A Novel Approach on Power System Fault Detection Using Bayes Optimisation

V Vijay Kumar, Jillella Gopinath

Abstract. One of the substantial tools for the diagnosis of the transmission line faults is the artificial neural network, due to its ability to distinguish between variegated configurations. The data fed to the network get noisy sometimes that cause miscalculate at the output of the plant. By using Bayesian optimization techniques which commission the naive baye’s process that minimize the sample data to quench the misreading at the output. This process scrutinizes the use of an optimization technique to pinpoint the selective collection of data set in real time using limited amount of sample data. Importantly, this paper investigates with the Bayesian approach that mixes the strengths of bayesian optimization [13]. The usage of gaussian regression strategies requires just a few number of information factors to model the complex goal gadget. Moreover because of using trust place constraint on sampling process, bayesian analysis tends to growth the target cost and converge toward near the superior. Simulation research the use of analytical features display that the Bayesian optimization can achieve an almost optimizing in a target value with rapid convergence. And these converged data sets are used to rehearse artificial neural networks (ANNs) for the fault classification in high voltage transmission lines. The back propagation algorithm [19] and gradient boosting function has been employed for detection and classification of the fault type.

Keywords: power system faults, neural networks, optimization.

I. INTRODUCTION

The electric utilities organizations are required to give buyers a persistent and fantastic administration at a focused and sensible expense. This implies they need to safeguard the unwavering quality of the framework to give shoppers an administration what is predictable with the security work force and hardware, and satisfy their needs inside indicated voltage and recurrence. Blames in the transmission lines are one of the components that the unwavering quality of the framework is influenced by. The more blames that happen, the less dependable the framework is, since they could cause blackouts in the power framework, which may result in an intrusion of the administration. In this manner, when planning the power transmission frameworks, electric organizations are required to pursue the arrangement of standard determinations, the less blames events will be and the more solid the power framework will be. To diminish the shortcomings and impact of flaws, compels identified with the transmission framework get the chance to improve. Enhancement is the scientific strategy which is worry with finding the most extreme and least of the capacity, perhaps subject to the requirements for nonstop and differential capacities. Enhancement approach can be utilized in various regions like engineering, financial aspects, material structure and transportation yet in this paper we center around voltage mutilations in three stage organize because of issues and characterize the sort of blame utilizing neural system by streamline the system parameters utilizing bays's hypothesis.

The idea of bayes' hypothesis is one of the major and critical speculations among contingent likelihood. As per the likelihood hypothesis, the contingent likelihood can decide by calculating the likelihood of an activity happened at a given another occasion has happened. On the off chance that the some occasion An and occasion B are expected to have happened then the contingent likelihood of A given upon B or the restrictive likelihood of B given upon An is typically composed as P(A|B). For instance, the likelihood that any given transmission line has a blame on some random unit of time might be x%. In any case, on the off chance that we know or expect that the line which get blame condition, at that point they are substantially more prone to be glitch of hardware now and then harm. The contingent likelihood of hardware harm given that you have a blame on framework may be an a lot higher X%. This procedure is determined by utilizing bayes's hypothesis [11] that gives estimated likelihood esteem utilizing typical conveyance which the given information is have a place with either flawed esteem or non-defective esteem. So by utilizing probabilistic capacity P(A|B), we can arrange the informational collections that we gauged amid blame happened on three stage line and limit the mistake at the characterization organize [4]. The way toward perceiving the kind of blame is finished by a neural system prepared by the information which experiences through the streamlining. The procedure is essentially looks a ton due to the extensive number of informational indexes get handled in disconnected condition. Yet, the outcome toward the end is very fulfilled when contrasted and the non-advanced information that yields colossal blunders on account of rehashed estimations and commotion amid the task of three stage transmission framework.

II. FAULT CLASSIFICATION ON POWER SYSTEM

Deficiencies can be characterized as the stream of a high plentifulness current through an ill-advised way which could cause substantial equipment damage which will prompt interference of intensity, individual damage.
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In augmentation, the size of voltage level will alternatethat can influence the hardware protection in the event of an increase or could cause a disappointment of gear start-up if the voltage is beneath a base dimension [1]. Hence, equipment will be presented to the threat of electricity which isn’t accepted. In request to forestall suchan occasion, the process of assessing the framework voltages and flows under different kinds of hardware conditions is called blame examination [3], which can decide the important security measures and the required protection framework. It is fundamental to ensure the security of open. The examination of shortcomings prompts appropriate protection settings which can be figured so as to select suitable wire, electrical switch size and kind of hand-off. Theseverity of the blame relies upon the short or open circuit areas, the path taken by blame current, the framework impedance and its voltage level. So as to keep up the continuation of intensity supply to all clients which is the center motivation behind the power framework presence, all blamed parts must be segregated from the system transitory by the security plans. At the point when a blame exists inside the assurance zone at any transmission line, a flag will excursion or open the electrical switch excluding the faulted line. Faults as a rule happen in a power framework because of protection breakdown, flashover, and physical harm. These faults may either be three stages in nature including all three phases in a symmetrical way, or might be asymmetrical where normally just a single or two stages might be included. Faults may likewise be brought about by either short circuits to earth or between live conductors, or might be brought about by broken conductors in one or more stages. Now and then concurrent deficiencies may occur involving both short out and broken-conductor blame otherwise called open-circuit faults. Overhead transmission line presented to basic climatic conditions, so the odds of occurrence of issues in overhead transmission lines were more when contrasted with underground links. Faultsin overhead transmission framework can be arranged into two kinds, for example open circuit blames and short out blame. Open circuit deficiencies can be recognized effectively by watching the each stage voltage. In the event that the voltage values expands, it shows that open conductor blame is happened. These shortcomings are very rarely occurred faults. Short circuit issues can be distinguished effectively by watching the each stage current. In the event that the present qualities increases, it shows cut off is happened. Short out issues are partitioned into two sorts, for example asymmetrical faults, and symmetrical issues [2] [3]. Uneven shortcomings line to ground, line to line, and twofold line to ground, and symmetrical deficiencies are triple line and triple line to ground issues. A vital target of all the power frameworks is to keep up an abnormal state of continuity of administration, and when unusual conditions happen, to limit the blackout times. It is practically difficult to maintain a strategic distance from outcomes of regular occasions, physical mishaps, gear disappointment which results in the loss of intensity, voltage plunges on the power system. Natural occasions can cause short circuits for example shortcomings which can either be single stage to ground or stage to stage to ground or a three stage blame. Most blames in an electrical framework happen with a system of overhead lines are single-stage to ground deficiencies caused because of lightning acted transient high voltage and from falling trees. In the overhead lines, tree contact brought about by wind is a noteworthy reason for blame. The recurrence of event of various sorts of flaws can be given as, Single line to ground blame – 70-80%, Line-Line blame - 10-17%, Line-Line to ground blame – 8-10%, Three stage – 2-3%.

III. BAYESIAN ANALYSIS AND OPTIMIZATION OF DATA

To illustrate the Bayesian approach [9], consider a fair coin that is equally balanced on both sides with neglecting the physical forces of it. If we throw the coin up in the air, it will come to relaxation both on its factor heads or on its tails. Assume we turn the coin n+1 instances, making sure that the bodily properties of the coin and the conditions below which it’s miles flipped continue to be strong extra time. From the first n observations, we need to determine the chance of heads on the n+1th toss. Within the classical analysis of this hassle, we assert that there’s a few bodily probability of heads, that is unknown. We estimate this physical probability from the n observations using criteria which includes low bias and occasional variance. We then use this estimate as our opportunity for heads on the n+1th toss. Within the bayesian approach, we additionally assert that there’s some physical possibility of heads, but we encode our uncertainty about this physical chance the use of bayesian possibilities, and use the regulations of possibility to compute our possibility of heads on the n+1th toss. To have a look at the bayesian evaluation of this hassle, we need a few variable set a is in configuration x. We use p(x|b) as a shorthand to indicate the possibility that a=x of a pattern with kingdom of data. We additionally use p(x|b) to denote the possibility distribution for a (density features). Whether p(x|b) refers to a posterior chance or aprobability distribution [11] could be clear from context.

\[
P(x|B) = \frac{p(x)P(B|x)}{P(B)}
\]

Where \(P(B) = \int P(B|x)p(x)dx\)

Next, we enlarge the term. Each bayesians and classical statisticians agree on this term: it is the chance feature for binomial sampling. The probability distributions and p are usually called the prior and posterior chance [14] respectively.
The quantities a and b are stated to be sufficient statistics for binomial sampling, due to the fact they offer a summarization of the data that is enough to compute the posterior from the previous. Eventually, we commonly over the viable values of x (using the expansion rules of probability) to decide the possibility that the n+1th toss of the coin will come up heads:

\[
P(A_{n+1} = \text{heads} | B) = \int P(A_{n-1} = \text{heads} | B) \cdot P(x) dx
\]

\[
= \int x P(x | B) dx = E_x P(x | B)
\]

Where \(E_x P(x | B)\) denotes the expectation of x with respect to the distribution \(P(x | B)\).

Bayesian Optimization with Gaussian process

Bayesian optimization is an method to optimizing goal capabilities [10] (the characteristic that it is favored to maximise or decrease) that take a long time to assessment. It is great-acceptable for optimization over continuous domains and resist to noise in feature reviews. It builds a surrogate for the objective and quantifies the uncertainty in the surrogate using a bayesian optimization, gaussian regression method, after which uses a further characteristic defined from this surrogate to decide wherein to sample. The gaussian system is based totally on bayes’ theorem with the impartial information sets among predictors. A gaussian version is uncomplicated manner to assemble the sequential parameter estimation which makes it specially beneficial for terribly huge datasets.

Bayes theorem provides a way to estimate the posterior probability \(P(A|B)\) from \(P(A), P(B), \) and \(P(B|A)\). The Gaussian approach assumes that the effect of the value of a predictor \(B\) on a given class \(A\) is independent of the values of other predictors. This assumption is called class conditional independence [8].

\(P(A|B)\) is a posterior probability of type given predictor.
\(P(A)\) is the prior chance of class.
\(P(B|A)\) is a likelihood likelihood of predictor given class.

\(P(B)\) is the prior likelihood of predictor.

The unknown data set which contains \(X_n\) attributes. That is, for any choice of distinct values \(n = 1, 2, 3, \ldots\) the random vector \(X_n = (x_1, x_2, \ldots)\) has a multivariate normal distribution [12] with mean \((\mu)\) and the covariance \(\sigma^2\), which will be denoted by:

\[
X \sim N(\mu, \sigma^2)
\]

Gaussian probability density function for likelihood given by,

\[
P(B|A) \sim f(x) = \frac{1}{\sqrt{2 \pi \sigma^2}} e^{-\frac{(x - \mu)^2}{2\sigma^2}}
\]

Co-variance,

\[
\sigma^2 = \frac{1}{n} \sum_{k=1}^{n} (X_k - \mu)^2
\]

Mean,

\[
\mu = \frac{1}{n} \sum_{k=1}^{n} X_k
\]

V. GAUSSIAN PROCESSES

Gaussian Process (GP) [12] give a rich and adaptable class of non-parametric factual models over capacity spaces with areas that can be ceaseless, discrete, blended, or even various leveled in nature. Moreover, the GP gives not only data about the reasonable estimation of \(f\), however essentially likewise about the vulnerability around that value. The multivariate ordinary appropriation, at that point it’s very little harder to comprehend Gaussian procedures. It have a lot of irregular factors \(Xn\) recorded by a set \(n\), and any limited subset of these arbitrary factors is together Gaussian. You could take \(n\) to be the genuine line, for instance. At that point at each point \(n\) in the genuine line, you have an arbitrary variable \(Xn\) which takes some esteem. While a multivariate Gaussian circulation is dictated by its mean and covariance, a Gaussian procedure is controlled by its mean capacity and covariance work. The mean capacity characterizes the mean stature of the capacity at each point and covariance work influences properties like the smoothness of the capacity, periodicity, and so on by saying how corresponded each pair of focuses is. Every one of these properties of multivariate Gaussians exist for Gaussian procedures too, similar to the basic equations for contingent desires and restrictive variations. You can surmised a Gaussian procedure [14] on an interim by choosing \(n\) to be a framework of equitably separated focuses that take some esteem. At that point to test from the procedure, you can simply test a multivariate Gaussian appropriation with a covariance characterized by your covariance work and the mean characterized by the mean function. A prevalent, basic decision for our mean is to take \(\mu\) expressing that our underlying best estimate for the capacity yield at any info is zero. Obviously, in the event that we have preferable learning over this task, it ought to be incorporated. Another plausibility is to take, as a non-zero consistent for all information sources, where this steady structures a hyper parameterabout which we will likewise have earlier convictions. Well known non-steady methods capacities incorporate polynomials of different orders. For the covariance, a typical desire we have about our capacity is that it be smooth to some degree.
That is, the estimation of a capacity at x is emphatically related with the qualities near x, these relationships getting to be more fragile further away. For this situation, the covariance will be of the homogenous form. The mean here communicates our assumption regarding the capacity estimates y before having mentioned any objective facts. This mean is produced by a mean capacity (X, n).

Gaussian methods are the extension of multivariate Gaussians to infinite-sized collections of real-valued variables. Specifically, this extension will allow us to consider gaussian methods as distributions now not simply over random vectors but in reality distributions over random features. To recognize how one may parametrize possibility distributions over functions, take into account the subsequent easy instance [7]. Permit x = x1,..., Xm be any finite set of factors. Now take into account the set ybe a class of functions mapping from x → y. A random characteristic f(y) from x is generated through which it became randomly drawn from x, in line with chance distribution over x. One ability supply of misunderstanding is that you’ll be tempted to consider random functions as capabilities whose outputs are in some manner stochastic; this isn’t always the case. Instead, a random feature f(y), as soon as selected from x probabilistically, implies a probabilistic mapping from inputs in x to outputs in y of all viable features mapping from x to r. As an example, one example of a function f0(Y) ∈ X is given by f (Y0)=[f(y1),f(y2),...]. Since the domain of any f(Y) ∈ X has only n elements, we can always represent f(Y) compactly as an m-dimensional vector, 

\[ f(Y) = [f(y_1), f(y_2), ..., f(y_n)]^T \]

In order to specify a chance distribution over features f(Y) ∈ X, we must companion some “probability density” with each function in X. One herbal way to do this is to discover the one-to-one correspondence between features f(Y) ∈ X. In unique if we specify to characterize the characteristic as follows,

\[ f(X) \sim N(\mu, \sigma^2) \]

Then this in flip implies a likelihood distribution over functions f(Y), whose likelihood density characteristic is given through

\[ P(Y) = \prod_{n=1}^{N} \frac{1}{\sqrt{2\pi\sigma^2}} \exp \left( \frac{-(y_n - \mu)^2}{2\sigma^2} \right) \]

Therefore probability distributions over capabilities with finite domains may be represented the use of a finite-dimensional multivariate gaussian distribution over characteristic outputs f(y1),f(y2),...,f(yn) at a finite number of input points x1,....,Xm. How can we specify opportunity distributions over capabilities while the domain size may be countless? For this, we flip to a fancier kind of possibility distribution known as a gaussian process. A stochastic manner is a group of random variables, f(y): y ∈ Ey. Inside the models which are used for gaussian method regression, however, the unknown set is taken to be the enter area of our regression hassle. A gaussian system is a stochastic method such that any finite sub series of random variables has a multivariate gaussian distribution. Specially, a set of random variables f(x) : x ∈ x is said to be drawn from a gaussian procedure with imply characteristic and covariance characteristic if for any finite set of factors x1, ..., xn ∈ x, the associated finite set of random variables is represented as,

\[ \begin{bmatrix} f(x_1) \\ \vdots \\ f(x_m) \end{bmatrix} \sim N \left( \begin{bmatrix} \mu(x_1) \\ \vdots \\ \mu(x_m) \end{bmatrix}, \begin{bmatrix} \sigma^2(x_1,x_1) & \cdots & \sigma^2(x_1,x_m) \\ \vdots & \ddots & \vdots \\ \sigma^2(x_m,x_1) & \cdots & \sigma^2(x_m,x_m) \end{bmatrix} \right) \]

This can denoted using the notation,

\[ f(x) \sim GP(\mu(X, m), \sigma^2(X, m)) \]
Intuitively, you may consider a characteristic f(y) drawn from a gaussian technique earlier as an extremely high-dimensional vector drawn from an exceptionally excessive-dimensional multivariate gaussian [9]. Right here, each size of the gaussian corresponds to an element x of the random vector represents the fee of f(x). The use of the marginalization belongings for multivariate gaussians, we are able to achieve the marginal multivariate gaussian density corresponding to any finite sub-collection of variables. In general, any actual-valued feature is suitable, however for , it must be the case that for any set of elements x1….. Xm∈ x, then the ensuing matrix.

\[ K = \begin{bmatrix} \sigma^2(x_1, x_1) & \ldots & \sigma^2(x_1, x_m) \\ \vdots & \ddots & \vdots \\ \sigma^2(x_m, x_1) & \ldots & \sigma^2(x_m, x_m) \end{bmatrix} \]

It’s miles a valid covariance matrix similar to a few multivariate gaussian distribution. Astandard result in probability concept states that that is authentic provided that ok is positivesemidefinite. The advantageous semi definiteness requirement for covariance matrices computed based totally onarbitrary enter points. A feature is a valid kernel furnished the resulting kernel matrix okay defined as above is continually nice semidefinite for any set of enter points x1…….xm∈ x. Gaussian procedures, consequently, are kernel-based opportunity distributions inside the feel that any valid kernel characteristic may be used as a covariance characteristic.

VI. PERFORMANCE OF SIMULATED MODEL

This section discusses about the construction and working of the every element used in the process to demonstrate the aim of this paper by using the Matlab software. Using the simulated data in the graphical user interface of the Matlab software that is voltage values that are recorded on the time scale is used to calculate the density function of P(A|B). Then data under the curve is edited to form a neural network which is employed to detect the fault and monitors the type of fault that occurred on the power system .

VII. SAMPLING THE DATA FOR THE CALCULATION OF LIKELIHOOD PROBABILITY FUNCTION

At first process begins with the collection of different voltage readings corresponding to system conditions either the fault or no fault condition.

The graph shows the magnitude of voltage at various data points on a single phase. This procedure is repeated for remaining phases to get the required sample data sets. Then mean and covariance values are calculated by using these constructed data sets. Values which are obtained after the evaluation is get substitute in the Gaussian process to get the values of X at x1…x_n. The Bayesian approach discussed in earlier parts the entire data set is consider being the likelihood to estimate the posterior distribution.

![Fig. 4 likelihood distribution of sample Y](image)

Now the new observation Y as y_1…..y_n is made it will processed to the already existing likelihood p(Y) to estimate the posterior distribution p(X|Y). This means every time a new set of values is available, when the set Y is placed in the posterior distribution. The data that received from the distribution function (data under the bell) is separated. The valued and separated information is compared with the already existing simulated data, which are used to form a separate data sheet to train a neural network that can identify the type of fault occurred on the power system.

VIII. ARTIFICIAL NEURAL NETWORK

Artificial neuralnetwork (ann) [18] makes use of the processing of the mind as a foundation to increase algorithms that can be used to version complex styles and prediction troubles [16]. Those are an training processing model that is adopted with the aid of the way organic frightened structures, inclusive of the human mind, manner records. The vital detail of this version is the little by little structure of the statistics processing device. It is built of a large variety of exceedingly interconnected processing factors (neurones) operating in concurrently to crack a specific problems. Anns is like human brains, study by examples. An ann is built for a specific software, inclusive of pattern reputation and records type [6], via a studying procedure .
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Lower back propagation [19] neural community is employed in this fault detection procedure. It’s miles a feedback type machine that makes use of errors signal to modify the weights of the neural network to get the desired output this is the method calculates the gradient of loss function with respect to all weights within the network. The gradient [16] is fed to the optimization technique which in turn uses it to update the weights, in an attempt to minimize the loss feature. A two-layer feed-forward network with sigmoid hidden neurons and linear output neurons can healthy multi-dimensional mapping [17] troubles arbitrarily well, given constant statistics and enough neurons in its hidden layer. The network will be skilled with backpropagation algorithm, until there is not sufficient reminiscence, in which case scaled conjugate gradient backpropagation may be used. The simulated community includes input layer, hidden layer, output layer. It feed with line voltage values at the side of the time axis. The network here is the use of ‘trainlm’ trining function. TrainLM is a community education feature that updates weight and bias values in keeping with levenberg-marquardt optimization. TrainLM is often the quickest backpropagation algorithm [18] within the toolbox, and is fantastically advocated as a primary-preference supervised algorithm, even though it does require more memory than different algorithms. This feature makes use of the jacobian for calculations, which assumes that overall performance is a median or sum of squared errors. And the adaptive getting to know program used by the community is gradient boosting system characteristic. To establish a reference to the statistical framework, a gradient-descent based components of boosting methods was derived. This framework also provided the essential justifications of the version hyper parameters and established the methodological base for in addition gradient boosting model improvement. The mastering system consecutively suits new fashions to offer a extra accurate possibility of implementing one's personal assignment-particular loss.

Fig. 6 neural network for fault detection

The fault detection process [5] is totally depending on predetermined values and the error that back forwarded during process of evaluation. The output of network is a single variable with respective to the three phase line voltage. The result of the system is equivalent to respective inputs that are measured from the power lines.

IX. EXECUTION OF SIMULATION MODEL

The model is consists of basic transmission system stages that is generation, transmission and demand side. The source side is taken as constant voltage station that delivers 230kv rms line voltage. The 3-segment source offers a balanced 3-section voltage supply with internal r-1 impedance. The three voltage sources are linked in y with an impartial connection that now not grounded. The source inner resistance and inductance can specify by using converting the source inductive short-circuit stage and x/r ratio. The source internal resistance is 0.8929 ohms (Ω). The source internal inductance is 16.58e-3 henry (H).

The transmission lines shown here are characterize with the pi section parameters and complete line is parted into two where the fault get created in between two pi section lines. The specifications each pi section of the transmission line is shown below as:

Positive-sequence resistances (Ohms/km) \( r_1 \) = 0.01273
Zero-sequence resistances (Ohms/km) \( r_0 \) = 0.3864
Positive-sequence inductances (H/km) \( l_1 \) = 0.9337e-3
Zero-sequence inductances (H/km) \( l_0 \) = 4.1264e-3
Positive-sequence capacitances (F/km) \( c_1 \) = 12.74e-9
Zero-sequence capacitances (F/km) \( c_0 \) = 0.01273
Line size (km) = 100

Fig. 7 simulation model for fault detection

The result of the system is equivalent to respective inputs that are measured from the power lines.
When fault occurred on the line, voltage waveform gets distorted and gives harmonic content. The bus at the receiving end measure the three phase voltage and fed the values to the neural network which was trained. The ANN classifies the fault type by evaluating the given input to it.

<table>
<thead>
<tr>
<th>Type of fault</th>
<th>Trained input</th>
<th>Output of neural network</th>
</tr>
</thead>
<tbody>
<tr>
<td>AB</td>
<td>1</td>
<td>1.6</td>
</tr>
<tr>
<td>AG</td>
<td>2</td>
<td>2.6</td>
</tr>
<tr>
<td>BC</td>
<td>3</td>
<td>2.8</td>
</tr>
<tr>
<td>BG</td>
<td>4</td>
<td>3.9</td>
</tr>
<tr>
<td>AC</td>
<td>5</td>
<td>5.1</td>
</tr>
<tr>
<td>CG</td>
<td>6</td>
<td>5.9</td>
</tr>
<tr>
<td>ABC</td>
<td>7</td>
<td>6.8</td>
</tr>
<tr>
<td>NO_FAULT</td>
<td>0</td>
<td>0.5</td>
</tr>
</tbody>
</table>

Table. Output of ANN for different types of faults

The neural network trained here on the input which is optimized by the Bayesian process. The data that received at the beginning was separated by highest probability rate which categorized into faulty and non-faulty readings. This sequential process is one time process to display the above shown output.

X. CONCLUSION

In this paper The Bayesian optimization method was used to optimize the sample data and converges to required result with minuscule amount of error due to repeated data points and tiny error in calculation of weights of neural network. The objective of fault identification by comparing the slight variation values of the detail signal in different phases. The Gaussian process algorithm for the Bayes theory allows us to estimate the true region and that give access to explore the behaviour of power system faults by using different types of data set. The evaluated posterior distribution divulges probabilistic density of each individual data point in the unknown data set that goes under Gaussian distribution. So the algorithm depends on the pre-recorded data and post-recording data sets to confine the fault type. The following figure explains the difference between the normal data set and optimized data set.

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