

Research and Modelling of Surface Roughness, Cutting Forces and I-kaz Coefficients for S42C in Turning using Response Surface Methodology

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Abstract— This paper presents the optimization in machining processes on the cutting parameters for the S45C in turning process using the response surface method (RSM). The experimental work conducted investigates the influence of cutting parameters on statistical analysis of signals and surface quality. The paper also presents a statistical analysis of signal processing. The cutting force was measured during machining using the Kistler 9129AA dynamometer to monitor the force signals and the data was analyzed using the I-kazTM method of statistical analysis. This statistical analysis was used to assess the effect of force signals during the machining process. The RSM models for Ra and Rz, and I-kaz coefficients (Z_{\square}) have been developed with ANOVA and multiple regression equations. The models also were compared and validated with the predicted and measured of Ra and Rz values, and I-kaz coefficients. The optimal configuration of cutting parameters was observed at 200 m/min, 0.1 mm/rev and 0.521 mm with desirability of 95.9%. It is observed that the models developed are suggested to be utilized for predicting surface roughness values and I-kaz coefficients for the machining of S45C steel.

Keywords: Cutting force, I-kazTM, response surface methodology, surface quality, turning.

I. INTRODUCTION

Nowadays, machining processes involve measuring, modelling, prediction, and optimization to produce products that require very high surface quality. Research in machining process still presents a challenge, because cutting parameters or cutting processes must be considered in order to determine the optimal process of machining conditions. In the turning processes, the cutting parameters commonly identified are materials and cutting tools. Meanwhile, the cutting processes are influenced by the tool condition, chatter, surface finish, dimensional precision, chip formation and cooling method. In order to model the machining, some researchers apply modelling approaches in their research. In [1] created the homotopy perturbation model for chatter prediction in turning using spindle speed variation technique and a mathematical model which it is showed good

agreement with experimental cutting tests. In [2] used an energy based modelling for prediction of process damping in milling and turning. Their results were useful for chatter stability analysis with low cutting speeds. In [3] studied the Kelvin-Voigt model that used to minimize the tool overshoot using computational objective function that influence the machining process, surface finish and tool life issues. In [4] mentioned that an understanding of measurement uncertainty of the model is required for a machine tool to produce the product quality and this is influenced by the model accuracy from the cutting tool that is utilized to post-process the CAD model.

Statistical methods were extensively used in machining for finding out the significance of cutting processes and parameters based on the modelling, prediction and optimization. In [5] carried out the response surface methodology which depended on faced centred composite design and ANOVA with mathematical modelling of surface roughness and flank wear for Monel-400 workpiece in turning process. From the regression equation, maximum errors between predicted and experimental measures obtained were 7% for surface roughness and 13% for flank wear. In [6] concluded that, compared to cutting speed and feed rate, the depth of cut has the largest influence on force signals. They used the AISI 52100 workpiece through RSM and ANNOVA with consideration for the optimization goals between surface roughness and cutting force values in tangential, thrust and feed forces. The goals of this research were to evaluate the correlation between surface roughness, cutting forces and statistical method I-KazTM to cutting parameters and then to determine the optimization model by using response surface methodology.

II. METHODOLOGY

A. Material and Workpiece

The experimental works in this paper were tested on a round bar work piece of medium carbon steel S45C with a diameter of 75 mm and length of 250 mm. Mild steel S45C is a medium carbon steel according to the Japanese Industrial Standard (JIS). These steel pieces have high weldability and machinability, and they can be subjected to various heat treatments. JIS S45C is medium strength steel and most commonly used in mechanical parts because its cost is comparatively small and it offers material properties suitable for many applications. The original Hardness

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Rockwell B is 59 HRB. This workpiece has nominal material properties of 0.42 per cent Carbon, 98.51 per cent to 98.98 per cent Iron, 0.15 per cent to 0.35 per cent Silicon, 0.6 per cent to 0.9 per cent Maganese, 0.03 per cent Plumbum and 0.035 per cent Sulphur. The end of the workpiece is clamped in a chuck and the other end is supported by a tailstock. In [7] classified the ratio of length to diameter used is 3:1 to 6:1. The length to diameter for this work piece in this paper is 3.33:1, which falls within the acceptable range of the ratio. The range of machine parameters was chosen during the investigation on the recommendation of the manufacturer of the cutting tool.

B. Experimental Procedure

Machining experiments were conducted to investigate the impact of the cutting parameters on the workpiece's surface roughness and I-kazTM's signal processing. The experiment was performed on the turning process using a computer numerical control (CNC) lathe machine. The lathe machine (Mazak SQT 200MY) was used for performing the machining operation. The cutting tool materials were selected based on the workpiece materials to be cut. Based on the recommendations of the cutting tool manual and the cutting manual, cutting tool inserts of coated carbide were used for turning of mild steel S45C material.

Table I shows that the cutting parameters in this experiment is 200-300 m/min for cutting speed, 0.5-1.5 mm for the depth of cut and 0.1-0.2 mm/rev for the feed rate. The machine tool was used the tool holder type ECLNR-2020K12 carbide by Chain designed with ISO 9001:2015 to hold the CVD-coated carbide insert type CNMG12044N-GU AC2000 by Sumitomo.

Table- I: Factor and response levels for the turning process

Level Factors		Unit	Responses		
			1	2	3
Cutting speed	<i>V_c</i>	m/min	200	250	300
Feed rate	<i>f</i>	mm/rev	0.10	0.15	0.20
Depth of cut	<i>d</i>	mm	0.50	1.00	1.50

The turning experiment conducted refers to the ISO3685 standard (ISO 3685, 1993). The cutting process was conducted without the use of cutting fluid for the S45C.

This paper uses the arithmetic average of the roughness profile, *R_a* and mean depth of profile surface roughness, *R_z* values. On the machined workpiece, the surface roughness, *R_a* and *R_z* were measured using the MarSurf PS1 gauge. The *R_a* and *R_z* values are the commonly used roughness parameter and most appropriate for observing the surface quality of the machining processes [8]-[11]. The force signals were measured using a dynamometer by Kistler type 9129AA and placed on the tool frame, measuring the force signals in the direction of tangential and cutting (to the moving workpiece), feed and also in the direction of radial or thrust.

C. Statistical Analysis Method

The I-kaz coefficient, $Z^{-\infty}$ was determined by statistical moments based on average value, standard deviation, root mean square and kurtosis. The first central moment is the expectation value for mean, which is the central location of

a distribution and is given in (1). In practice it is estimated by the average or the mean deviation from the mean as shown in (2). For the chosen workpiece and tool material combination, Wang et al. (2014) used average forces for *X* and *Y* directions [12].

$$\mu = E(\bar{x}) = \frac{1}{n} \sum_{i=1}^n x_i \quad (1)$$

$$\bar{x} = \frac{1}{n} \sum_{i=1}^n (x_i - \mu) \quad (2)$$

Since the first moment data is for mean, μ the second statistical moment is for variance (*var*) and the standard deviation, σ . The average deviation, $(x_i - \mu)$ is a more robust analysis tool of the width of the peak appearance. In (3) shows the variance, it provides a measure of the data spread and it is frequently used interchangeably with its positive square root, defining the standard deviation in (4).

$$\text{var} = \frac{1}{n} \sum_{i=1}^n (x_i - \mu)^2 \quad (3)$$

$$\sigma = \sqrt{\text{var}} = \frac{1}{n} \sum_{i=1}^n (x_i - \mu) \quad (4)$$

In (5) shows the third central moment, skewness (*S*) which identifies a distribution's degree of asymmetry around its mean. Wang et al. (2017) used skew, mean and kurtosis to assess surface roughness and used wavelet packet transform to extract surface texture [13]. They found that the mean, skewness and kurtosis values increased with the rise in noise, meaning that these statistical moments are influenced by noise much stronger than surface roughness values. The skewness is a non-dimensional quantity.

$$S = \frac{1}{n} \sum_{i=1}^n \left(\frac{x_i - \mu}{\sigma} \right)^3 \quad (5)$$

The fourth-order statistical moment is kurtosis (*K*). It measures the relative peakness or flatness of a distribution. Platykurtic is called flat-looking distributions, while peaked distributions are called leptokurtic distributions. In the I-kazTM definition, the Gaussian distribution data for kurtosis is about 3.0 and the value of -3 has been ignored to create the zero value for the normal distribution as shown in (6). Higher kurtosis values show a Gaussian distribution with more extreme values. The Kurtosis is also non-dimensional quantity and used in engineering to detect symptoms of fault owing to its sensitivity to elevated amplitude occurrences.

$$K = \frac{1}{n} \sum_{i=1}^n \left(\frac{x_i - \mu}{\sigma} \right)^4 \quad (6)$$

Traditionally, sample data processes by root mean square and kurtosis were utilized as a measure of the impulsivity and energy of the signal for signal processing applications [14]. In [15] stated that measures of skew and kurtosis are often utilized to describe the distribution shape. They found that with the larger sample sizes, the mean-square errors for skewness and kurtosis decreased, and with small sample sizes, error increased.

The study shows that the use of kurtosis is significant in the machining process because normally larger samples are

used. Kurtosis is highly sensitive to raw data spikiness. A signal processing approach, I-kazTM is based on the fourth order statistical moment or kurtosis. In this paper, the statistical analysis method developed by [16] was used. The method was an alternative statistical analysis for Z-filter. The integrated kurtosis-based algorithm was applied to evaluate the degree of dynamic signal analysis for scattering of the raw signal data with respect to the centroid. In this method the Z-notch filter was used due to the fact that the filter efficiently extracted the component of noise from the measured data of the machining signals [17]. The centroid is accessed by decomposition from the average position of all the points of the all data signal.

Fig. 1 shows the I-kazTM decomposition procedure. From the signal data distribution, raw time domain data is processed at three different frequency ranges as low (LF) = $0 - 0.25f_{\max}$, high (HF) = $0.25f_{\max} - 0.5f_{\max}$ and very high (VF) = $0.5f_{\max} - f_{\max}$ frequencies. The selection of the frequency ranges takes into account the Daubechies concept with second order in the process of decomposition of signal on the raw signal, $f_{\max} = f_s/2.56$, where, f_{\max} is maximum frequency span, f_s is the sampling frequency and 2.56 is the Nyquist number. The I-kazTM technique generates a graphical representation of 3 dimensions by scattering the signal decomposition for each frequency distribution, low, high and very high bands. The standard deviation provides the mean deviation, $(x_i - \mu)$ between the immediate data, x_i and mean value, μ as shown in (7):

$$\sigma_{LF}^2 = \frac{1}{n} \sum_{i=1}^n (x_{LF,i} - \mu_{LF})^2 \quad (7)$$

$$\sigma_{HF}^2 = \frac{1}{n} \sum_{i=1}^n (x_{HF,i} - \mu_{HF})^2 \quad (8)$$

$$\sigma_{VF}^2 = \frac{1}{n} \sum_{i=1}^n (x_{VF,i} - \mu_{VF})^2 \quad (9)$$

where σ_{LF}^2 , σ_{HF}^2 and σ_{VF}^2 are the variances, $x_{LF,i}$, $x_{HF,i}$ and $x_{VF,i}$ are i -sample time of the mean data range, μ_{LF} , μ_{HF} and μ_{VF} , while n is the data sizes. In (7) shows the sum of the variances can be expressed as the sum of levels of intensity.

$$Z^\infty = \sqrt{\sigma_{LF}^4 + \sigma_{HF}^4 + \sigma_{VF}^4} \quad (10)$$

$$Z^\infty = \sqrt{\frac{\sum_{i=1}^n (x_{LF,i} - \mu_{LF})^4}{n^2}} + \sqrt{\frac{\sum_{i=1}^n (x_{HF,i} - \mu_{HF})^4}{n^2}} + \sqrt{\frac{\sum_{i=1}^n (x_{VF,i} - \mu_{VF})^4}{n^2}} \quad (11)$$

$$Z^\infty = \frac{1}{n} \sqrt{K_{LF} s_{LF}^4 + K_{HF} s_{HF}^4 + K_{VF} s_{VF}^4} \quad (12)$$

It is possible to simplify the I-kaz coefficient in (7) and (8) is the sum of the root mean square of the standard deviation, σ and the kurtosis, K from the measured data of force signals, K_{LF} , K_{HF} and K_{VF} are the signal kurtosis and s_{LF}^2 , s_{HF}^2 and s_{VF}^2 are LF , HF and VF ranges for standard deviation respectively. In (9) is used to help display statistical signal analysis in three-dimensional graphical representation using the I-kazTM method. In the meantime, the I-kaz coefficient is determined in (10). The stationary dynamometer provides the force signals in three component

measurement directions F_X for X -direction, F_Y for Y -direction and F_Z for Z -direction, for measuring forces during the cutting process for radial, feed and cutting forces. The radial force moves the tool out of the machine. The cutting forces, force the cutting tool to turn and the feed or thrust force move it in the direction of the feed. Comparing the three forces, the magnitude of cutting force is the most important criteria to quantify the machinability of a material. Nevertheless, in this paper the investigation of the statistical signal processing was considered on three force signals for all directions to seek the effect of each force signal on the surface roughness values.

D. Response Surface Methodology

A statistical approach using design of experiment is among the effective ways to analyze the influence of any input and process factors on their output responses. Some researchers have used different DOE approach for optimization in machining processes. In this paper, response surface methodology (RSM) by Design-Expert v.11 was used for optimizing because of the problems in the choice of cutting parameters based on modeling and assessment, where the output parameters are influenced by several parameters therefore creating a need to minimize the input parameters [18]. In [5] used RSM with factors as input parameters and response as output parameters for performing and modelling the relationship between them. They studied the optimization with four input factor parameters (workpiece temperature, depth of cut, cutting speed and feed rate) and two response parameters (tool wear and surface roughness) using the central composite design (CCD) in RSM and found that the cutting speed was the parameter that most affected surface roughness, next to the temperature for flank wear. Other researchers also used the optimization approach by RSM for measuring the optimum cutting parameters with output response parameters other than surface roughness and tool wear, such as chatter and wavelet transform [19], power, cutting force and specific cutting force [20], surface roughness, thrust, feed and tangential forces, and tool life, cutting forces [21]. The central composite rotatable design (CCRD) with 3 numeric factors and 5 responses, together with full type, 14 non-center points and 6 center points was used to (8) in 20 experiments and the factorial portion of the design, composed of points, is generally presented.

In (13) and (14) show the relationship between the input and output parameters [5].

$$Y = F((V_c), (f), (d)) + Error \quad (13)$$

$$Y = c_0 + \sum_i^3 c_i x_i + \sum_{ii}^3 c_{ii} x_i^2 + \sum_{i < j}^3 c_{ij} x_i x_j \quad (14)$$

where, Y is a response in quadratic multiple polynomial regression, $Error$ is a residual error from the experimental errors, V_c , f and d are cutting parameters for turning in a function, c_0 is the polynomial constant, c_i , c_{ii} and c_{ij} are the polynomial coefficients, x_i and x_j are the input parameters.

III. RESULTS AND ANALYSIS

In this paper, the I-kaz coefficients were obtained from the cutting force in the time domain as shown in Fig. 1. The cutting forces for X-, Y- and Z-directions were executed before and after the cutting processes. Fig. 2 shows the measured cutting force signals and Table II shows the measured values of the surface roughness from the experimental work. Fig. 3 shows the measured I-kaz coefficient and graph in 3D representation. The highest

force value obtained was 0.3037 kN at Y-direction for Experimental run 2. The surface roughness values were obtained in the range of 0.88–1.66 μm for R_a and 5.45–9.07 μm for R_z . Meanwhile, the I-kaz coefficients were obtained in the range of 3.8607E-09 – 5.3592E-08 for Z_X^∞ , 9.8487E-09 – 1.0940E-07 for Z_Y^∞ and 2.4236E-09 – 4.9783E-08 for Z_Z^∞ .

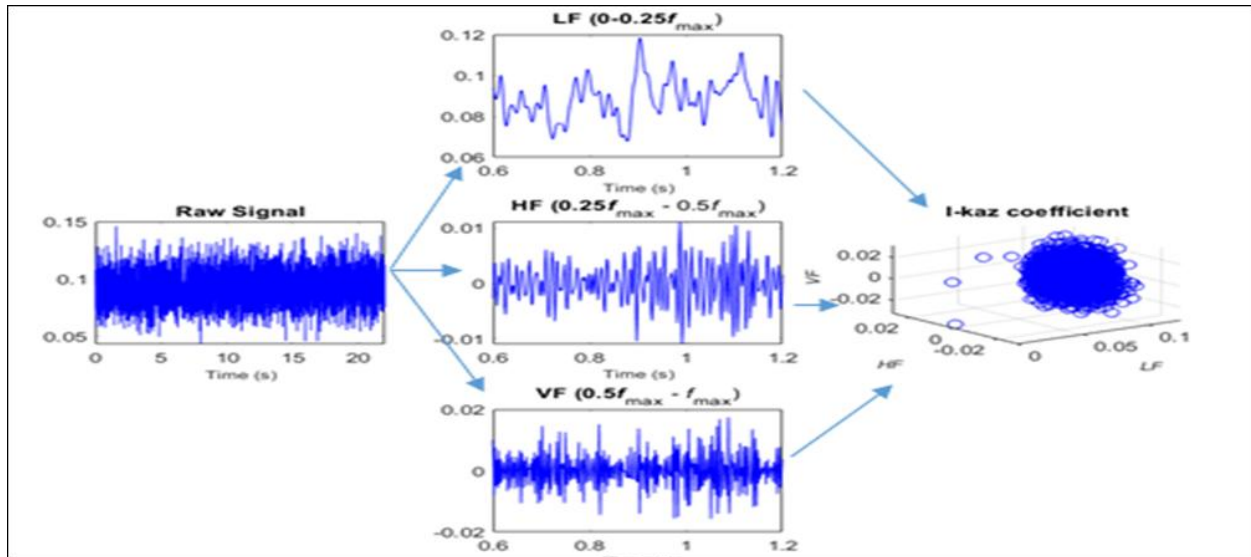
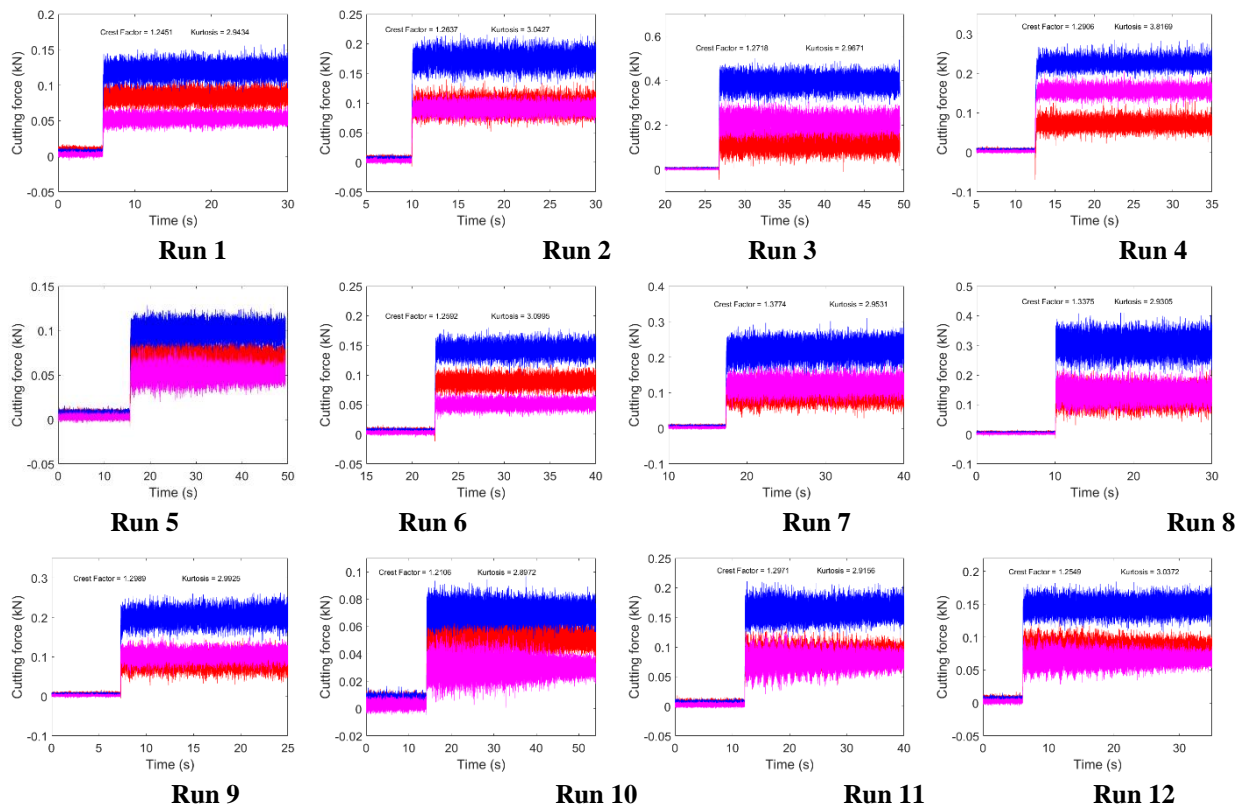


Fig. 1. Signal decomposition process for I-kazTM method



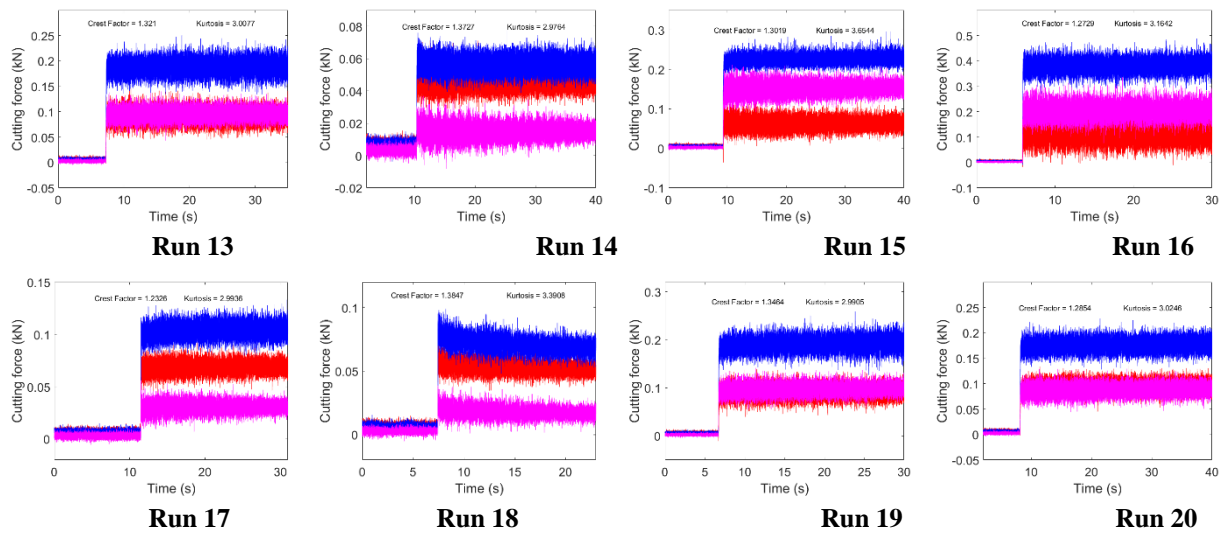
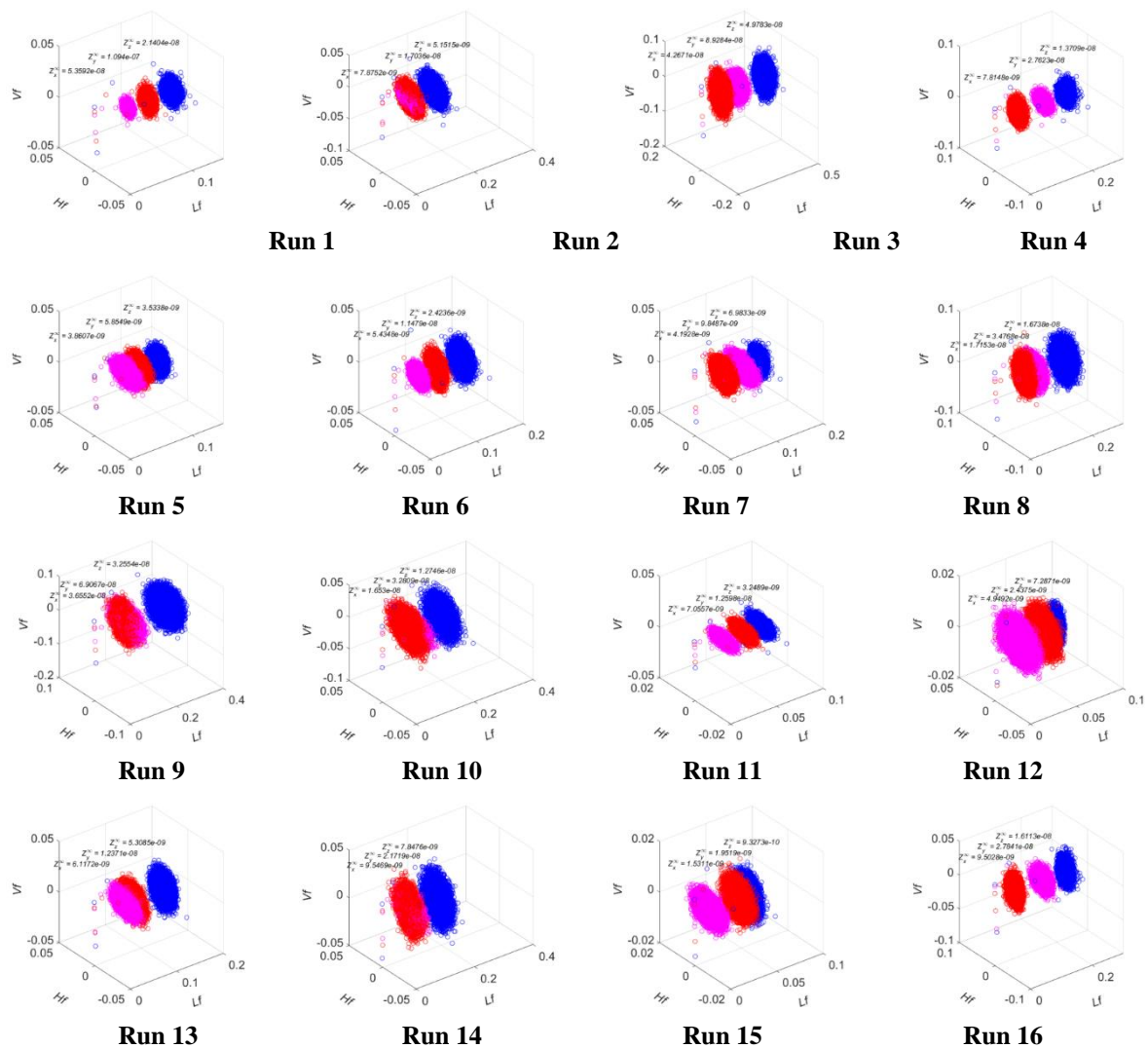


Fig. 2. Cutting forces (X-, Y- and Z-directions) for all experimental runs



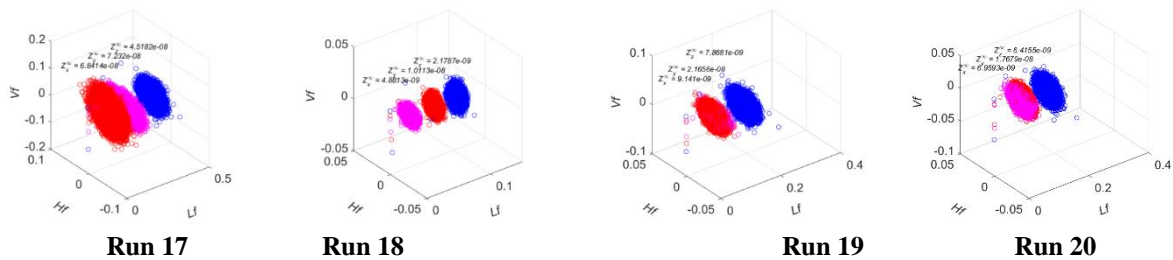


Fig. 3. Measured I-kaz coefficient and graph in 3D representation

Table- II: Experimental results for surface roughness parameters and I-kazTM coefficients

Exp Run No.	Factors			Responses				
	Vc (m/min)	f (mm/rev)	d (mm)	Ra (μm)	Rz (μm)	Z _x [∞] (10 ⁻⁹)	Z _y [∞] (10 ⁻⁹)	Z _z [∞] (10 ⁻⁹)
1	250	0.15	1.84	0.99	6.54	53.5924	109.3987	21.4042
2	250	0.15	1.00	1.17	6.89	7.8752	17.0357	5.1515
3	300	0.20	1.50	1.51	8.48	42.6708	89.2838	49.7825
4	200	0.10	1.50	0.92	6.09	7.8148	27.6228	13.7093
5	200	0.10	0.50	0.88	5.46	3.8607	5.8549	3.5338
6	200	0.20	0.50	1.54	7.70	5.4348	11.4791	2.4236
7	250	0.07	1.00	0.91	5.45	4.1928	9.8487	6.9833
8	250	0.15	1.00	1.19	6.60	17.1530	34.7677	16.7381
9	250	0.23	1.00	1.66	9.07	36.5517	69.0667	32.5535
10	334	0.15	1.00	1.38	7.77	16.5304	32.8087	12.7461
11	300	0.10	0.50	1.15	6.62	4.9492	2.4375	7.2871
12	250	0.15	1.00	1.22	6.56	8.5189	15.8684	9.9977
13	250	0.15	1.00	1.30	6.92	6.1172	12.3708	5.3085
14	250	0.15	1.00	1.31	7.11	9.5469	21.7192	7.8476
15	250	0.15	0.16	1.21	6.86	1.7339	1.1779	1.6211
16	300	0.10	1.50	1.33	7.50	9.5028	27.8412	16.1128
17	200	0.20	1.50	1.64	8.01	65.8605	68.2716	43.5425
18	300	0.20	0.50	1.63	7.82	2.5979	4.5335	1.3140
19	250	0.15	1.00	1.32	7.43	9.1410	21.6563	7.8681
20	166	0.15	1.00	1.31	7.17	6.9593	17.6797	6.4155

A. ANOVA and Factor Analysis

Tables II and III show the variance analysis (ANOVA) results for Ra and Rz , and I-kaz coefficients (Z_x^∞ , Z_y^∞ and Z_z^∞) are shown in Tables IV, V and VI. Using RSM by Design-Expert v.11, the responses obtained were the sum of squares, df, p-value, F-value and remarks. All models use optimization design generally estimated non-linear, or quadratic process order, have significant effect on Ra , Rz , Z_x^∞ , Z_y^∞ and Z_z^∞ which has probability values less than 0.05, based on the significant statistical parameters with their respective type III. Meanwhile, the lack of fit is not significant and has good indications for fitting the models. In terms of the main factors from the cutting parameters, depth of cut and feed rate are significant, while cutting speed is not significant for Ra and Rz . In statistical signal processing I-kazTM method, the probability values are significant for feed rate and depth of cut, and not significant for cutting speed even when all directions have been considered. The analysis has been performed for 95% confidence level.

From the analysis, the feed rate and the depth of cut have a greater impact on the surface roughness and I-kaz coefficient, while the cutting speed is very small but significant. This can be seen from the contribution number (F-value), the feed rate with contributions of 70.4% and 71.8%, the depth of cut with contributions of 14.7% and 16.1%, while the cutting speed is 0.06% and 1.77% for Ra

and Rz respectively. The rest of the contribution percentages are the interaction factor effect. In the case of the I-kaz coefficients, the contribution percentage is highest for depth of cut with 37.8%, 53.4% and 53.7% for Z_x^∞ , Z_y^∞ and Z_z^∞ respectively.

Second highest is feed rate with 30.9%, 25.8% and 20.5% for Z_x^∞ , Z_y^∞ and Z_z^∞ respectively. Then, cutting speed with 0.0027%, 1.229% and 1.471% for Z_x^∞ , Z_y^∞ and Z_z^∞ respectively.

It can be found that the increase of the Ra and Rz values and the I-kaz coefficients caused by the increase of the depth of cut and the feed rate. The increase in feed rate causes a higher amount of cutting material in the same time unit, as well as an influence on the cutting force. However, the Ra and Rz , and I-kaz coefficients decreased with an increase in cutting speed because of the reduction in the material shear strength [20].

Table- III: ANOVA result for R_a

Source	Sum of Squares	df	Mean Square	F-Value	p-Value
Model	1.13	9	0.1261	27.37	< 0.0001
V_c	0.0007	1	0.0007	0.1620	0.6958
f	0.8057	1	0.8057	174.87	< 0.0001
d	0.1686	1	0.1686	36.60	0.0001
$V_c \times f$	0.0172	1	0.0172	3.72	0.0825
$V_c \times d$	0.0343	1	0.0343	7.43	0.0213
$f \times d$	0.0397	1	0.0397	8.61	0.0149
V_c^2	0.0230	1	0.0230	5.00	0.0494
f^2	0.0045	1	0.0045	0.9802	0.3455
d^2	0.0506	1	0.0506	10.98	0.0078
Residual	0.0461	10	0.0046		
Lack of Fit	0.0259	5	0.0052	1.28	0.3951
Pure Error	0.0202	5	0.0040		
Cor Total	1.18	19			

Table- IV: ANOVA result for surface R_z

Source	Sum of Squares	df	Mean Square	F-Value	p-Value
Model	14.02	9	1.56	8.13	0.0015
V_c	0.2490	1	0.2490	1.30	0.2810
f	10.10	1	10.10	52.68	< 0.0001
d	2.27	1	2.27	11.82	0.0064
$V_c \times f$	0.0011	1	0.0011	0.0059	0.9404
$V_c \times d$	0.2720	1	0.2720	1.42	0.2611
$f \times d$	0.7351	1	0.7351	3.83	0.0787
V_c^2	0.3437	1	0.3437	1.79	0.2102
f^2	0.0926	1	0.0926	0.4833	0.5027
d^2	0.0048	1	0.0048	0.0252	0.8770
Residual	1.92	10	0.1917		
Lack of Fit	1.39	5	0.2776	2.62	0.1567
Pure Error	0.5291	5	0.1058		
Cor Total	15.94	19			

Table- V: ANOVA result for Z_x^∞

Source	Sum of Squares	df	Mean Square	F-Value	p-Value
Model	4.459E-15	9	4.954E-16	23.28	< 0.0001
V_c	1.237E-19	1	1.237E-19	0.0058	0.9407
f	1.388E-15	1	1.388E-15	65.23	< 0.0001
d	1.698E-15	1	1.698E-15	79.80	< 0.0001
$V_c \times f$	7.541E-17	1	7.541E-17	3.54	0.0891
$V_c \times d$	3.523E-17	1	3.523E-17	1.66	0.2272
$f \times d$	9.625E-16	1	9.625E-16	45.23	< 0.0001
V_c^2	1.082E-17	1	1.082E-17	0.5083	0.4922
f^2	2.211E-16	1	2.211E-16	10.39	0.0091
d^2	1.045E-16	1	1.045E-16	4.91	0.0511
Residual	3.183E-16	10	3.183E-17		
Lack of Fit	2.448E-16	5	4.897E-17	3.33	0.1062
Pure Error	7.344E-17	5	1.469E-17		
Cor Total	6.553E-15	19			

Table- VI: ANOVA result for Z_y^∞

Source	Sum of Squares	df	Mean Square	F-Value	p-Value
Model	1.182E-14	9	1.313E-15	24.67	< 0.0001
V_c	1.466E-16	1	1.466E-16	2.75	0.1281
f	3.070E-15	1	3.070E-15	57.66	< 0.0001
d	6.356E-15	1	6.356E-15	119.38	< 0.0001
$V_c \times f$	3.609E-18	1	3.609E-18	0.0678	0.7999
$V_c \times d$	3.165E-17	1	3.165E-17	0.5945	0.4585
$f \times d$	1.412E-15	1	1.412E-15	26.51	0.0004
V_c^2	1.683E-17	1	1.683E-17	0.3161	0.5864
f^2	5.373E-16	1	5.373E-16	10.09	0.0099
d^2	3.409E-16	1	3.409E-16	6.40	0.0298
Residual	5.324E-16	10	5.324E-17		
Lack of Fit	2.265E-16	5	4.530E-17	0.7405	0.6252
Pure Error	3.059E-16	5	6.118E-17		
Cor	1.235E-14	19			

Total					
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Table- VII: ANOVA result for Z_z^∞

Source	Sum of Squares	df	Mean Square	F-Value	p-Value
Model	3.286E-15	9	3.651E-16	21.88	< 0.0001
V_c	4.867E-17	1	4.867E-17	2.92	0.1185
f	6.795E-16	1	6.795E-16	40.72	< 0.0001
d	1.778E-15	1	1.778E-15	106.57	< 0.0001
$V_c \times f$	1.484E-17	1	1.484E-17	0.8894	0.3679
$V_c \times d$	3.684E-17	1	3.684E-17	2.21	0.1681
$f \times d$	4.302E-16	1	4.302E-16	25.78	0.0005
V_c^2	1.546E-18	1	1.546E-18	0.0926	0.7671
f^2	2.225E-16	1	2.225E-16	13.34	0.0044
d^2	1.005E-16	1	1.005E-16	6.02	0.0340
Residual	1.669E-16	10	1.669E-17		
Lack of Fit	7.515E-17	5	1.503E-17	0.8193	0.5839
Pure Error	9.172E-17	5	1.834E-17		
Cor Total	3.453E-15	19			

B. Multiple Regression Equations

The factor-response relationship was based on quadratic regression equations. The obtained multiple equations of regression were shown follows.

The final equation of regression in terms of R_a and R_z models with coefficient of determination, R^2 96.1% and 87.98% respectively, are given in (15) and (16).

$$R_a = 0.04245 - 0.003296V_c + 11.43133f + 0.532218d - 0.03535V_c f - 0.000385V_c d - 1.135fd + 0.00002V_c^2 + 11.32303f^2 - 0.144864d^2 \quad (15)$$

$$R_z = 5.08795 - 0.02391V_c + 29.81226f + 0.467409d - 0.099V_c f + 0.003V_c d - 2.7fd + 0.000082V_c^2 + 52.7942f^2 - 0.264018d^2 \quad (16)$$

The $I\text{-}kaz_x$, $I\text{-}kaz_y$ and $I\text{-}kaz_z$ coefficient models are given in (17), (18) and (19) with R^2 is 95.44%, 95.69% and 95.17% respectively.

$$Z_x^\infty = -8.91964 \times 10^{-9} + 3.38525 \times 10^{-10}V_c - 2.27312 \times 10^{-7}f - 6.93714 \times 10^{-8}d - 1.56782 \times 10^{-9}V_c f - 1.11533 \times 10^{-10}V_c d + 4.72723 \times 10^{-7}fd - 1.20712 \times 10^{-14}V_c^2 + 1.20808 \times 10^{-6}f^2 + 2.69364 \times 10^{-8}d^2 \quad (17)$$

$$Z_y^\infty = 1.01591 \times 10^{-7} - 3.85178 \times 10^{-11}V_c - 8.57117 \times 10^{-7}f - 1.36127 \times 10^{-7}d + 6.60895 \times 10^{-10}V_c f + 1.37725 \times 10^{-10}V_c d + 4.92099 \times 10^{-7}fd - 3.02181 \times 10^{-13}V_c^2 + 1.70796 \times 10^{-6}f^2 + 4.10986 \times 10^{-8}d^2 \quad (18)$$

$$\begin{aligned} Z_z^\infty = & 8.29624 \times 10^{-8} - 1.21475 \times 10^{-10} V_c \\ & - 7.01669 \times 10^{-7} f - 6.17282 \times 10^{-8} d \\ & - 1.33295 \times 10^{-10} V_c f + 2.18065 \times 10^{-11} V_c d \\ & + 3.61131 \times 10^{-7} f d + 2.98768 \times 10^{-13} V_c^2 \\ & + 1.73955 \times 10^{-6} f^2 + 1.06945 \times 10^{-8} d^2 \end{aligned} \quad (19)$$

In (15) to (19) can be applied to model and predict the values of the surface roughness and I-kaz coefficients. Fig. 4 shows the comparison between measured and predicted responses for surface roughness Ra and Rz for all experimental runs. Fig. 5 shows the comparison between measured and predicted responses for Z_x^∞ , Z_y^∞ and Z_z^∞ for all experimental runs.

C. Optimization of Cutting Conditions

The criteria of the cutting parameters, surface roughness and I-kaz coefficients (Z_x^∞ , Z_y^∞ and Z_z^∞) were constrained based on in ranges for cutting speed, feed rate and depth of cut, minimize the values of Ra and Rz and I-kaz coefficients. Table VIII shows the criteria and goals for cutting conditions. The optimal setting of cutting parameters is observed at 200 m/min, 0.1 mm/rev and 0.521 mm for cutting speed, feed rate and depth of cut respectively as shown in Table XI.

Table- VIII: Criteria and goals for the condition of cutting.

Criteria	Goal	Lower Limit	Upper Limit
Cutting speed, V_c	in range	200	300

Feed rate, f	in range	0.1	0.2
Depth of cut, d	in range	0.5	1.5
Ra	minimize	0.88	1.657
Rz	minimize	5.45	9.07
I-kaz TM _x	minimize	2.5979E-09	6.8410E-08
I-kaz TM _y	minimize	2.4375E-09	1.0940E-07
I-kaz TM _z	minimize	1.3140E-09	4.9783E-08

D. Validation of Experiments

Table- IX and Table X demonstrate the validation experiment and their contrast with the expected model for surface roughness and I-kaz coefficients. For surface roughness and I-kaz coefficients, the three conformation experiments were conducted. The analysis of Tables IX and X indicates that the calculated errors are small. In comparison, the errors between predicted and experimental values for Ra , Rz , Z_x^∞ , Z_y^∞ and Z_z^∞ were within -1.78 to 8.83, -3.47 to -5.19, 2.99 to 10.22, 2.65 to 4.43 and -9.82 to 9.75 respectively. In this experiment, 95% prediction interval was applied for the confidence level. Thus, the model accurately obtained as the comparison between predicted and measured data, and errors of mean relative percentages shown in Fig. 6(a), Fig. 6(b) and Fig. 6(c). Fig. 7(a) and Fig. 7(b) show the effect of feed rate and cutting speed on Ra , Rz , Z_x^∞ , Z_y^∞ and Z_z^∞ . The predicted response surface plane generally cuts through the middle of the design points. The depth of cut and feed rate show a significant effect on Ra , Rz , Z_x^∞ , Z_y^∞ and Z_z^∞ .

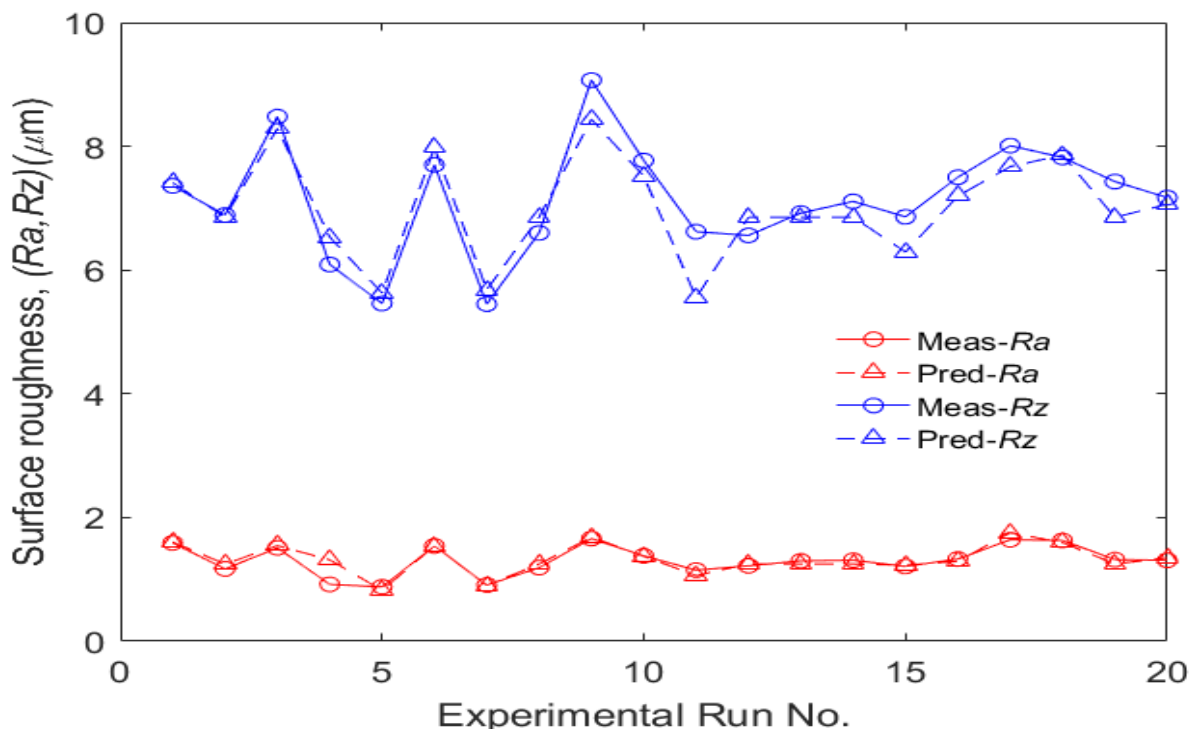


Fig. 4. Predicted and measured surface roughness values

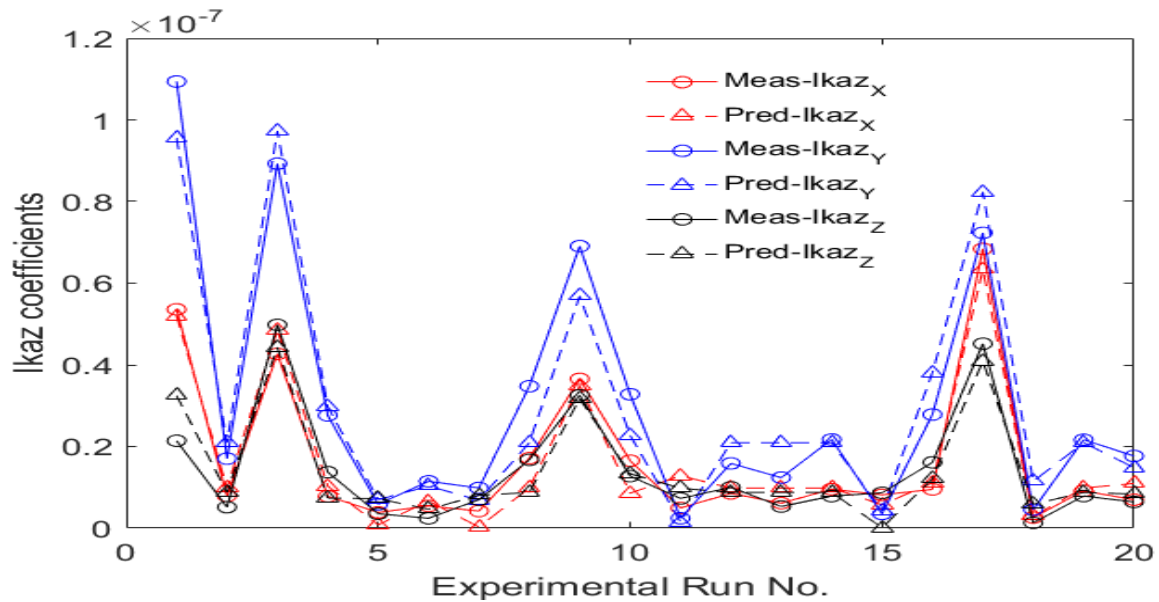


Fig. 5. Predicted and measured I-kaz coefficients

Table- IX: Confirmation experiments for surface roughness values

No.	Vc (m/min)	f (m/rev)	d (mm)	Surface Roughness					
				Ra (μm)			Rz (μm)		
				Actual	Pred	Error (%)	Actual	Pred	Error (%)
1	210	0.12	0.75	1.118	1.019	8.83	5.90	6.21	-5.19
2	225	0.15	0.75	1.225	1.198	2.17	7.15	6.742	5.69
3	200	0.12	0.6	1.016	0.997	-1.78	5.67	5.867	-3.47

Table- X: Confirmation experiments for I-kaz coefficients

No.	Vc (m/min)	f (m/rev)	d (mm)	I-kaz Coefficient (Z^∞)								
				Z_x^∞			Z_y^∞			Z_z^∞		
				Actual ($\times 10^9$)	Pred ($\times 10^9$)	Error (%)	Actual ($\times 10^9$)	Pred ($\times 10^9$)	Error (%)	Actual ($\times 10^9$)	Pred ($\times 10^9$)	Error (%)
1	210	0.12	0.75	4.5520	4.4160	2.99	7.6651	7.4622	2.65	3.7208	3.3581	9.75
2	225	0.15	0.75	4.9504	4.4443	10.22	0.1069	0.1022	4.43	3.1312	3.4388	-9.82
3	200	0.12	0.6	3.4810	3.1865	8.46	5.3169	5.1196	3.71	1.5662	1.6215	-3.53

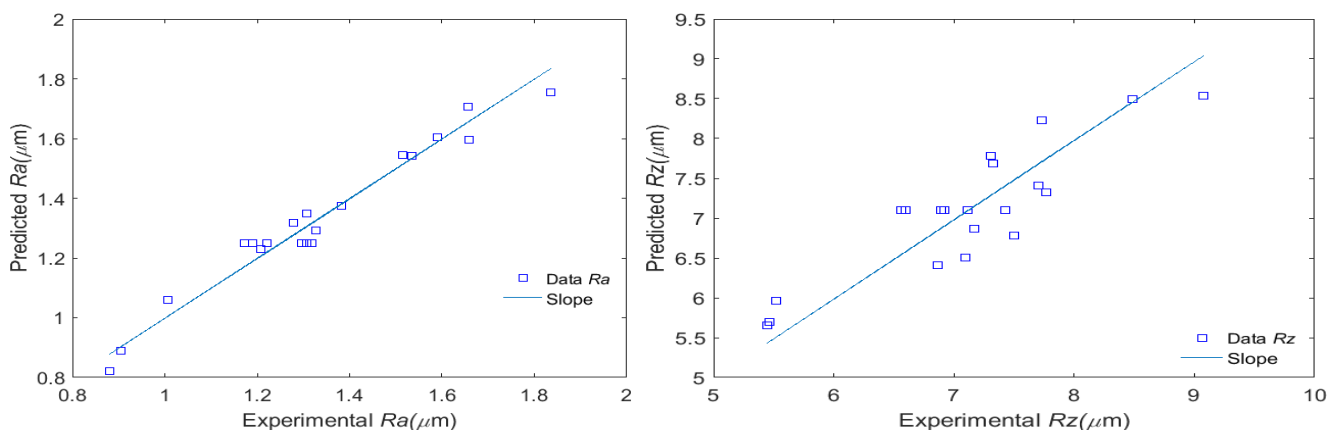


Fig. 6(a). Comparison between measured and prediction data for Ra and Rz

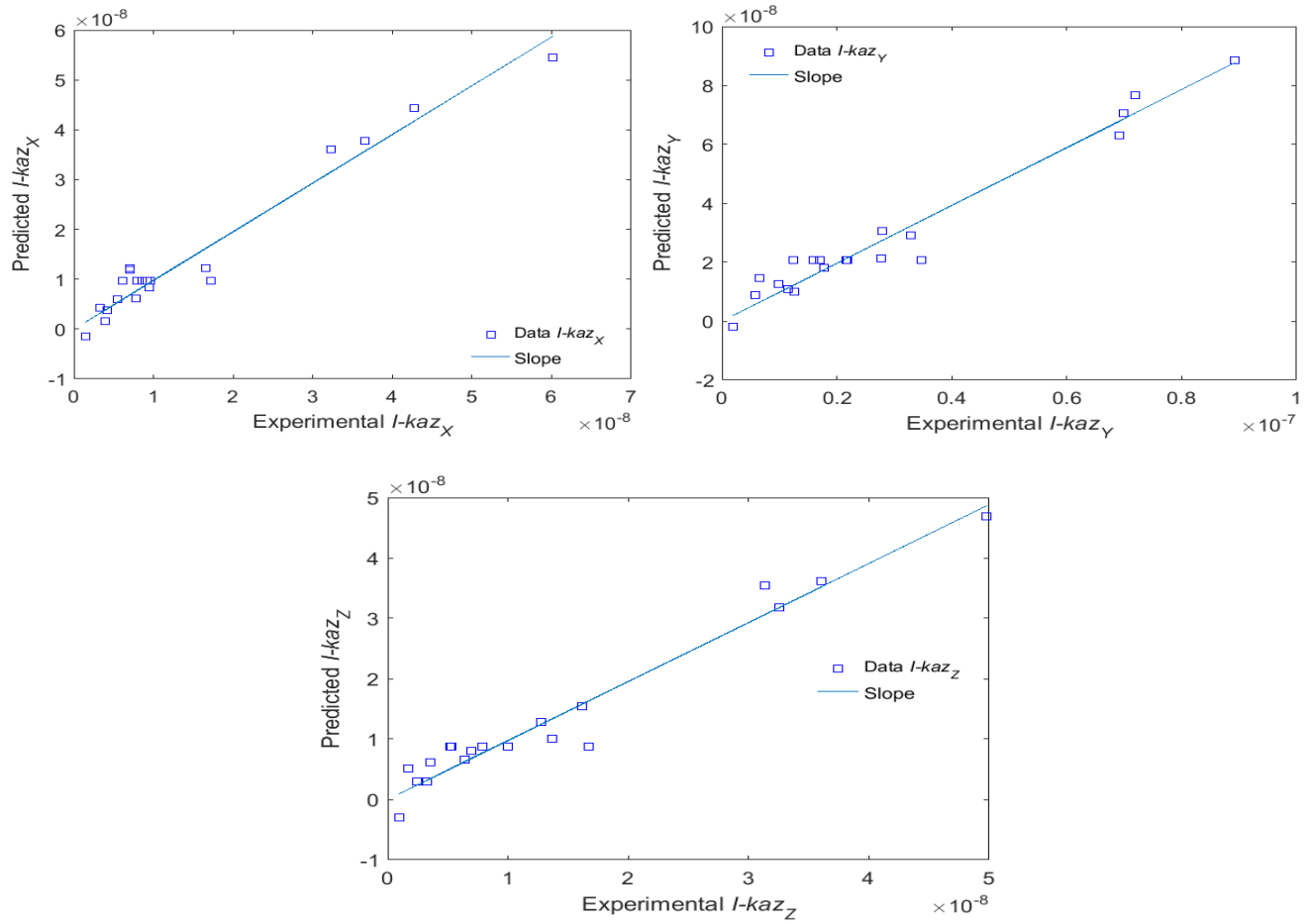


Fig. 6(b). Comparison between measured and prediction data Z_X^∞ , Z_Y^∞ and Z_Z^∞

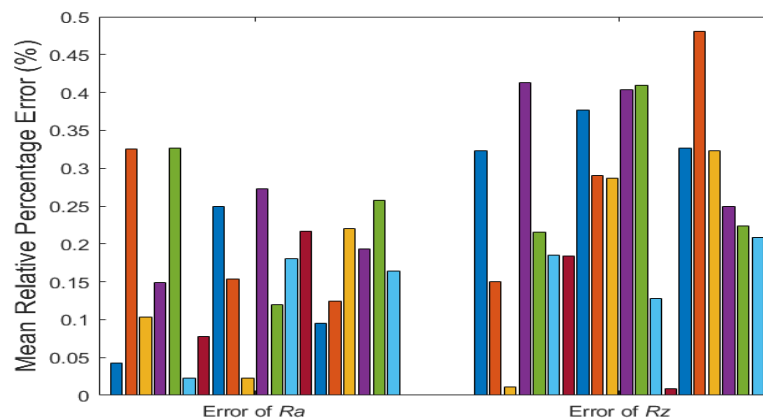


Fig. 6(c). Mean relative percentage error for Ra and Rz

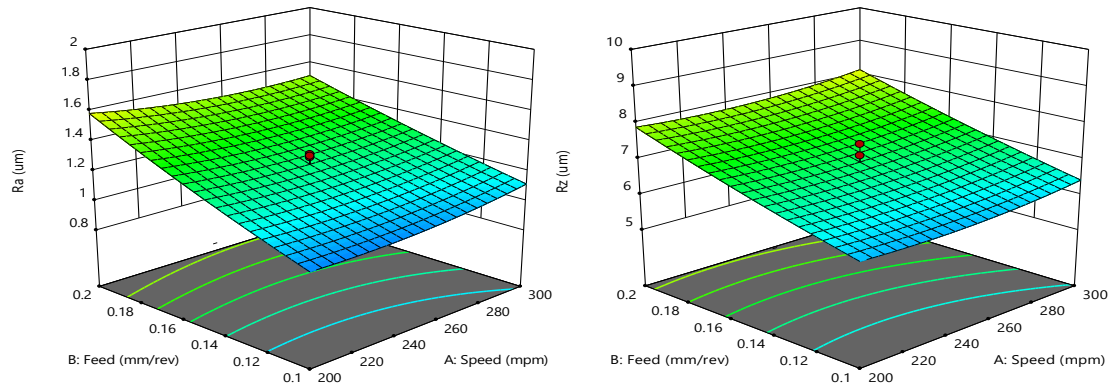


Fig. 7(a). Influence of feed rate and cutting speed on Ra and Rz

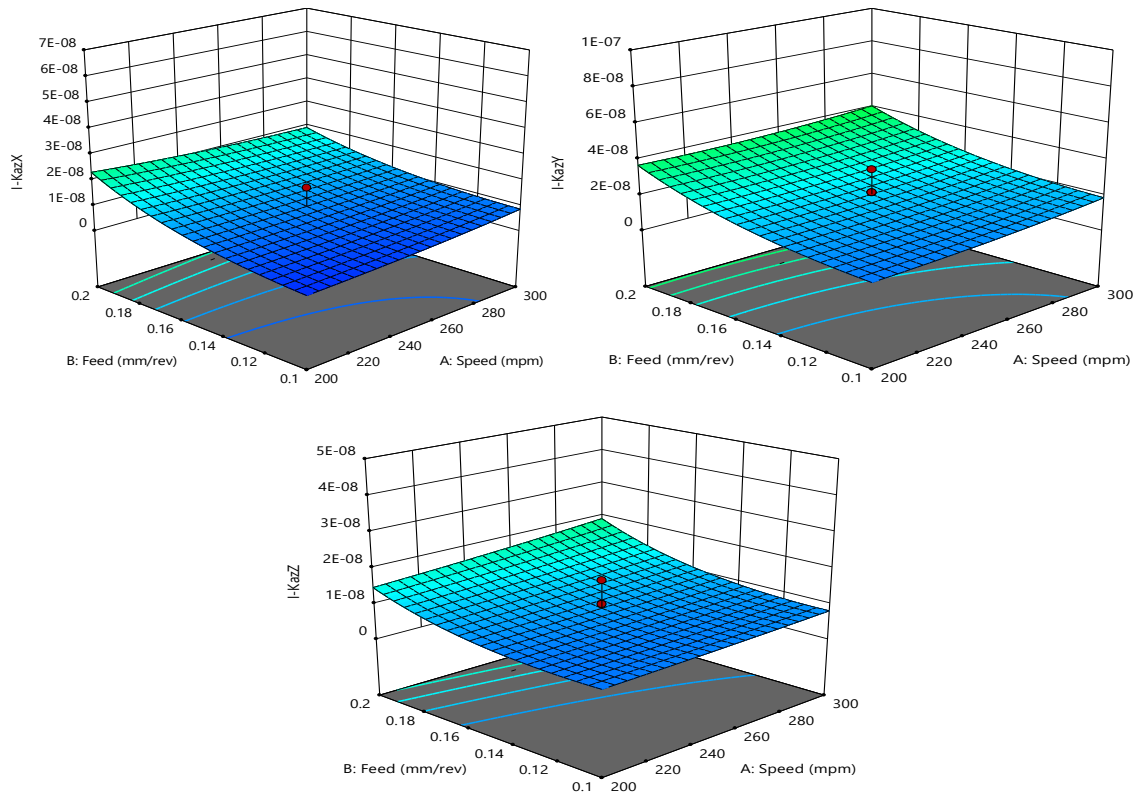


Fig. 7(b). Influence of feed rate and cutting speed on Z_X^∞ , Z_Y^∞ and Z_Z^∞

Table- XI: Optimization of the responses for surface roughness values and I-kazTM coefficients

Test No.	Vc (m/min)	f (mm/rev)	d (mm)	Surface Roughness		I-kaz Coefficients (Z^∞)			Desirability
				Ra	Rz	Z_X^∞	Z_Y^∞	Z_Z^∞	
1	200.001	0.100	0.521	0.881	5.603	4.654E-08	6.602E-09	7.006E-08	0.959
2	200.005	0.100	0.558	0.888	5.622	9.951E-11	6.049E-09	6.648E-08	0.959
3	200.012	0.100	0.503	0.880	5.602	7.461E-10	6.856E-09	7.104E-09	0.958
4	207.049	0.100	0.505	0.886	5.607	1.597E-09	6.709E-09	7.164E-09	0.957
5	207.748	0.100	0.500	0.886	5.606	1.765E-09	6.767E-09	7.211E-09	0.956
6	209.695	0.100	0.530	0.894	5.628	1.471E-09	6.241E-09	6.914E-09	0.955
7	210.963	0.100	0.582	0.909	5.672	7.799E-10	5.516E-09	6.328E-09	0.953
8	225.000	0.100	0.568	0.928	5.716	2.597E-09	5.357E-09	6.674E-09	0.945

IV. CONCLUSION

This research presents the optimization of cutting parameters in turning process based on the surface roughness, the cutting forces and I-kaz coefficients of the S45C mild steel. The following conclusion can be drawn:

- The comparison between the predicted and measured surface roughness values of Ra and Rz and the I-kaz coefficients reveals that strong agreement has been reached. The model can therefore be used to predict surface roughness and I-kaz coefficients.
- The surface roughness is strongly affected by the feed rate (70.4121% for Ra and 71.8157% for Rz) and followed by depth of cut (14.7371% for Ra and 16.1136% for Rz).
- The I-kaz coefficients are strongly affected by the depth of cut (37.7708% for Z_x^∞ , 53.3498% for Z_y^∞ and 53.6763% for Z_z^∞) and followed by feed rate (30.8746% for Z_x^∞ and 25.7677% for Z_y^∞ and 20.5095% for Z_z^∞).
- The optimal configuration of cutting parameters is observed at a cutting speed of 200 m/min, a depth of cut of 0.521 mm and a feed rate of 0.1 mm/rev with 95.9% desirability.

The experimental investigation in this paper verified that the optimization models can be used for turning S45C steel.

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