Enhancing the Performance of DPFC with Different Control Techniques

D Narasimha Rao, P Srinivas Varma

Abstract: Modern day power system statistics and dynamics include the management and supplementing of reactive power in accordance with load requirements and specific considerations. The losses are significantly increased and reduces the ability of power delivery to the load end is attributed to the poor reactive power management. The FACTS technology is the latest revolution in the field of transmission systems which improve the worth and steadfast of power arrange to the load end. Among the various FACTS devices, Distributed Power flow controller is discussed in this paper and the suitable control schemes for the power flow controller are analyzed and the appropriate one is proposed. The various control techniques are traditional proportional integral method, sliding mode converter, fuzzy based control and artificial neural network assisted control strategy. The performance measure is harmonic analysis of the source current and voltage across the load. MATLAB/SIMULINK is the software platform used to defend the advantages of the superior control technique compared to others.

Index Terms: power flow, transmission system, flexible AC transmission, Distributed power flow controller, proportional integral control.

I. INTRODUCTION

Power flow is limited by control of active power in the present day power system scenario using different controlling techniques and devices called power flow controlling devices. Flexible AC transmission system is a revolution in the area of transfer of power transmission system. Distributed Power - flow controller (DP FC) is a novel variant of Unified Power - flow controller (UP FC) and a class of FACTS device which control various parameters like voltage of the buses, impedance of the power line, phaseangle adjustment between starting and finishing end voltages. The operation of the shunt converter does not relate or depend on the operation or working of series converter due to the absence of dc link in case of DPFC. The design of series converter is based on distributed concept of modeling of FACTS controllers. The reliability of the transmission system and minimization of the overall cost is achieved by the usage of individual single phase converters in contrast to the traditional three phase converter. The DPFC configuration is based on the transmission line enabled exchange of active power in the system which predominantly occurs in at 3rd harmonic frequency order. Single phase to ground voltage applied to the converter of the DPFC, eliminates the need for isolation of high voltage components. Therefore, the reduced cost of economics is an added advantage for DPFC unlike UPFC. The expanding use of power causes more request in utilizing the sustainable power provenance make it mandatory to control a colossal power that empowers the power framework for a fast link between the sustainable power sources and the remain by control age. This requests the accessibility of remain by control at whatever point sustainable power source can't supply the heap [1].Therefore the need to control the power techniques is expanded. The specification used to control voltage esteem, transmission edge, line impedance is balanced with a specific end goal to improve the power stream [2, 3]. The Power Flow Controlling Device (PF-CD) is a gadget that tries to change framework specification to upgrade the power stream execution. The joined FACTS parts are the proper gadgets to upgrade dynamic power stream. [4, 5]. The UPFC is the capable PF-CD, ready to alter line inside edge of the machine, transport voltage, and the specification of power line framework. The real task of the UPFC is executed with arrangement converter by infusing the voltage, to control stage point, extent, of the power line [6]. DPFC copies UPFC in freely modifying the line impedance, control ability, inner point between the transport voltage and instigated EMF [7]. In DPFC there is nonattendance of DC connect which makes to interface converters consecutive in UPFC.

Fig.1. Complete Line Diagram of DPFC System

The electrical representation of the DPFC circuit arrangement is presented in Figure 1. The presence of an separate capacitor to each single phase series converter is a remarkable feature in case of DPFC. Another significant variation that is exclusively found in DPFC is that the incorporation of filter.
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typical high pass filter, which an extra element added to the line if it encounters a star delta transformer configuration.
The reasons for choosing DPFC over UPFC is attributed to the following points
i. Minimization of the cost due to reduced rating of series converter and absence of the need for large voltage isolation.
ii. The steadfast of the overall circuit configuration is enhanced due to the choice and arrangement of series converter.

II. DPFC PRINCIPLE

The exchange of the regulation of the active power is enabled through the transmission line existing between AC terminals of the series and shunt converters. Fourier analysis is an robust computational tool for the microscopic harmonic analysis of the voltage and current waveforms [7].
The active power of the transmission system is given by

\[ P = \sum_{i=1}^{\infty} V_i I_i \cos \theta_i \]  (1)

\( i \) = frequency of the harmonics and denoted by order

\( V_i \) = Voltage across the line to ground

\( I_i \) = current flowing through the line

\( \theta_i \) = phase difference between the harmonic voltage and current

From the expression, it is noticed that at dissimilar frequencies, the real power is isolated from each other and the active power at any frequency is not altered by the magnitude or phase angle of the current and voltage. The frequency component does not show any variation on the active power. Therefore, the active power can be generated and transferred as well as consumed at different frequencies. There is no frequency constraint on the flow of the active power.

In case of DPFC, the parallel converter takes the reactive power from the grid at the base frequency i.e., system nominal frequency. This reactive power is inserted into the grid at an frequency other than elementary frequency whenever required [7-8]. The current corresponding the non elementary frequency will pass through the high power line system. The series converter of the DPFC generates the useful power on the basis of the requirement for active power at the nominal frequency. The effective power consumed and generated the base frequency and off nominal frequencies respectively are said to be equal and same.

The off nominal frequencies are allowed through the high pass filter which facilitate return path for the harmonic components. The path provided by the series converter of DPFC; shunt converter of DPFC in combination with the ground. Among the harmonics present in the system, 3rd harmonic is dominating and has special attention compared to the other harmonics. Therefore, the third harmonic is chosen for the facilitation of active power exchange the undesirable zero sequence component present in the system which can be subsided by the appropriate transformer connection namely star delta configuration. This transformer scheme for arrangement of winding is predominantly used in the maximum times during the operation of power system for variation in the voltage level. Therefore, this configuration for mitigation of zero sequence components eliminates the need for any other filtering arrangements [8, 9].

2.1. Control principle of DPFC

The control of the novel FACTS device, DPFC involves control of the two DPFC converters and a coordinated control scheme for the two converter controls. The entire control scheme is depicted in Figure 2. The converter control scheme is employed at the respective terminals of the converter and is called local controllers. The centralized control coordinates the individual converter controllers in addition to the control of various parameters of DPFC.

2.1.1. Main Control

At the framework level, the focal control is subject to the useful task of the DP-FC; they are sodden out power motions at low recurrence, control stream control and awry segments adjusting. The preeminent capacity of the principle control regularly known as focal controller is to produce reference signals for supervised converters of the DP-FC. These are produced at the framework recurrence. [8] The focal control gives mentioned value of current and voltages for both the controllers as per the framework necessity.

2.1.2. Series Control

Arrangement series control is available in all the single stage supervising circuits. The controller is to settle the capacitor voltage of converter will help of third symphonious voltage or streams. [7] It infuses voltage at supply recurrence affirmed by the fundamental control. In DP-FC arrangement converter control, the real control circle is the third consonant recurrence control. For DC voltage control phasor control standard is connected [9].

2.1.3. Shunt Control

It infuses a settled power which blend of key and third symphonious segment current into transmission line keeping in mind the end goal to transmit the genuine power for arrangement converters is the principle target of shunt control. At the key recurrence of the third consonant current and transport voltage are bolted. The adage of parallel converter is to trade required Q VAR’S to framework and furthermore keeping up settled DC capacitor voltage [7, 8, 9].

III. METHODOLOGY
3.1. Controller pattern using PI

The transfer function of the PI controller is described as:

\[ H_p(s) = K_p + K_i s \]  (2)

Corresponding increase is inferred utilizing \( K_P = 2.2 \zeta \omega_n C \) which ascertains the execution of the DC interface voltage control. So also, the vital pick up is inferred utilizing \( K_I = \text{Con}2 \) that decides its settling time.\[10\] The PI controller is to set the DC-interface voltage as adequacy of the d hub current of the APF inverter to control the DC-connect voltage for covering the inverter misfortunes in view of its reference esteem. The distinction of reference estimation of the APF present and estimated esteem estimated load or stack current.

3.2. Sliding Mode controller (SMC) of DC voltage

SMC strategy has been normally applied for power converters problems, because of its operation characteristics like stability, response quick and strength throughout high variation in load \[11, 12\]. The management action SMC utilizes SM theory as a jump perform that is given by the equation (3).

\[ s(y) = k \cdot \text{sign}(y) \]  (3)

The Lyapunov perform should be dropped at zero; and to attain this, it's decent that its spinoff isn't positive \[11\]. To minimize the chattering development thanks to the discontinuous nature of the controller, it is important to outline a unique function in neighborhood of the slippy surface with most and minimum limit value. If a degree of the state mechanical phenomenon falls at intervals this interval, a swish function will replace the discontinuous a part of the control. Thus, the controller becomes

\[ u_n = \{ k_c \cdot \varepsilon(y) \text{ if } |s(y)| < \varepsilon \neq 0 \}
\]

\[ k_c \cdot (s(y)) \text{ if } |s(y)| > \varepsilon \]  (4)

Where, \( k_c \) represents the optimal finest value. In order to control the DC link voltage \( V_{dc} \) and to remove the chattering by using this SMControl, the block diagram of the SMC strategy is given by Fig. 3. As per Fig.3, the sliding surface \( d_1(y)/d_2 = 0 \) is used to synthesis a command current \( I^* \). In this case I is given by

\[ I^* = k_c \cdot s_i g(\sigma_c) \]  (5)

![Fig.3. line diagram of SM Controller for voltage setup](image)

3.3. Introduction and Design of proposed methodology

Fuzzy Logic Controller

There are two noteworthy parts of fuzzy rationale controller they are Takagi– Sugeno and Mamdani compose, in light of fluffy tenets segments were arranged this paper is centers around mamdani type fuzzy controller with a specific end goal to demonstrate the change in execution of DPFC. Reference estimation of DC voltage on DC Side and ordinary estimation of DC voltage on DC side of arrangement converter were utilized as fluffy controller inputs and the yield of fluffy controller is third consonant part of Direct Axis Component Reference arrangement infused voltage Fuzzification is where input factors are mapped onto fluffy factors each fuzzified variable as a specific participation work, here the data sources are fuzzified into seven fluffy sets seven enrollment capacities were utilized as a part of this paper which was trapezoidal and triangular fit as a fiddle. Both yield and info are fuzzified utilizing fluffy set which are viewed as seven they are Z(Zero), SP(Short - Positive), MP(Medium - Positive), SN(Small - Negative), MN(Medium Negative), LN(Large - Negative)\[13\] which are said in figures 4, 5, 6 and Table 1.

![Fig.4. Membership functions of Input 1](image)

![Fig.5. Membership function of Input 2](image)

![Fig 7:Membership function of output](image)

<table>
<thead>
<tr>
<th>Fuzzy Rule Based table</th>
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<tr>
<td>( \zeta )</td>
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<tr>
<td>LN</td>
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<tr>
<td>MN</td>
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<td>SN</td>
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<tr>
<td>ZE</td>
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<tr>
<td>SP</td>
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<tr>
<td>MP</td>
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<td>LP</td>
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3.4 ANN controller of DC voltage

Manufactured manmade Neural Network is a piece of the group of factual learning techniques motivated by organic sensory system and are utilized to appraise and surmised capacities that depends just on an extensive number of information sources. ANN is an interconnection of neurons which send messages to each other. The associations have numerical weights that can be tuned in view of understanding. This paper draws consideration on the multi-layer sustain forward ANN which that of the nonlinear multivariable capacity portrayal. The ANN is utilized for the mapping between the distinction of reference DC and Changed Value of DC on DC side of arrangement converter for appropriate working conduction and ideal controller parameter [14,15].

IV. SIMULATION RESULTS

To reenact the DPFC with PI, SMC, FUZZY and ANN controllers a model in Matlab/Simulink is created. The

Simulink demonstrate is appeared in Fig.8. Reenactment works are completed to break down the DPFC execution in a transmission framework. A two transport control framework is considered for reenactment. Dynamic Power streams between the two transport frameworks are gotten by permitting distinctive stage between the two frameworks. DPFC comprises of 6-single stage arrangement converters and shunt controller. The parallel converter is a 1-Ø controller set between nonpartisan purpose of - Y transformer and strong ground, and on its opposite side is empowered by steady DC source. Here a transmission framework with a voltage of 380V and 50Hz is considered. The framework parameters in Simulink and estimated estimations of converter are appeared in table 2 and 3. The Simulation Results of proposed Simulink display are appeared in figures 9, 10, 11 and 12. The Conclusion execution of DPFC with various control strategies as far as Harmonic bending level is appeared in table 4.
Fig. 11. Bus Voltage Current at delta side of the transformer

Fig. 12. Line Current Due to step response

Fig. 13. Both active and reactive power injected by series converter

Table 2: System parameters in Simulink

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Abbreviation</th>
<th>Value</th>
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<tbody>
<tr>
<td>Vr</td>
<td>Sending end voltage</td>
<td>220 V</td>
</tr>
<tr>
<td>Vr</td>
<td>Receiving end voltage</td>
<td>210 V</td>
</tr>
<tr>
<td>L</td>
<td>Inductance component in line</td>
<td>6 mH</td>
</tr>
<tr>
<td>0</td>
<td>Angle between two end bus voltages</td>
<td>1°</td>
</tr>
</tbody>
</table>

Table 3: Measured Values of converter

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Description</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Vs</td>
<td>Maximum shunt voltage by shunt converter</td>
<td>50 V</td>
</tr>
<tr>
<td>Ish,max</td>
<td>Maximum shunt current by shunt converter</td>
<td>9 A</td>
</tr>
<tr>
<td>Ish,ref</td>
<td>Shunt converter reference third harmonic current</td>
<td>3A</td>
</tr>
<tr>
<td>Vsh,dc</td>
<td>Source supply</td>
<td>20V</td>
</tr>
<tr>
<td>Vse,max3</td>
<td>Series converter Maximum ac voltage at line side of</td>
<td>7 V</td>
</tr>
<tr>
<td>fsw</td>
<td>Series Converter Switching frequency for shunt and</td>
<td>6 kHz</td>
</tr>
<tr>
<td>Ise,max</td>
<td>Series Converter peak ac current at line terminal of</td>
<td>15 A</td>
</tr>
</tbody>
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Figures 14, 15, 16, 17 which represent THD percentage on injected voltage by series converter with different control techniques
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V. CONCLUSION

The DPFC is utilized for transmission system in this paper with two different control strategies namely traditional and proposed controllers. The performance response in terms of system dynamics is improved by using controller. The performance of DPFC by using different control techniques like SMC, FUZZY and Neural technique the improved performance has been studied on injected voltage and receiving end current by considering their THD values for certain period during dynamic variations conditions. Another remarkable feature of the controller is that the line voltage present of the series converter is regulated. The harmonic analysis of the current and voltage waveforms demonstrate the effectiveness of the proposed control strategies.

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Table 4: DPFC with different control techniques in terms of Harmonic distortion level

<table>
<thead>
<tr>
<th>Type of Controller</th>
<th>Elementary Injected Voltage (%)</th>
<th>Current at receiving end (%)</th>
</tr>
</thead>
<tbody>
<tr>
<td>PI</td>
<td>19.98</td>
<td>3.8</td>
</tr>
<tr>
<td>SMC</td>
<td>20.1</td>
<td>3.5</td>
</tr>
<tr>
<td>FUZZY</td>
<td>21.49</td>
<td>3.38</td>
</tr>
<tr>
<td>NEURAL NETWORK</td>
<td>19.5</td>
<td>3.6</td>
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</table>