the matching condition (39),  $\theta^1|_{\eta=-\infty} \approx \theta^1|_{y_1=0^-} \approx Z\theta|_{y_1=0^-}$ . Thus,  $\theta^0 \approx \theta, \theta^1|_{y_1=0^-} \approx Z\theta|_{y_1=0}, \zeta^0 \approx \zeta, v \approx v^0$ . (44)

The jump conditions are obtained (with the change of variables  $\tau \rightarrow Z\tau$  under the integral)

$$\left( \frac{\partial \theta}{\partial y_1} \right)^2 |_{y_1=0^+} - \left( \frac{\partial \theta}{\partial y_1} \right)^2 |_{y_1=0^-} = 2Z \left( 1 + \left( \frac{\partial \zeta}{\partial x} \right)^2 \right)^{-1} \times \int_{-\infty}^{\theta^1|_{y_1=0^-}} \exp\left(\frac{\tau}{z^{-1}+\delta\tau}\right) d\tau \quad (45)$$

$$\frac{\partial \theta}{\partial y_1} |_{y_1=0^+} - \frac{\partial \theta}{\partial y_1} |_{y_1=0^-} = -\left( 1 + \left( \frac{\partial \zeta}{\partial x} \right)^2 \right)^{-1} \times \left( \frac{\partial \zeta}{\partial x} + (v_x \frac{\partial \zeta}{\partial x} - v_y) |_{y_1=0} \right) + v_z |_{z_1=0^+} - v_z |_{z_1=0^-} \quad (46)$$

$$\frac{\partial v_y}{\partial y_1} |_{y_1=0^+} = \frac{\partial v_y}{\partial y_1} |_{y_1=0^-} \quad (48)$$

$$\frac{\partial^2 v_y}{\partial y_1^2} |_{y_1=0^+} = \frac{\partial^2 v_y}{\partial y_1^2} |_{y_1=0^-} \quad (49)$$

$$\frac{\partial^3 v_y}{\partial y_1^3} |_{y_1=0^-} - \frac{\partial^3 v_y}{\partial y_1^3} |_{y_1=0^+} = -R_p \left( 1 + \left( \frac{\partial \zeta}{\partial x} \right)^2 \right)^{-1} \times \left( \left( 1 + \left( \frac{\partial \zeta}{\partial x} \right)^2 \right)^{-1} - 1 \right) \frac{\partial \theta}{\partial y} |_{y_1=0^+} \quad (50)$$

Here only the component  $v_y$  of the velocity is used. (38)

### 2) 3.2 FORMULATION OF THE INTERFACE PROBLEM

The interface problem will be written in two system of equations one for the media before reaction, and one for the media after reaction; and for the jump conditions they will be extracted from the free boundary problem seen previously.

To find the jump conditions approximation and solution of the interface problem, the matched asymptotic expansions method is used, this leads to:

for unburnt medium ( $y > \zeta$ ):

$$\frac{\partial \theta}{\partial \tau} + v \cdot \nabla \theta = \Delta \theta \quad (51)$$

$$\alpha \equiv 0 \quad (52)$$

$$\frac{1}{V_a} \frac{\partial v}{\partial \tau} + v + \nabla p = R_p (\theta + \theta_0) \gamma \quad (53)$$

$$\nabla \cdot v = 0 \quad (54)$$

and for the burnt medium

( $y < \zeta$ ):



$$\frac{\partial \theta}{\partial t} + v \cdot \nabla \theta = \Delta \theta, (55)$$

$$\alpha \equiv 1, (56)$$

$$\frac{1}{V_a} \frac{\partial v}{\partial t} + v + \nabla p = R_p (\theta + \theta_0) \gamma, (57)$$

$$\nabla \cdot v = 0, (58)$$

These systems is completed by the following jump conditions at the interface  $y = \zeta$ :

$$[\theta] = 0, \left[ \frac{\partial \theta}{\partial y} \right] = \frac{\frac{\partial \zeta}{\partial t}}{1 + \left( \frac{\partial \zeta}{\partial x} \right)^2} (59)$$

$$\left[ \left( \frac{\partial \theta}{\partial y} \right)^2 \right] = - \frac{2z}{1 + \left( \frac{\partial \zeta}{\partial x} \right)^2} \int_{-\infty}^{\theta(t,x,\zeta)} \exp\left(\frac{s}{z + \delta s}\right) ds, (60)$$

$$[v] = 0, (61)$$

$$\left[ \frac{\partial v}{\partial y} \right] = 0, (62)$$

$$\left[ \frac{\partial^2 v}{\partial y^2} \right] = 0, (63)$$

with  $[f]$  denotes the jump at the interface,

$$[f] = f|_{\zeta_0^+} - f|_{\zeta_0^-}.$$

This free boundary problem is completed by the following conditions:

$$\theta = -1 \text{ and } v = 0 \text{ when } y \rightarrow +\infty, (64)$$

$$\theta = 0 \text{ and } v = 0 \text{ when } y \rightarrow -\infty. (65)$$

### 3) 3.3 TRAVELLING WAVE SOLUTION

In this subsection, the linear stability analysis of the steady-state solution for the interface problem is performed. Indeed, this interface problem has a travelling wave solution  $(\theta, \alpha, v)$  such as:

$$\begin{aligned} \theta(t, x, y) &= \theta_s(y - ut), \\ \alpha(t, x, y) &= \alpha_s(y - ut), v = 0, \zeta = ut, \end{aligned} (66)$$

with

$$\theta_s(y_1) = \begin{cases} 0 & \text{if } y_1 < 0 \\ e^{-uy_1} - 1 & \text{if } y_1 > 0 \end{cases} (67)$$

and

$$\alpha_s(y_1) = \begin{cases} 1 & \text{if } y_1 < 0 \\ 0 & \text{if } y_1 > 0 \end{cases} (68)$$

here  $y_1 = y - ut$  denotes the moving coordinate frame, where  $u$  is the wave speed. With these coordinates, the travelling wave is a stationary solution of the problem:

$$\frac{\partial \theta}{\partial \tau} + u \frac{\partial \theta}{\partial y_1} + v \cdot \nabla \theta = \Delta \theta, (69)$$

$$\frac{1}{V_a} \frac{\partial v}{\partial \tau} + v + \nabla p = R_p (\theta + \theta_0) \gamma, (70)$$

$$\nabla \cdot v = 0, (71)$$

supplemented with the jump conditions (59)-(63).

Consider now a small time-dependent perturbation of the stationary solution of the form. To be done, let's choose the perturbation of the temperature and the velocity in the following form:

$$\theta(t, x, y) = \theta_s(y - ut) + \theta_j(z) e^{\omega t + ikx}, j = 1, 2, (72)$$

$$v_j(t, x, y) = v_j(z) e^{\omega t + ikx}, (73)$$

where

$$z = y - \zeta(t, x) = y - ut - \xi(t, x),$$

$$\xi(t, x) = \epsilon_1 e^{\omega t + ikx}, (74)$$

$j = 1$  corresponds to  $z < 0$  and  $j = 2$  to  $z > 0$ .

Now, the system (69)-(71) needs to be linearized around the stationary solution. For simplicity, the pressure  $p$  and the

component  $v_x$  of the velocity will be eliminated from the interface problem by applying two times the operator *curl*. Hence, this expression is obtained by applying this transformation to the equation (70):

$$\frac{1}{V_a} \frac{\partial}{\partial t} (\nabla \times (\nabla \times v)) + \nabla \times (\nabla \times v) = R_p \nabla \times (\nabla \times (\theta + \theta_0) \gamma), (58)$$

$$\text{thus } \frac{1}{V_a} \frac{\partial}{\partial t} (\nabla(\nabla \cdot v) - \Delta v) + \nabla(\nabla \cdot v) - \Delta v = R_p (\nabla(\nabla \cdot (\theta + \theta_0) \gamma) - \Delta (\theta + \theta_0) \gamma), (59)$$

due to the incompressibility of the fluid, it deduced

$$\frac{1}{V_a} \frac{\partial}{\partial t} (-\Delta v) + (-\Delta v) = -R_p (\nabla(\nabla \cdot (\theta \gamma)) - \Delta \theta \gamma), (60)$$

which drive to

$$\begin{aligned} \frac{-1}{V_a} \frac{\partial}{\partial t} \left( \frac{\partial^2 v_y}{\partial x^2} + \frac{\partial^2 v_y}{\partial y^2} \right) - \left( \frac{\partial^2 v_y}{\partial x^2} + \frac{\partial^2 v_y}{\partial y^2} \right) = \\ R_p \left( \frac{\partial^2 \theta}{\partial y^2} - \left( \frac{\partial^2 \theta}{\partial x^2} + \frac{\partial^2 \theta}{\partial y^2} \right) \right), \end{aligned}$$

by replacing  $v_y$  by its value (73), it result

$$\frac{1}{V_a} \frac{\partial}{\partial t} (-k^2 v_j e^{\omega t + ikx} + v_j^i e^{\omega t + ikx}) + (-k^2 v_j e^{\omega t + ikx} + v_j^i e^{\omega t + ikx}) = (-k^2 \theta_j) e^{\omega t + ikx},$$

so

$$\frac{\omega}{V_a} (-k^2 v_j + v_j^i) + (-k^2 v_j + v_j^i) = R_p (-k^2 \theta_j).$$

From below, the following differential systems of equations are obtained:

$$\text{for } z < 0: (66)$$

$$\theta_1'' + u \theta_1' - (\omega + k^2) \theta_1 = 0, (75)$$

$$v_1^i - k^2 v_1 = - \frac{V_a}{\omega + V_a} R_p k^2 \theta_1. (76)$$

$$(68)$$

for  $z > 0$ :

$$\theta_2'' + u \theta_2' - (\omega + k^2) \theta_2 = -v_2 u e^{-uz}, (77)$$

$$v_2^i - k^2 v_2 = - \frac{V_a}{\omega + V_a} R_p k^2 \theta_2. (78)$$

these systems is supplemented with the following linearized jump conditions:

$$\theta_2(0) - \theta_1(0) = u \epsilon_1, (79)$$

$$\theta_2'(0) - \theta_1'(0) = -\epsilon_1 (u^2 + \omega), (80)$$

$$-u(u^2 \epsilon_1 + \theta_2'(0)) = Z \theta_1(0), (81)$$

$$v_1^{(i)}(0) = v_2^{(i)}(0) \text{ for } i = 0, 1, (82)$$

where

$$v^{(i)} = \frac{\partial^i v}{\partial z^i}, \theta^i = \frac{\partial \theta}{\partial y_1},$$

for  $z < 0$ , the resolution of (75) and (76) gives:

$$\theta_1(z) = \alpha_1 e^{\mu z},$$

$$v_1(z) = a_1 \frac{R_p k^2 V_a}{(k^2 - \mu^2)(\omega + V_a)} e^{\mu z} + a_2 e^{kz} \quad (83)$$

with  $\mu = \frac{-u + \sqrt{u^2 + 4(\omega + k^2)}}{2}$   
and for  $z > 0$ , the resolution of (77) and (78) gives:

$$v_2(z) = b_1 w_1 + b_2 w_2, \theta_2(z) = b_1 s_1 + b_2 s_2,$$

with

$$w_i(z) = \sum_{j \geq 1} a_{i,j} e^{\sigma_{i,j} z} \text{ and } s_i(z) = \sum_{j \geq 1} c_{i,j} e^{\sigma_{i,j} z} \quad \text{for } i = 1, 2 \quad (84)$$

here  $a_1, b_1, a_2,$  and  $b_2$  are arbitrary constants and the coefficients  $a_{i,j}, \sigma_{i,j}$  are given by:

$$\begin{aligned} \sigma_{1,1} &= \frac{-u - \sqrt{u^2 + 4(\omega + k^2)}}{2}, \sigma_{2,1} = -k, \\ c_{1,1} &= 1, c_{2,1} = 0, a_{1,1} = 0, a_{2,1} = 1, \\ \forall j \geq 1: \sigma_{i,j+1} &= \sigma_{i,j} - u \text{ for } i = 1, 2, \\ \forall j \geq 1: c_{i,j+1} &= \frac{-u}{\sigma_{i,j+1}^2 + u \sigma_{i,j+1} - (\omega + k^2)} c_{i,j} \\ \text{for } i &= 1, 2 \end{aligned}$$

with respect of the conditions:

$$\begin{aligned} (V_a + \omega) &\neq 0, \\ \forall j \geq 1: \sigma_{i,j+1}^2 + u \sigma_{i,j+1} - (\omega + k^2) &\neq 0 \\ \text{for } i &= 1, 2, \\ \forall j \geq 1: (\sigma_{i,j}^2 - k^2) &\neq 0 \\ \text{for } i &= 1, 2, \end{aligned}$$

$$\forall j \geq 1: a_{i,j} = \frac{-R_p k^2 V_a}{(V_a + \omega)(\sigma_{i,j}^2 - k^2)} c_{i,j}$$

for  $i = 1, 2$  and  $(i, j) \neq (2, 1)$ .

The constants are sought from the jump condition

$$\begin{cases} b_1 s_1(0) + b_2 s_2(0) - a_1 = u \epsilon_1 \\ b_1 s'_1(0) + b_2 s'_2(0) - \mu a_1 = -\epsilon_1 (u^2 + \omega) \\ b_1 s''_1(0) + b_2 s''_2(0) + a_1 \frac{Z}{u} = -u^2 \epsilon_1 \\ b_1 w_1(0) + b_2 w_2(0) + \frac{V_a R_p k^2 a_1}{(\omega + V_a)(\mu^2 - k^2)} - a_2 = 0 \\ b_1 w'_1(0) + b_2 w'_2(0) + \frac{V_a R_p k^2 \mu a_1}{(\omega + V_a)(\mu^2 - k^2)} - k a_2 = 0 \end{cases} \quad (86)$$

to find the dispersion relation, it is convenient to subtract the third equation from second equation of the system (86), which gives:

$$a_1 = \frac{u\omega}{u\mu + Z} \epsilon_1 \quad (87)$$

Now by using the right linear combination of the first and second lines in (86), the coefficients  $b_1$  and  $b_2$  are obtained

$$b_1 = \frac{(a_1 + u \epsilon_1) s'_2(0) + (\epsilon_1 (u^2 + \omega) - \mu a_1) s_2(0)}{s'_2(0) s_1(0) - s_2(0) s'_1(0)},$$

$$= \frac{(u s'_2(0) + (u^2 + \omega) s_2(0)) \epsilon_1 + (s'_2(0) - \mu s_2(0)) a_1}{s'_2(0) s_1(0) - s_2(0) s'_1(0)} \quad (88)$$

$$b_2 = \frac{(a_1 + u \epsilon_1) s'_1(0) + (\epsilon_1 (u^2 + \omega) - \mu a_1) s_1(0)}{s'_1(0) s_2(0) - s_1(0) s'_2(0)},$$

$$= \frac{(u s'_1(0) + (u^2 + \omega) s_1(0)) \epsilon_1 + (s'_1(0) - \mu s_1(0)) a_1}{s'_1(0) s_2(0) - s_1(0) s'_2(0)},$$

to obtain  $a_2$ , the fourth line in the system (86) will be used. That's leads:

$$a_2 = b_1 w_1(0) + b_2 w_2(0) + \frac{V_a R_p k^2}{(\omega + V_a)(\mu^2 - k^2)} a_1.$$

at end from the fifth equation of the system (86), the following dispersion relation is obtained:

$$\frac{(k w_1(0) - w'_1(0))(B u \omega + F(u \mu + Z))}{(u \mu + Z) D} + \frac{(A u \omega + E(u \mu + Z))(k w_2(0) - w'_2(0))}{(u \mu + Z) C} + \frac{V_a R_p k^2 u \omega}{(\omega + V_a)(\mu + k)(u \mu + Z)} = 0 \quad (91)$$

with

$$\begin{aligned} A &= s'_1(0) - \mu s_1(0), B = s'_2(0) - \mu s_2(0), \\ C &= -s'_1(0) s_2(0) + s_1(0) s'_2(0), \\ D &= -s'_2(0) s_1(0) + s_2(0) s'_1(0), \\ E &= u s'_1(0) + (u^2 + \omega) s_1(0), \\ F &= u s'_2(0) + (u^2 + \omega) s_2(0). \end{aligned}$$

#### IV. NUMERICAL SIMULATIONS

The dispersion relation (91) is solved numerically by using Maple software and the convergence of the series (84) is tested within small tolerance limit. This gives the stability threshold of the reaction front. From (83), (85) and (87), it's seen that when  $\omega = 0$ , Vadasz number will not affect the stability threshold. For this reason, those numerical simulations will check the oscillatory stability threshold.

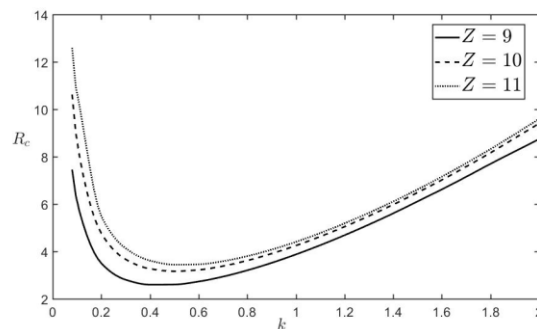
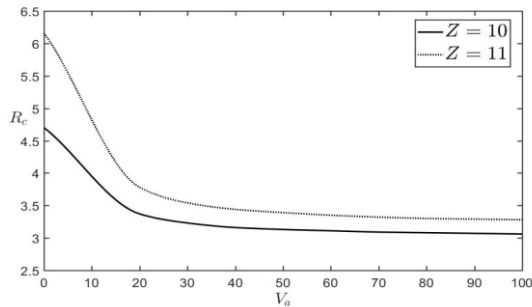


Figure 1: Critical Rayley  $R$  versus wave number  $k$  for different values of Zeldovich number  $Z$  and for  $V_a = 40$ .

Following the same steps as in (Khalfi, O, 2016), the interface problem is solved by introducing the travelling wave solution and reducing the system to a dispersion relation. Figure 1 shows the evolution of critical Rayleigh number  $R_c$  as function of wave number  $k$  for different values of Zeldovich number with  $u = \sqrt{2}$ . Here, it is remarked that the reaction front gains stability when Zeldovich number increases. It can also be seen that for small values of  $k$  ( $k < 0.4$ ) the number critical Rayleigh becomes very large and  $R_c$  increases with the wave number  $k$  when ( $k < 0.4$ ).



**Figure 2: Critical Rayleigh number  $R_c$  versus Vadasz number  $V_a$  for different values of Zeldovich number  $Z$  and for  $k = 0.5$ .**

the critical Rayleigh number  $R_c$  versus Vadasz number for different values of Zeldovich number with  $u = \sqrt{2}$  and  $V_a = 40$  is shown in figure 2. Here, the loss of stability is visible when Vadasz number  $V_a$  increases, it is also remarked that the loss of stability is more important for a bigger values of Zeldovich number  $Z$ .

## V. CONCLUSIONS

In this paper, we have studied a problem describing the reaction front propagation in porous media. The model consists of two reaction diffusion equations of heat and concentration coupled of those of hydrodynamics under Darcy law.

It was observed that the key parameters of the problem play an essential role in the convective stability of the propagating reaction front. Indeed, it was observed that the reaction front gains stability when Zeldovich number increases, also the loss of stability is remarked when Vadasz number increases.

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## AUTHORS PROFILE



**Oussama Khalfi** is pursuing his Doctorate in applied mathematics from Faculty of Sciences and Technologies, Hassan 2 University of Casablanca and member of Laboratory Mathematics and Applications. He received Master degree from the Faculty of Sciences at the Mohammed V University of Rabat, Morocco, where he

defended his master thesis on Sylvester equation solution by using Arnoldi process. He has two publications in reputed, peer reviewed International Journal, the first one was in IJAAMM titled “On convective instability of reaction fronts in porous media using the Darcy-Brinkman formulation” and the second was in AJMHT titled “Influence of Vadasz Number on Convective Instability of Reaction Front in Porous Media”. He also participates in many national and international conferences. His research area includes numerical analysis, convection, fluid dynamics, partial differential equations, linear stability analysis, modelling physical problems, frontal polymerization, reaction front and other areas.



**Karam Allali** is a Professor at Faculty of Sciences and Technologies, Hassan 2 University of Casablanca, Morocco and the head of Laboratory Mathematics and Applications. He received Master degree from the Faculty of Sciences at the University of Rabat, Morocco, and received a PhD in Applied Mathematics from the University of Lyon, France. His research activities are mainly focused on mathematical modelling and numerical simulations. He has total academic teaching experience of more than fifteen years with more than fifty publications in international journals. His research area includes numerical analysis, biomathematics, natural convection, fluid mechanics, scheduling, vibration, nonlinear dynamics, dynamical systems, combustion, frontal polymerization, reaction front, chaotic systems and other areas.