

Research on Harmonics and Ripple Content in Vector Control Schemes for Induction Motor

M.Rama Prasad Reddy, T.Sudhakar Babu, A.Suresh Kumar,U.Chaitanya

Abstract— on this paper 3 considered one in every of a type vicinity based totally vector manage plans are enlisted for the assessment of the track and swell substance texture inside the engine flows and reliable kingdom torque waveforms. the interest in those vector oversee plans is, the reference flows are produced is as on the subject of ordinary vector control and selection of the voltage vectors is as almost about coordinate torque oversee. So the ones vector manipulate plans be part of the requirements of both conventional vector oversee and direct torque manage. the ones plans are confirmed within the MATLAB/Simulink scenario and the consequences are as concept approximately amongst them.

Watchwords—FOC, DTC, Induction engine, exchanging table, vector manage

I. INTRODUCTION

The gifted one within the cutting-edge pressure engine is popularity engine because it were. that is because of its much less assist and low weight volume share. From the preceding four many years many variety of controlling methods were proposed for the enlistment engine manipulate sports. among those the scalar manipulate method is giving the sluggish reaction, to conquer those complexities associated with the scalar control ordinary FOC become proposed in [1]. The FOC gives quick and dynamic transient response because of the decoupled control of transition and torque. Be that as it may, there is a downside on this FOC likewise that is the reference define modifications. To decrease the unpredictability engaged with the FOC the DTC was proposed in [2]. further, to build the adequacy of these manipulate systems staggered sustained acceptance engines are applied. A correlation amongst DTC and FOC of stage strengthened enlistment engine drive changed into talked about in [3]. Later couple of control strategies that are applied for the misfortune advancement methods of FOC of IM force [4]. some other manner with brief and dynamic calculation is proposed in [5] with LabVIEW. The ever calculation technique SVM based totally inverter interest with 8 switches is proposed in [6] with the traditional FOC method simply, yet the replacing of the inverter activates complicated calculation. In [7], a close to file on various adjustment strategies for the FOC changed into proposed. each this kind of strategies applied the fast and dynamic calculation frameworks.

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To overcome the downsides of ordinary vector control calculation and to lessen the calculation problem at the processors, in this paper, in this paper three notable territory fundamentally primarily based vector control plans are applied for the examination of the tune and swell substance in the engine flows and normal kingdom torque waveforms. the freshness in

The ones vector oversee plans is, the reference flows are produced is as in understanding to everyday vector manipulate and desire of the voltage vectors is as in undertaking with direct torque oversee. So the ones vector manipulate plans consolidate the fashions of every customary vector control and direct torque oversee.

II. CLASSICAL QUARTER ORIENTATED MANAGE

Within the Classical hassle oriented manage strategy the decoupling manipulate a massive quantity of the torque and motion is gotten with the precious asset of moving most people of the quantities to a synchronous reference frame. so the torque trouble i_{qs}^* and the transition fabricating aspect i_{ds}^* is created with the manual of stator front line vector is i_s^* . anyway in mild of the decoupled manage the appealing influenza brought on the whole with q-pivot is zero. by techniques for method for this the electromagnetic torque condition is modified as

$$T_e = \frac{3}{2} \frac{P}{L_r} \frac{L_m}{L_r} (\psi_{dr} i_{qs}^*) \quad (1)$$

In this paper the main attention is focused on rotor flux angle calculation. This rotor flux angle calculated from (2).

$$\theta_s = \theta_r + \theta_{sl} = \int (\omega_r + \omega_{sl}) dt \quad (2)$$

$$\omega_{sl} = \frac{L_m R_r}{L_r \lambda_r} i_{qs}^*$$

Where

Proposed Vector control methods

The electromagnetic torque of an induction motor is expressed as

$$T_e = \frac{3}{2} \frac{P}{L_r} \frac{L_m}{L_r} |\bar{\lambda}_r| |\bar{i}_s| \sin \delta \quad (3)$$



RESEARCH ON HARMONICS AND RIPPLE CONTENT IN VECTOR CONTROL SCHEMES FOR INDUCTION MOTOR

In which is the factor of view among and . as a result, a short control on torque might be completed by way of techniques for manner of controlling the factor anyway due to the widespread idleness of rotor circuit; the version within the rotor transition is practically reliable for a fast time intervening time. accordingly from the condition (three) the torque may be restrained by using converting over the stator cutting area angle. this will be achieved through way of changing the stator carry voltage. From the above situation the stator reducing part vector got as

$$\Delta \vec{i}_s = \frac{1}{\sigma L_s} \vec{v}_s \Delta t \quad (4)$$

By means of choosing the precise voltage vector it's miles then viable to alternate stator contemporary in required way. for this reason the decoupling manipulate may be carried out among i_{ds} and i_{qs} additives of the stator modern-day vector.

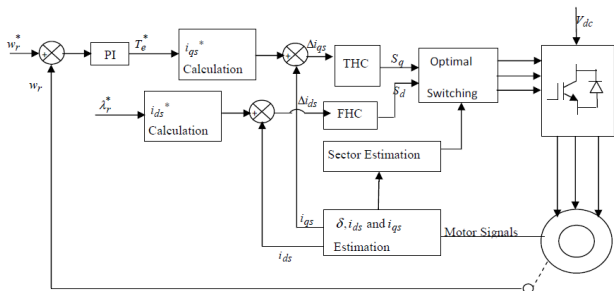


Fig.1. Block diagram of proposed vector controlled induction motor drive

The square graph of the predicted vector manage set of guidelines is as analyzed in Fig. 1. in the expected oversee method, the reference stator slicing side components are at synchronously pivoting reference outline. the ones are altogether created through the usage of the usual of normal vector manage set of recommendations. At that factor, inside the anticipated manage hysteresis comparators are utilized for torque and motion control. with the high-quality useful useful precious asset of taking the reference stator present day-day-day segments and actual stator modern parts, the mistake the front line day signs and indications and facet effects and signs and side results and symptoms are delivered. those blunders cutting edge signs and symptoms and symptoms and side effects and signs and symptoms and manifestations and signs and side consequences and symptoms and indicators and signs and side effects is probably given to the torque hysteresis comparator (THC) and transition hysteresis comparator (FHC). the ones hysteresis comparators will create the digitized yields based totally absolutely clearly past query honestly for the most component on the combination-up sizes. based at the digitized yields of the hysteresis comparators and normal for the stator present day-day (so that you can provide region assortment), the proper voltage vector are settled on a super method to preserve the blunder esteems in the evaluated data transmission of the hysteresis comparators.those notable voltage vectors

may be helpful to the voltage supply inverter sustained enlistment engine stress.

A. Six location essentially based actually definitely Vector oversee The practicable voltage vectors for a 2-degree inverter may be spoken to as inspected in Fig.

three, which incorporates six exuberant states and 0 states. on the equivalent time as, the isis within the major locale as tried in Fig.three, at that factor voltage vectors V2 and V6 can development the i_{ds} and V3 and V5 can deliver down the i_{ds} . further V2 and V3 can enlarge the torque factor contemporary-day-day i_{qs} and V5 and V6 can convey down the i_{qs} what's greater the excellent voltage vectors can be settled on for specific components. on this procedure, the cutting edge botches sizes are restricted to 2Dids and 2Diqs internal their separate hysteresis businesses. on the off hazard that enlargement in i_{ds} is required, at that factor $S_d = 1$; within the event that discount in i_{ds} is needed, at that factor $S_d = \text{zero}$. moreover, if increment in i_{qs} is required then $S_q = 1$, within the event that reduction in i_{qs} is needed, at that factor $S_q = -1$, and at the off threat that no exchange i_{qs} is needed, at that factor $S_q = \text{zero}$. The virtual yield cautions from movement difficulty hysteresis controller (FHC) and torque inconvenience hysteresis controller (THC) is probably abridged as in desk. 1.

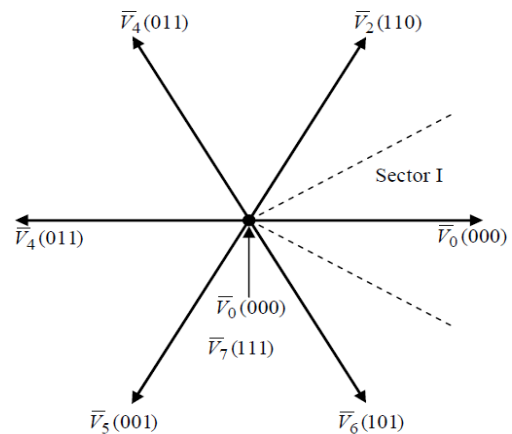


Fig. 2 Possible voltage space vectors for VSI

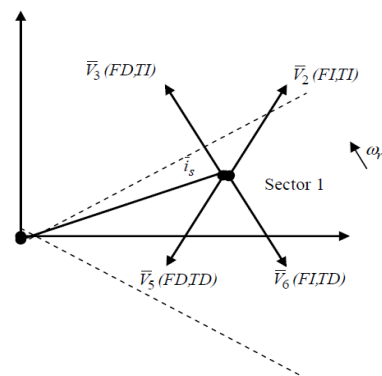


Fig. 3 selection of suitable voltage space vector insector I (-30° to 30°)

Table. 1 digitized output values of the hysteresis controllers

Controller	Condition	Output of the controller
FHC	$\bar{i}_{ds} \leq \bar{i}_{ds}^* - \Delta\bar{i}_s$	$S_d = 1$
	$\bar{i}_{ds} \geq \bar{i}_{ds}^* + \Delta\bar{i}_s$	$S_d = 0$
THC	For anti-clockwise rotation	
	$\bar{i}_{qs}^* - \bar{i}_{qs} \geq \Delta\bar{i}_{qs}$	$S_q = 1$
	$\bar{i}_{qs} \geq \bar{i}_{qs}^*$	$S_q = 0$
	For clockwise rotation	
	$\bar{i}_{qs} \leq \bar{i}_{qs}^*$	$S_q = 0$
	$\bar{i}_{qs}^* - \bar{i}_{qs} \leq -\Delta\bar{i}_{qs}$	$S_q = -1$

Fundamentally dependent on the estimations of S_d, S_q and the situation of the stator current vector, the perfect voltage vector is chosen from the investigations work area as given in table. 2.

B. 12-division based absolutely totally Vector control in the 6-locale based vector control, best an incomplete state of vigorous voltage vectors are utilized each region. a top notch approach to use each of the six vivacious states in each locale and to reduce the THD what's more, the space vector flying machine is isolated into twelve parts in decision to 6 as affirmed in Fig. four. however, it's miles required to give a reason to little and huge deviations. it is seen that V1 will deliver an enormous increment in motion and a little development in torque in zone-12. as a substitute it is discovered that V2 will create an enormous addition in torque and a little augmentation in motion. The anticipated 12-zone essentially based vector oversee rehearses a four phase torque hysteresis controller (TI: torque development, TSI: torque little development, TD: torque abatement and TSD: torque little cut cost) and a level motion hysteresis controller. the appearance up work area for 12-zone based absolutely FOC is realistic in table 3.

Table. 2 Optimum voltage vector switching table for 6-sector based vector control

Sectors		I	II	III	IV	V	VI
Sd	Sq						
1	1	\bar{V}_2	\bar{V}_3	\bar{V}_4	\bar{V}_5	\bar{V}_6	\bar{V}_1
	0	\bar{V}_7	\bar{V}_0	\bar{V}_7	\bar{V}_0	\bar{V}_7	\bar{V}_0
	-1	\bar{V}_6	\bar{V}_1	\bar{V}_2	\bar{V}_3	\bar{V}_4	\bar{V}_5
0	1	\bar{V}_3	\bar{V}_4	\bar{V}_5	\bar{V}_6	\bar{V}_1	\bar{V}_2
	0	\bar{V}_0	\bar{V}_7	\bar{V}_0	\bar{V}_7	\bar{V}_0	\bar{V}_7
	-1	\bar{V}_5	\bar{V}_6	\bar{V}_1	\bar{V}_2	\bar{V}_3	\bar{V}_4

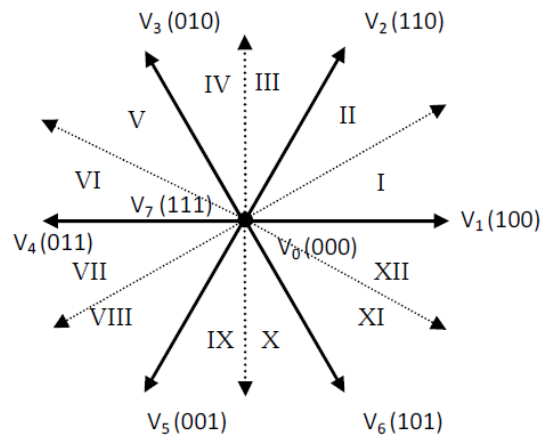


Fig. 4 Possible voltage space vectors for VSI in 12-sector based vector control algorithm

C. 24-place basically primarily based Vector oversee to diminish the THD improvement, on this paper a 24-locale basically based totally vector manipulate set of regulations has been anticipated. in this technique the distance vector air deliver is a component into 24 regions as permitted in Fig. five. in this framework, just like the 6-segment primarily based surely thoroughly manage method, the bleeding area botches extents are restrained to twoδids and more than oneδiqs interior their person hysteresis groups. in the 24-region manipulate, 3-arrange hysteresis controllers are utilized for d-and q-tomahawks current controllers. The arrangement of the 3-diploma hysteresis controller is related to that of q-pivot modern-day controller of 6-location based totally honestly vector oversee calculation.

Table. 3 Optimum voltage vector switching table for 12-sector based vector control

S_d	S_q	S_1	S_2	S_3	S_4	S_5	S_6	S_7	S_8	S_9	S_{10}	S_{11}	S_{12}
1	TI	\bar{V}_2	\bar{V}_3	\bar{V}_3	\bar{V}_4	\bar{V}_4	\bar{V}_5	\bar{V}_5	\bar{V}_6	\bar{V}_6	\bar{V}_1	\bar{V}_1	\bar{V}_2
	TsI	\bar{V}_2	\bar{V}_2	\bar{V}_3	\bar{V}_3	\bar{V}_4	\bar{V}_4	\bar{V}_5	\bar{V}_5	\bar{V}_6	\bar{V}_6	\bar{V}_1	\bar{V}_1
	TsD	\bar{V}_1	\bar{V}_1	\bar{V}_2	\bar{V}_2	\bar{V}_3	\bar{V}_3	\bar{V}_4	\bar{V}_4	\bar{V}_5	\bar{V}_5	\bar{V}_6	\bar{V}_6
	TD	\bar{V}_6	\bar{V}_1	\bar{V}_1	\bar{V}_2	\bar{V}_2	\bar{V}_3	\bar{V}_3	\bar{V}_4	\bar{V}_4	\bar{V}_5	\bar{V}_5	\bar{V}_6
0	TI	\bar{V}_3	\bar{V}_4	\bar{V}_4	\bar{V}_5	\bar{V}_5	\bar{V}_6	\bar{V}_6	\bar{V}_1	\bar{V}_1	\bar{V}_2	\bar{V}_2	\bar{V}_3
	TsI	\bar{V}_4	\bar{V}_4	\bar{V}_5	\bar{V}_5	\bar{V}_6	\bar{V}_6	\bar{V}_1	\bar{V}_1	\bar{V}_2	\bar{V}_2	\bar{V}_3	\bar{V}_3
	TsD	\bar{V}_7	\bar{V}_5	\bar{V}_0	\bar{V}_6	\bar{V}_7	\bar{V}_1	\bar{V}_0	\bar{V}_2	\bar{V}_7	\bar{V}_3	\bar{V}_0	\bar{V}_4
	TD	\bar{V}_5	\bar{V}_6	\bar{V}_6	\bar{V}_1	\bar{V}_1	\bar{V}_2	\bar{V}_2	\bar{V}_3	\bar{V}_3	\bar{V}_4	\bar{V}_4	\bar{V}_5

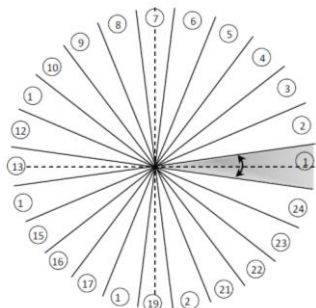


Fig. 5 Possible voltage space vectors for VSI in 24-sector based vector control algorithm

Table.4 digitized output values of the hysteresis controllers

Controller	Condition	Output of the controller
FHC	For anti-clockwise rotation	
	$\bar{i}_{ds}^* - \bar{i}_{ds} \geq \Delta \bar{i}_{ds}$	$S_q = 1$
	$\bar{i}_{ds} \geq \bar{i}_{ds}^*$	$S_q = 0$
	For clockwise rotation	
THC	$\bar{i}_{ds} \leq \bar{i}_{ds}^*$	$S_q = 0$
	$\bar{i}_{ds}^* - \bar{i}_{ds} \leq -\Delta \bar{i}_{ds}$	$S_q = -1$
	For anti-clockwise rotation	
	$\bar{i}_{qs}^* - \bar{i}_{qs} \geq \Delta \bar{i}_{qs}$	$S_q = 1$
THC	$\bar{i}_{qs} \geq \bar{i}_{qs}^*$	$S_q = 0$
	For clockwise rotation	
	$\bar{i}_{qs} \leq \bar{i}_{qs}^*$	$S_q = 0$
	$\bar{i}_{qs}^* - \bar{i}_{qs} \leq -\Delta \bar{i}_{qs}$	$S_q = -1$

Based on the values of S_d , S_q and sector number, the suitable voltage vector is selected from the lookup table as given in Table. 5.

Table. 5 Optimum voltage vector switching table for 24-sector based vector control

Sector	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24
d_q	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24
1	V_2	V_3	V_4	V_5	V_6	V_1	V_2	V_3	V_4	V_5	V_6	V_1	V_2	V_3	V_4	V_5	V_6	V_1	V_2	V_3	V_4	V_5	V_6	V_1
1	V_1	V_2	V_3	V_4	V_5	V_6	V_1	V_2	V_3	V_4	V_5	V_6	V_1	V_2	V_3	V_4	V_5	V_6	V_1	V_2	V_3	V_4	V_5	V_6
1	V_6	V_1	V_2	V_3	V_4	V_5	V_6	V_1	V_2	V_3	V_4	V_5	V_6	V_1	V_2	V_3	V_4	V_5	V_6	V_1	V_2	V_3	V_4	V_5
0	V_3	V_4	V_5	V_6	V_1	V_2	V_3	V_4	V_5	V_6	V_1	V_2	V_3	V_4	V_5	V_6	V_1	V_2	V_3	V_4	V_5	V_6	V_1	V_2
0	V_0	V_0	V_0	V_0	V_0	V_0	V_0	V_0	V_0	V_0	V_0	V_0	V_0	V_0	V_0	V_0	V_0	V_0	V_0	V_0	V_0	V_0	V_0	V_0
0	V_6	V_1	V_2	V_3	V_4	V_5	V_6	V_1	V_2	V_3	V_4	V_5	V_6	V_1	V_2	V_3	V_4	V_5	V_6	V_1	V_2	V_3	V_4	V_5
-1	V_4	V_5	V_6	V_1	V_2	V_3	V_4	V_5	V_6	V_1	V_2	V_3	V_4	V_5	V_6	V_1	V_2	V_3	V_4	V_5	V_6	V_1	V_2	V_3
-1	V_4	V_5	V_6	V_1	V_2	V_3	V_4	V_5	V_6	V_1	V_2	V_3	V_4	V_5	V_6	V_1	V_2	V_3	V_4	V_5	V_6	V_1	V_2	V_3
-1	V_5	V_6	V_1	V_2	V_3	V_4	V_5	V_6	V_1	V_2	V_3	V_4	V_5	V_6	V_1	V_2	V_3	V_4	V_5	V_6	V_1	V_2	V_3	V_4

III. SIMULATION IMPACTS AND TALK & RESULTS

To approve the anticipated examinations tables based absolutely totally point of fact vector control set of rules numerical recreation assessments were done through utilizing MATLAB. For the reproduction look into the engine parameters are taken as $R_s = 1.57\omega$, $R_r = 1.21 \Omega$, $L_m = \text{zero}.165H$, $L_s = 0.17H$, $L_r = 0.17H$ and $J = \text{zero}.089 \text{ Kg-m}^2$. also, for the reenactment results equivalent band widths have been estimated for the hysteresis groups

inside the anticipated and blessing contemporary-day controlled vector oversight drives. The recreation consequences of zone 6, 12 and 24 vector oversight acceptance engine stress are appeared in Fig.6-Fig.sixteen. From the reproduction impacts, it could be seen that the 24 research table based absolutely totally vector control calculations offer quick concise response like customary vector control set of principles. and yet as contrasted and the 6 area activity the 12 and 24 area activity is demonstrating a more slow reaction. moreover, it could be found that the 12 and 24 - part set of tips gives bounty considerably less acclaimed symphonious contortion (THD) charge at the equivalent time as contrasted and the 6 place fundamentally based completely most likely vector oversee set of proposals for same band width of the hysteresis controllers. moreover, the 12 and 24-locale based really vector control set of recommendations gives steady exchanging recurrence activity on a similar time as related with the six area vector control set of proposals, which can be seen from the engine torque swell and speed waveforms. From the steady u .s .a . recreation results and consonant spectra of line flows, it could be situated that the anticipated 24 quarter query table based vector control set of guidelines offers diminished symphonious mutilation while in assessment with the inverse control calculations.

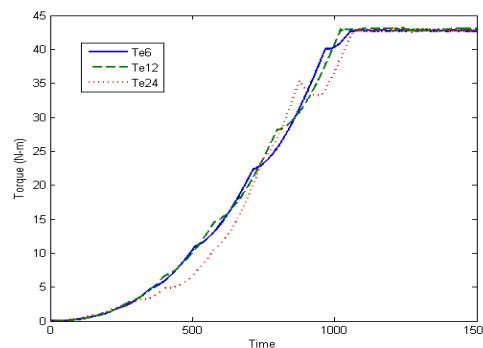


Fig. 6 Starting torque transients of 6, 12 and 24 sector based vector control.

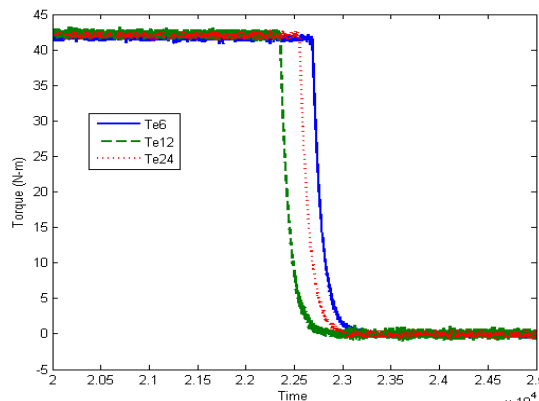


Fig. 7 Torque transients reaching the steady state of 6, 12 and 24 sector based vector control

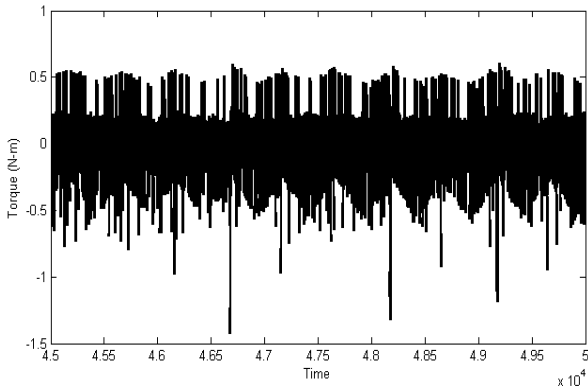


Fig. 8 Torque ripple during steady state (6 Sector)

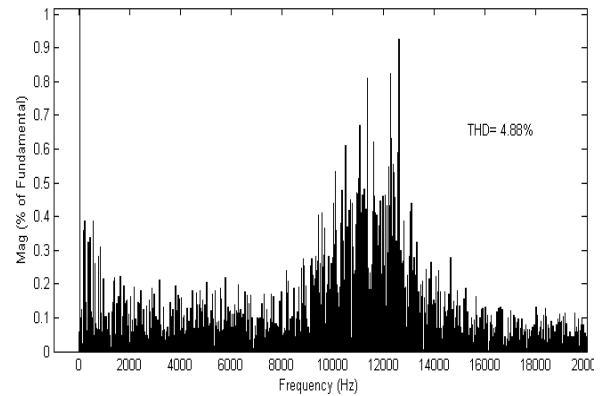


Fig. 12 %THD of 12 Sector based voltage oriented control of induction motor

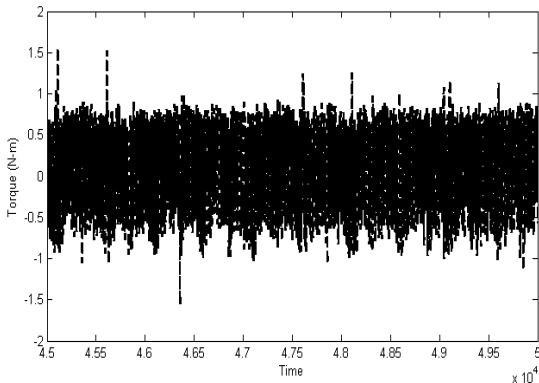


Fig. 9 Torque ripple during steady state (12 Sector)

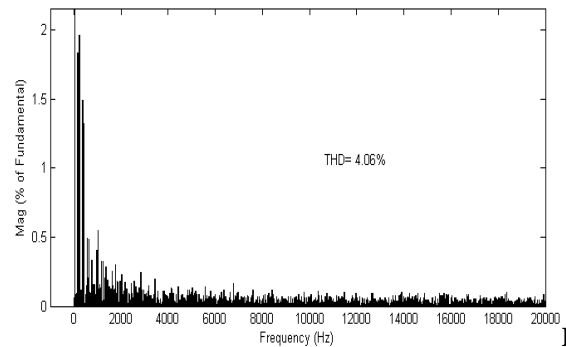


Fig. 13 %THD of 24 Sector based voltage oriented control of induction motor

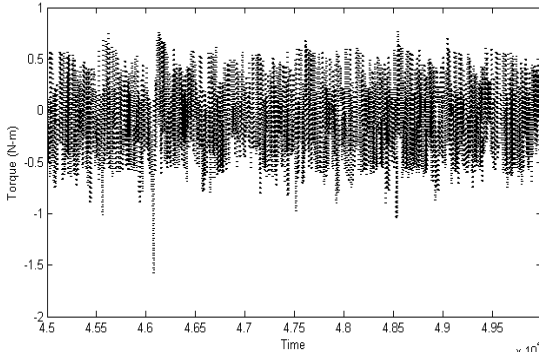


Fig. 10 Torque ripple during steady state (24 Sector)

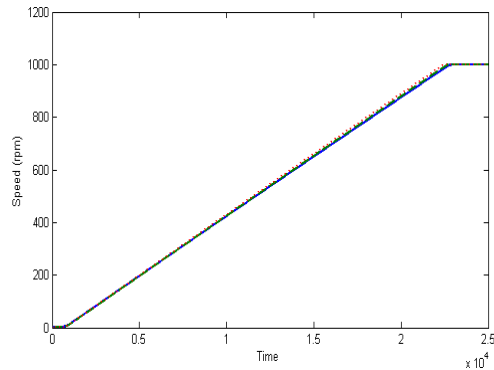


Fig. 14 Speed curve of 6, 12 and 24 Sector based voltage oriented control of induction motor

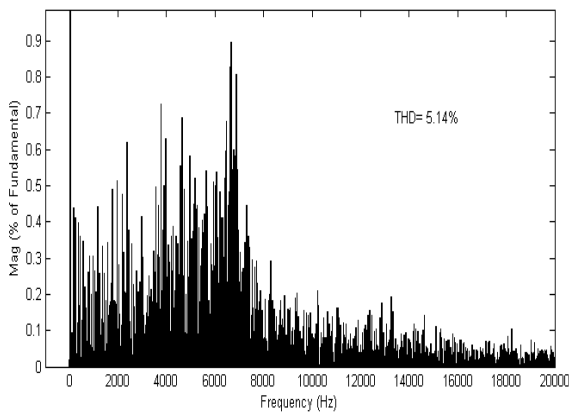


Fig. 11 %THD of 6 Sector based voltage oriented control of induction motor

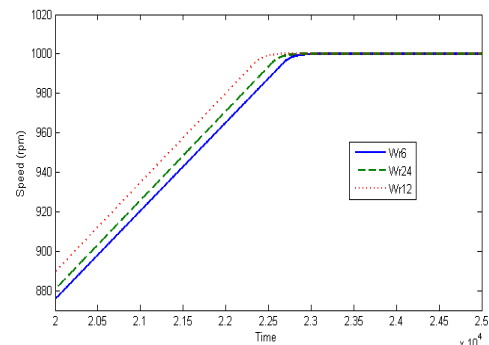


Fig. 15 Speed curve of 6, 12 and 24 Sector based voltage oriented control of induction motor reaching the rated speed

