

Multi Group Based Daily Living Activity Recognition (DLAR) using Advanced Machine Learning Algorithm

Doreswamy, Yogesh K M

Abstract: Human activity recognition (HAR) has realized more interest in several research communities given that understanding user activities and behavior help to deliver proactive and personalized services. Different types of noise in wearable sensors data frequently hamper the human activity recognition classification process. Categorically, in this proposed work designs the three-level hierarchical classification structure, i.e., instance based, group and sub-group based and subject based to detect the daily activity of human body motion among activity groups. In correlation with other famous classifiers, for such as Random Forest Tree, J48, Decision Table, Multilayer Perceptron, NaïveBayes, oneR and REPTree (Reduced Error Pruning Tree), etc., thorough experiments on the mHealth dataset (Shimmer2 mHealth Data) demonstrate that group based classification achieves the best classification results, reaching RFT 99.97%. We trained classifier in order to estimate accuracy classification based on (gender, age, height, and weight). We applied validation methods to the process, 10-fold cross-validation. For all three classification structure, we achieve high accuracy values for all three classification task.

Index Terms: 3D-Accelerometer, Shimmer2, HAR, Wearable Sensor, Machine Learning.

I. INTRODUCTION

Physical activity recognition utilizing wearable sensors has empowered established researchers to create novel applications, particularly in the region of social insurance and helped living. As of late, PDAs have been utilized for action acknowledgment, since they are promptly outfitted with a few Sensors helpful for action acknowledgment, for example, movement and area sensors. Additionally, they are conveyed by nearly everybody in their day by day lives [1]. Be that as it may, as far as we could possibly know, there is no examination exploring the presentation of these sensors in detail considering distinctive capabilities, more tasteful, diverse telephone conveying positions, both independently, just as in mix. A few scientists have just explored the blend of different movement sensors in action acknowledgment [2]. For instance, in be that as it may, these past investigations have investigated the blend of different movement sensors just in some specific situations. So as to respond to our inquiry, we think about the job of these sensors in detail in various situations [3]. We completed three diverse

assessment situations so as to cover the most normally utilized situations in the past investigations Specifically client with his/her own information. In addition, we assess the acknowledgment execution with four unique sensors: an accelerometer, a spinner, a direct speeding up and a magnetometer and a gyro meter, a magnetometer [4]. The straight speeding up sensor is a virtual sensor, got from the accelerometer by expelling the gravity part. These sensors are chosen Sensors since they were utilized in past action acknowledgment thinks about [5]. The fundamental center, in any case, is on the accelerometer and the spinner, since these are the for the most part utilized sensors in comparative examinations. Specifically, the objective of this paper is to give an itemized investigation of whether to combine information from numerous sensors. We trust that our exertion will help the readership and this will spare time for future investigations by not rehashing similar analyses.

II. RELATED WORK

Human activity recognition wearable sensors is an exceptionally across the board examine subject. Telephone based accelerometers to perform movement acknowledgment, an errand which includes recognizing the physical action a client is performing. To actualize this framework creators gathered named accelerometer information from twenty-nine clients as they performed day by day exercises, for example, strolling, running, climbing stairs, sitting, and standing, and after that amassed this time arrangement information into precedents that condense the client movement more than 10-second interims. Creators at that point utilized the subsequent preparing information to instigate a prescient model for action acknowledgment. Prior work by Kwapisz J R et al [6]. Introduce a pushed forward estimation of delicate biometric data from inertial sensor. By tackling distinctive classification undertakings like age, weight and tallness based on the movement information of human strolling steps spoken to by increasing speeds and rakish speeds. Information were recorded by one sensor set at different areas on the human body, to be specific the chest, the lower back, the wrist and the lower leg. The outcomes demonstrate that these classification errands can be comprehended well by utilizing accelerometers and additionally whirligigs at any of the given order just as given areas.

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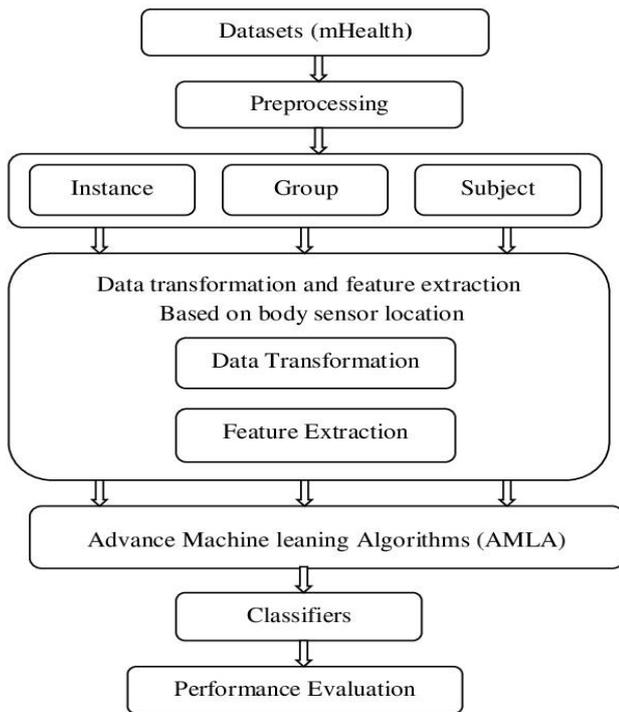
Yogesh K M, Computer Science, Mangalore University, Mangalore, Karnataka, India.

Doreswamy, Computer Science, Mangalore University, Mangalore, Karnataka, India.

The order rates were most astounding for sensors situated at the lower back and chest in every one of the investigations, yet at the same time practically high when the sensor is connected to the wrist or lower leg. The tests have clarified that there isn't one component for the most part in charge of any of the refinements important for a characterization. In any case, the component significance in every one of the grouping gave pointers about what blend of highlights delivers the best outcomes. The most significant endings were that precise speeds showed improvement over increasing velocities. Qaiser Riaz Akker et al [7], earlier work by Incel et al [8]. Studies movement acknowledgment examines utilizing PDAs. In any case, most research depicted in that still includes disconnected handling of the information gathered on the advanced mobile phone. Kunze et al [9]. Examined how increasing speed and spinner signals are influenced by sensor uprooting.

III. PROPOSED MODEL

Fig. 1. Proposed Human Activity Recognition (HAR) System



A. Data Set Description

Characterize information related to propose inquire about examination is MOBILE HEALTH (mHealth) informational collection, which is fundamentally produced by Banos, et.al [1]. what's more, facilitated to AI document of place for Machine Learning (ML) and intelligent systems (IS) at the college of California, Irvine(UCI), This mHealth information is utilized as auxiliary information for learning revelation identified with human movement acknowledgments and pulse exercises rely upon shifting human exercises [1], [10].

B. Data Selection

Primary information were obtained from three diverse portable wellbeing sensor hubs put at the chest position

containing accelerometer and electrocardiogram (ECG) sensors, and a sensor put at the left ankle (LA) and the right-lower-arm (RLA) positions contain an accelerometer, magnetometer and gyro meter. The acceleration(x, y, and z), magnetometer(x, y, and z) and gyroscope(x, y, and z) produce three-dimensional information. Furthermore, Electrocardiogram (ECG) sensors produce two dimensional information (L1, L2) individually Lead-I (L1) and Lead-II (L2). In this paper, the chest sensor accelerometer informational indexes are chosen for comprehension about human body movement regarding chest position.

Table1. Activity Set

Sl.No	Human Physical Activity(HPA)	Actual time in second	Time
1	Standing still	61.44	1 min
2	Sitting and relaxing	61.44	1 min
3	Lying down	61.44	1 min
4	Walking	61.44	1 min
5	Climbing stairs	61.44	1 min
6	Waist bends forward	20	20 sec
7	Front elevation of arms	20	20 sec
8	Knees bending	20	20 sec
9	Cycling	61.44	1 min
10	Jogging	61.44	1 min
11	Running	61.44	1 min
12	Jump front & back	20	20 sec

C. Data Preprocessing

The raw accelerometer sensor information regularly needs to drawing closer predisposed in order to dispose of filthy, uproarious what's more, excess information. As these sorts of information are free from uproarious, in this way, information changes are proposed for lessening the bigger size of the information to the diminished portrayal by creating highlights for a changing window estimate.

D. Data Transformation and Feature Generation

MHealth information contains 10 people/clients of varying gender, height, weight and different age and each user was done 12 exercises that are appeared table1. The mHealth information contains 12, 15,749 occurrences. All detecting modalities are recorded at an examining rate of 50 Hz, the sensor limit gadget was sufficient for getting Human Physical Activity (HPA). Time taken for producing one occasion was 0.02/ms time, which is relating to $t = (1/50)$ Hz = 0.02/ms. Each client played out all exercises and every action was performed for 1 min and the exercises midriff twist forward, front height of arms, knee bowing and hop front and back were performed 20/sec as it were. For example, time taken for every action can be determined utilizing the underneath recipe [1].

$$T = T_A \frac{E_t * I_t}{t}$$

T_A = Total time taken for each activity

E_t = Time take for each instance

I_t = total number of instance in an individual activity

T = Time in second

Ordinary investigation of classification methodology could be unequivocally reasonable to time succession increasing speed sensor information, however, it leads computational multifaceted nature and decreases proposition of a more tasteful. Consequently, information change is sent on the crude time arrangement window tests. To achieve this information is partitioned into changing windows sizes that are relating to 10, 20, 30, 40, 50, and 60-second, information part containing 512,1024,1536, 2048, 2560 and 3072, readings separately Table 1.

E. Feature Extraction

An occurrence of wt seconds ($W = fs \text{ wt samples}$) is utilized to compute the list of capabilities for a specific action. Here, fs are the recurrence testing of the speeding up information. For each element of the quickening sensor, twelve distinct highlights in the time-space are separated. Following is the detail of each time space includes. Let x is the sign of window measure wt seconds having W windows tests or information focuses [11]. . Presents a total rundown of highlights extricated from various parts of increasing velocities and rakish speeds. For every single step, the list of capabilities comprises of includes altogether. Measurable highlights include: mean, middle, worldwide least, worldwide most extreme, first Quartile, third Quartile, standard deviation, mean an outright mistake, mean square blunder and root mean square the majority of the rest of the features are figured for all 3D increasing velocities.

Table 2

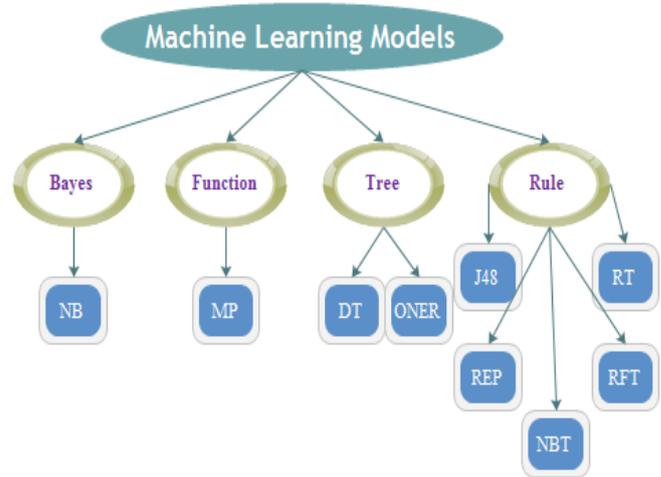
Description of the Extracted Features the Time and Frequency Domain is computed

Features Name	Sensor	Axis	Total
Mean	A	X,Y,Z	9
Median	A	X,Y,Z	9
Minimum	A	X,Y,Z	9
Maximum	A	X,Y,Z	9
First Quartile Range	A	X,Y,Z	9
Entropy	A	X,Y,Z	9
Standard Deviation	A	X,Y,Z	9
Mean Absolute Value	A	X,Y,Z	9
Harmonic Mean	A	X,Y,Z	9
Variance (VR)	A	X,Y,Z	9
Root Mean Square	A	X,Y,Z	9
Skewness	A	X,Y,Z	9
Kurtosis	A	X,Y,Z	9
Simple Squared Integral	A	X,Y,Z	9

MHealth information contains 10 people of shifting age, stature, weight and diverse sexual orientation and every client was completed 12 various sorts of movement that are appeared in table 2. The component was extricated diving window wt of 10/sec time term [6]. Shimmer2 wearable information in X, Y and Z measurements of the three significant body position and the significant highlights are extricated and got from every 512 occasions in each physical action this window to perceive the development as being one of twelve possible choices. The sampler recurrence was recorded the accelerometer information at the 50Hz limit. An association of one 1/sec is considered for sliding the window on the shimmer2 sensor information [12]. Time-space

highlights are proposed on the span of 10/sec and 512 occasions are gotten in every action from each put of accelerometer sensors, set on the Chest, Right Lower Arms (RLA) and Left Ankle(LA), separately. Table 3 demonstrates the scattering of examples of the distinctive day by day physical exercises in the component sets [13].

Fig2. Schematic representation of Advanced Data Mining Techniques



IV. FEATURE GENERATION

Classification is the way toward structure a model (or capacities), which depicts and recognizes information classes or ideas, for the reasons for having the option to utilize the model to anticipate the class of articles whose class name is obscure. The characterization models are built dependent on the investigation of 3/4th of preparing information whose class mark is known and tried on 1/4th of real cases as testing tests. The propelled Data Mining Techniques sent for grouping of mHealth informational collections are classified in table3 [14].

Table 3
Number of Features Vectors per User and Activities

Nor	Person										Total
	1	2	3	4	5	6	7	8	9	10	
1	6	6	6	6	6	6	6	6	6	6	60
2	6	6	6	6	6	6	6	6	6	6	60
3	6	6	6	6	6	6	6	6	6	6	60
4	6	6	6	6	6	6	6	6	6	6	60
5	6	6	6	6	6	6	6	6	6	6	60
6	2	2	2	2	2	2	2	2	2	2	60
7	2	2	2	2	2	2	2	2	2	2	60
8	2	2	2	2	2	2	2	2	2	2	60
9	6	6	6	6	6	6	6	6	6	6	60
10	6	6	6	6	6	6	6	6	6	6	60
11	6	6	6	6	6	6	6	6	6	6	60
12	2	2	2	2	2	2	2	2	2	2	60
All	56	56	56	56	56	56	56	56	56	56	560

Human action recognition frameworks depend on cutting edge information mining calculations to anticipate a person’s action amid a specific timescale.



Moreover, it has been stressed that distinctive classification techniques could be utilized in HAR frameworks, contingent upon the specific qualities of every situation (e.g., the arrangement of exercises, the kind of sensors, etc). Miguel A. Labrador Oscar D.et al [12]. Expand on the benefits of actualizing a totally portable HAR framework as far as dependability, adaptability, and vitality utilization, just to specify a couple. Yet, such an errand involves the assessment of a classification model on the Saxophone, which achieves an

extra test that is actualizing every single more tasteful under the Android stage. This could be very tedious given the hidden unpredictability in the usage of AI calculations, alongside the computational limitations present in cell phones. The focal point of this paper, in this manner, is to use the usage of various classification strategies given by WEKA to empower Classifiers assessment so as to assemble these under the Android structure [15].

Features	Description
Mean	The DC component (average value) of the signal over the window
Standard Deviation	Measure of the spreadness of the signal over the window
Inter Quartile Range	The median of the upper half of the data set.
Mean Absolute Value	The summation inters quartile range which describes the variability of a window.
Harmonic Mean	The harmonic mean is the reciprocal of the arithmetic mean of the reciprocals.
Variance	The square of standard deviation
Root Mean Square	The quadratic mean value of the signal over the window
Skewness	The degree of asymmetry of the sensor signal distribution
kurtosis	The degree of peakedness of the sensor signal distribution
Simple Squared Integral	The basic squared fundamental computes the efficiencies of signs
Median	The median signal value over the window
Minimum	The minimum value over the window
Maximum	The maximum values over the window
First Quartile Range	Measure of the statistical dispersion, 25th percentiles of the signal over the window
Third Quartile Range	Measure of the statistical dispersion, 75th percentiles of the signal over the window

A. Evaluation

This stage includes thinking about different models and picking the best one dependent on their prescient presentation (i.e., clarifying the changeability being referred to and creating stable outcomes crosswise over examples). This may seem like a basic task, yet in reality, it some of the time includes an exceptionally intricate procedure. There are assortments of systems created to accomplish that objective numerous of which depend on purported "aggressive assessment of models," that is, applying various models to similar information set and after that contrasting their exhibition with pick the best [16].

- 1) **True Positives (TP):** The number of positive instances that are classified as positive.
- 2) **True Negatives (TN):** The number of negative instances that are classified as negative.
- 3) **False Positives (FP):** The number of negative instances that are classified as positive.
- 4) **False Negatives (FN):** The number of positive instances that are classified as negative.

Accuracy: It is the most standard metric to summarize the overall classification performance for all classes and it is dened as follows:

$$Accuracy = \frac{(TP + TN)}{(TP + TN + FP + FN)}$$

Precision: It is often referred to as positive predictive value and is the ratio of correctly classified positive instances to the total number of instances classified as positive

$$Precision = \frac{TP}{(TP + FP)}$$

Recall: It is also called true positive rate, is the ratio of correctly classified positive instances to the total number of positive instances:

$$Recall = \frac{TP}{(TP + FN)}$$

F-Measures: It combination of precision and recall in a single value:

$$F - Measures = 2 * \frac{(Precision + Recall)}{(Precision + Recall)}$$

Finally, the False Positive Rate (FPR) and the False Negative Rate (FNR) are defined as follows:

$$FPR = \frac{FP}{(TN + FP)} \quad \text{and} \quad FNR = \frac{FN}{(TP + FN)}$$

V. EXPERIMENTS

Human Physical Activity Recognition (HPAR) the machine When the model is built and assessed to guarantee the execution of classifiers testing tests, characterization precision alone is regularly insufficient data to settle on this choice.



Further the diverse propelled classifiers strategies such as Nave bayes, multilayer perceptron, choice Table, OneR, J48, Random Forest, Random Tree, and Reduced Error Pruning (REP) Tree and gullible Bayes Tree were tested and assessed on three classifications of information such case, gathering and subject based information and separately called as Instance based order (IBD), Group based arrangement (GBC) and Subject based order (SBC).The trial consequences of everyone is portrayed in the accompanying segment [7].

A. Group and Sub-Group based classification

Be that as it may, in this paper bunch based grouping we expect that the application space enables us to use from the earlier information that the entire gathering of marked examples have a place to the class, and furthermore yet known, class [7]. Along these lines, we just need consider the 12 conceivable class marks for the arrangement. Group Based Classification (GBC) there four diverse characterization errands. Preparing

Algorithm 1 Classifier for Gender based data

```

INPUT: Gender based data values
INPUT: Gender based classification accuracy
Classification(gender, classifiers)
{
if(gender == NULL)
    Classifiers(exit)
else
    classification(gender → classifiers)
}
    
```

Algorithm 1 Classifier for Gender based data

```

INPUT: Gender based data values
INPUT: Gender based classification accuracy
Classification(gender, classifiers)
{
if(gender == NULL)
    Classifiers(exit)
else
    classification(gender → classifiers)
}
    
```

Algorithm 3 Classifier for height based data

```

INPUT: Height based data values
INPUT: Height based classification accuracy
Classification(height, classifiers)
{
if(height == NULL)
    Classifiers(exit)
else
    classification(height → classifiers)
}
    
```

Algorithm 4 Classifier for Weight based data

```

INPUT: Weight based data values
INPUT: Weight based classification accuracy
Classification(height, classifiers)
{
if(weight == NULL)
    Classifiers(exit)
else
    classification(weight → classifiers)
}
    
```

and approval information were likewise arranged for classification inside member subgroups for sexual orientation, weight stature and age Classification. In table the qualities of the populace inside various classification undertakings are exhibited as appeared table 4. The above table shows four diverse grouping errands. Sex arrangement, in this characterization seven male and three female, age order have five more prominent than or equivalent to 25 age and under 25

age, stature arrangement have three more noteworthy than or equivalent to 170/cm stature and under 170/cm tallness. Also weight arrangement has five more prominent than or equivalent to 25/kg weight/kg and under 25/kg. In any case, the focal point of this paper is on consecutive compound choices and bunch based order specifically table5. identified by movement chronicles of any of the utilized sensors. The aftereffects of the ternary classification for accelerometer sensor on chest position sensor are given in table 7.

Table 5: Number of Features Vectors per User and Activities

Group	DT	J48	MP	NB	NBT	OneR	RFT	RT	REP
Male	70.79	83.33	65.26	65.02	79.21	53.97	99.96	99.96	79.75
Female	71.87	84.39	68.04	66.12	79.37	56.72	99.96	99.96	79.9
A > = 26	71.42	84.38	67.04	65.51	8016	55.06	99.95	99.96	80.74
A < 26	70.66	82.55	64.68	65.11	77.89	54.4	99.97	99.97	78.38
H > = 172	70.52	82.93	64.7	65.09	78.63	54.06	99.97	99.97	79.33
H < 172	72.01	84.71	68.19	65.73	80.2	55.9	99.95	99.95	80.49
W > =70	71.37	83.81	66.45	65.53	79.95	54.3	99.96	99.96	80.66
W < 70	70.86	83.48	65.73	65.17	78.56	55.28	99.96	99.97	78.93

1. Gender Based Classification (GBC):

Our objective was to demonstrate that classification errands with respect to the sex order of the preliminary subject can be performed adequately well by utilizing the proposed sensors connected to chest position of human. The sex can be identified by movement chronicles of any of the utilized sensors the outcomes introduced in table 6.

2. Age Based Classification (ABC):

Here, the Classification assessed the task to two classes as indicated by two age gatherings (age > = 26, age < 26) of members.



3. Height Based Classification (HBC):

Another objective was body height classification from just increasing velocities sensor. The age gathering of people can be identified by movement chronicles of shimmer2 sensor gadget. The consequences of the ternary classification for accelerometer sensor on chest position sensor are given in table 8. Here, the Classification assessed the task to two classes as indicated by two age gatherings (tallness > = 172, stature > 172) of members.

4. Weight Based Classification (WBC):

Another objective was body weight classification from just increasing speeds sensor from chest position. The weight gathering of people can be identified by movement accounts of shimmer2 sensors. The consequences of the ternary Classification for accelerometer sensor on chest position sensor are given in table 8. Here, the Classification evaluated the task to two classes as per two weight gatherings (weight > = 70, weight > 70) of members.

A. Instance Based Classification

Examinations of various classifiers are done on every window containing number of occasions: W1-512, W2-1024, W3-1536, W4-2048, W5-2560, and W6-3072 in every action regarding all matters. The normal grouping exactness of each model on every one of the 10 people under every window measure is figured. A similar methodology is registered utilizing calculation given underneath. The normal perforce of the classifiers on changing breeze measure is shifting. Be that as it may, the RFT and RT classifiers are going 100% classification exactness. This table 4 determines the prescient precision related with every one of the order strategies for each case in every one of the windows [13].

Table 6: Group and sub-group based classification

Instance	DT	J48	MP	NB	NBT	One R	RFT	RT	REP
W1:512	72.1	83.4	68.2	66.5	77	57.3	100	99	77.2
W1:1024	72	82.4	64.7	66.8	76.8	56.7	100	99	77.2
W1:1536	74.5	83.2	67.6	70.9	79.3	59.4	100	99	79.7
W1:2048	74	82.7	71.6	70.5	78.2	59.1	100	99	79.7
W1:2560	73.6	82.4	68.6	70.1	78.1	58.8	100	99	78.8
W1:3072	73.2	82	69.8	69.7	77.1	58.5	100	99	78.8

Algorithm 5 Classifier for Instance based data

```

INPUT: Instance based data values
INPUT: Instance based classification accuracy
Classification(window, classifiers)
{
  if(windowsize == NULL)
    Classifiers(exit)
  else
    classification(windowsize → classifiers);
}
    
```

Algorithm 6 Classifier for Subject based data

```

INPUT: Subject data values
INPUT: Subject classification accuracy
Classification(subject, classifiers)
{
  if(subject == NULL)
    Classifiers(exit)
  else
    classification(subject → classifiers);
}
    
```

Fig3. Group and sub-group based classification

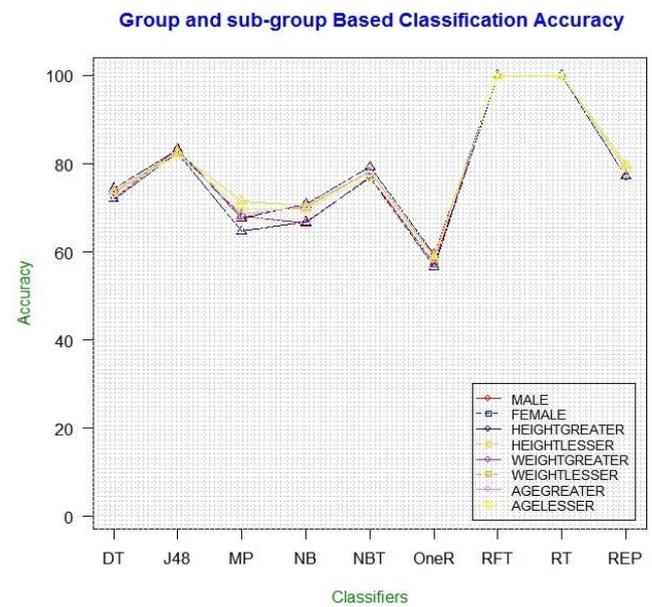
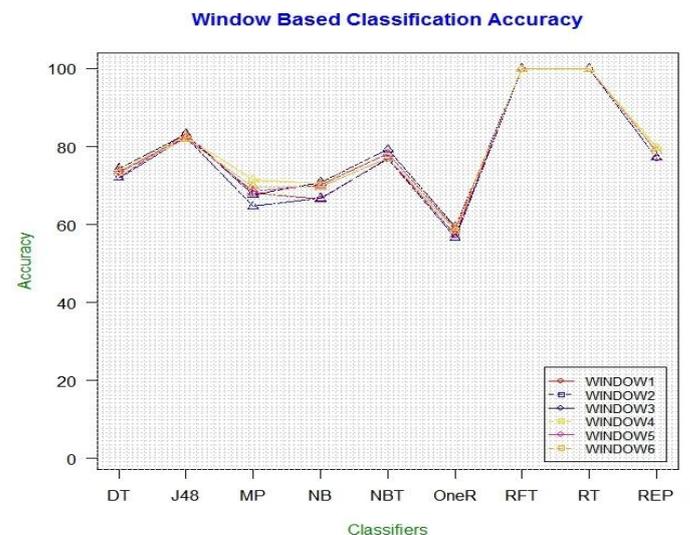


Fig: 4 Window based classification



B. Subject Based Classification

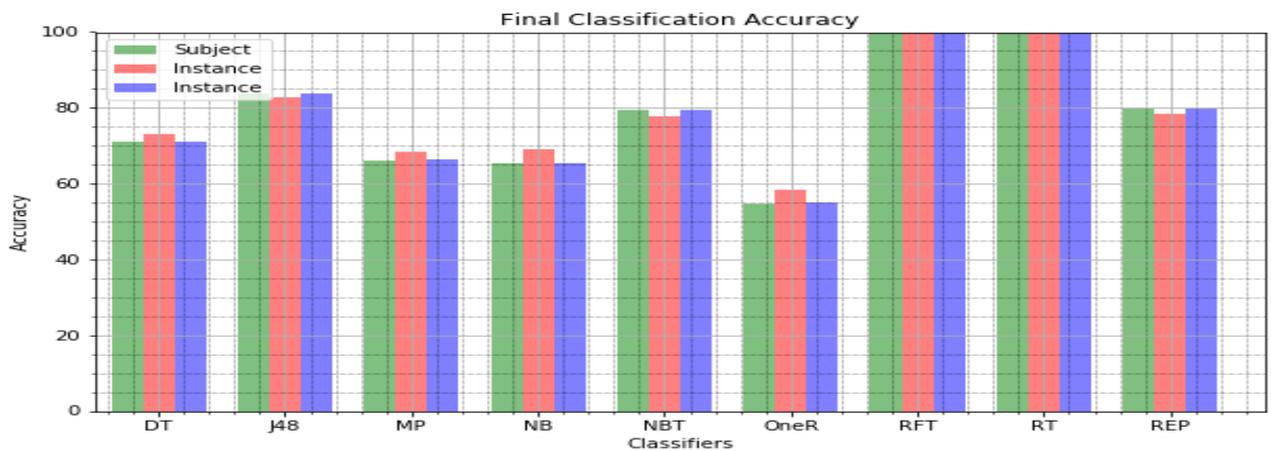
This step was performed by extracting the raw accelerometer data from subject or person wise during the data collection process. The each person took all twelve activities. The person was taken 1/min time for each activity, and each activity data can be divide 10/s, 20/s, 30/s, 40/s, 50/s, 60/s data, and extracted features for every 10 to 60/s data and apply advance classifiers methods. At the human chest position 12, 15,749 instances were produced, with 3072 instances for each activity, except Waist bends forward, Front elevation of arms, Knees bending, and jump front and back, where the trainings for both instance were conducted using the 10fold cross validation method. Tastings Were then performed using the untrained datasets to test the accuracy of the trained classifiers, here we showed final average of all nine advanced classifiers methods of all ten person. In this methods Random forest tree (RFT) and Random tree (RT) gives more than 99% of accuracy and also lying down and

standing still activity getting more than 95% of accuracy because there is no lot of difference between lying down, sitting and relaxing and standing still so both activity got more than 99% accuracy in all selected advanced classifiers. Here we have showed two different graphical representations figure 5 shows Column representation and figure 6 shows 2-D line graphical representation [13].

Table 7: Subject Based Classification

Id	DT	J48	MP	NB	NBT	OneR	RFT	REP
P1	72.4	82.5	67.6	67.1	77.7	56.8	99.7	78.3
P2	69.6	81.3	66.6	65.4	76.5	54.6	99.9	78.8
P3	70.5	82.9	62.0	64.2	78.3	52.2	99.7	78.2
P4	68.1	81.2	62.4	63.5	76.3	54.0	99.7	76.7
P5	68.2	83.7	64.5	61.9	76.8	55.6	99.6	78.2
P6	72.4	85.6	68.6	64.5	82.6	53.4	99.2	82.2
P7	71.5	83.3	66.5	65.7	79.1	54.4	99.7	80.3
P8	74.9	86.8	71.9	69.2	83.6	57.6	99.6	83.1
P9	73.4	87.3	68.6	69.02	85.1	56.1	99.8	84.0
P10	69.8	81.3	61.7	62.8	76.2	52.8	99.4	77.8

Fig: 5 Final classification accuracy



The figures demonstrate that in most cases we can achieve high levels of accuracy. For the three most common activities, lying, standing still, and sitting and relaxing. We generally achieve accuracies above 90%. Sitting and relaxing appears easier to identify than standing still, which seems to make sense, since jogging involves more extreme changes in acceleration. It appears much more difficult to identify the two stair climbing activities, but as we shall see shortly, that is because those two similar activities are often confused with one another. Note that although there are very few examples of sitting and standing, we can still identify these activities quite well, because, as noted earlier, the two activities cause the device to change orientation and this is easily detected from the accelerometer data. Our results indicate that none of the three learning algorithms consistently performs best, but the multilayer perceptron does perform best overall. More detailed results are presented in above Tables, which show the activity accuracy with each of the learning algorithms [17].

the last ordered exactness related with three characterizations

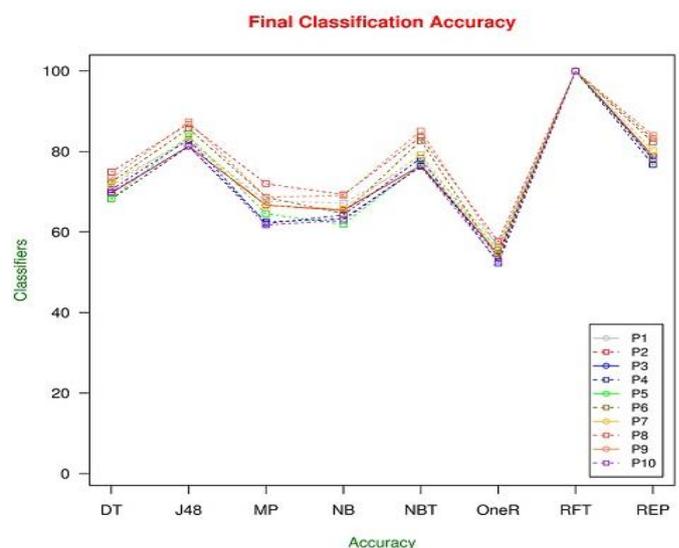


Fig: 6. Subject based classification

VI. CLASSIFICATION ACCURACY AND RESULT

The outline results for human action acknowledgment experiments are introduced in Table 11. This table indicates

The J48 Decision tree classifier pursues the accompanying straightforward calculation. So as to characterize another thing, it first needs to make a choice tree dependent on the trait estimations of the accessible preparing information. While evaluating the general execution of the classifier (i.e., the last line of Table 11), in this general outline Random woodland tree(RFT) and irregular tree(RT) classifiers gives more than 99% precision in every one of the three sorts of order [18]. For grouping issues, given a lot of straightforward trees and a lot of arbitrary indicator factors, the Random Forest strategy characterizes an edge work that measures the degree to which the normal number of votes in favor of the right class surpasses the normal vote in favor of some other class present in the reliant variable. This measure gives us not just with an advantageous method for making forecasts, however likewise with a method for partner a certainty measure with those forecasts. Beneath tables contain by and large exactness from accelerometer chest sensor information [19].

VII. CONCLUSION

The work described in this paper is part of a larger effort to mine sensor data from shimmer wireless sensor devices. We plan to continue mHealthDroid-based project, applying the accelerometer data to other tasks besides activity recognition and collecting and mining other sensor data, especially Accelerometer, magnetometer, and gyro meter data. We believe that shimmer2 (BUR10) sensor data provides tremendous opportunities for data mining and we intend to leverage mHealthDroid-based data collection/data mining platform to the fullest extent possible.

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AUTHORS PROFILE



Yogesh K M is currently a Research Scholar department of Computer Science. He received B.Sc. from University of Mysore in 2012 and M.Sc. degree in Computer Science from Mangalore University in 2014 respectively. After completion of his Post Graduation Degree. He joined as Research in Computer Science at Mangalore University in the year 2015 still him pursuing PhD on Human physical activity recognition using mHealth datasets. He has published more than 6 contribute research papers at National/International Journals and Conferences.



Dr. Doreswamy is currently a Professor of Computer Science in the Department of Computer Science. He received B.Sc. and M.Sc. degree in Computer Science from University of Mysore in 1993 and 1995 respectively. After completion of his Post Graduation Degree. He joined as Associate Professor in Computer Science at Mangalore University in the year 2003. He was the Chairman of the Department of Post-Graduate Studies and Research in Computer Science during 2003-2005 and 2008-2012 and served at various capacities in Mangalore University, as a Chairman and member of DOC, DOS and UG/PG BOS and BOE in Computer Science. Started Ph.D. programme in Computer Science and Technology in Mangalore University with effect from the academic year 2003-04 onwards. His areas of research interests include Data Mining and Knowledge Discovery, Artificial Intelligence, Machine learning and Scalable Advanced Data Mining Algorithms. He has published more than 60 contributed peer-reviewed research papers at National/International Journals and Conferences. He has chaired many National and International Conferences in India. He has completed one minor research project that was sanctioned by University Grants Commission (UGC). He completed Major Research Project entitled "Scientific Knowledge Discovery Systems (SKDS) for advanced Engineering Materials Design Applications" from the funding Agency University Grant Commission, New Delhi, INDIA.

