

Content Based Image Retrieval based on Domain Knowledge Acquisition

Feroza D Mirajkar, Ruksar Fatima, Shaik A Qadeer

Abstract-Enormous growth has been noted in digital technology over the years and this has led to massive growth in data mainly images and videos, hence with the volume of the data has also increased. Moreover, searching and retrieval of the accurate image from the huge dataset has become eminent as well as one of the challenging issue. In order to solve mainly two technique were used i.e. based on text and content. Moreover, content based is technique that is more efficient. In past several technique were used but they lack from the efficiency. Hence, in this paper we have proposed a methodology based named as DKA (Domain Knowledge Acquisition), DKA focuses on two main goals first is learning the similarities across the varied domain and other is learning on complex objects. The main advantage of DKA is the whether the object is whether from same domain or the other the retrieval process is very smooth. Moreover In order to evaluate the performance we have retrieved the top 5 response of query image and later it is compared with the several state-of-art technique and the existing method based on the precision parameter.

Keyword: CBIR, DKA, Image retrieval

I. INTRODUCTION

Due to extensive connectivity and easily availability of digital imaging technologies and internet, multimedia files have increased exponentially and data sharing, searching and posting has become very flexible. Hence, these multimedia data is used for real time video as well as audio conferencing. Moreover, this has led the creation of massive image from the various fields, at the same time the need for the image retrieval tool has become one of the fundamental requirement.

There are two types of image retrieval is used namely text based retrieval and content based image retrieval [1]. Moreover, in the early day's text based approach was used, however this method leads us to the increase in size and it results in being subjective [2]. Hence in the early 90s wide research has resulted in development of CBIR i.e. Content based Image retrieval [3], here the image retrieval were Based on the AM (Automated Matching) through the similarity evaluation. CBIR (Content Based Image Retrieval) is the bottleneck when it comes to accessing the multimedia databases; the main intention behind the CBIR is to retrieve the similar image [4, 5]. There exist two major problem which is quiet difficult to solve the issue, first is the segmentation of images i.e. when the image is parted into several meaningful parts based on the LL-(Low Level) feature such as spatial , shape ,texture and color.

Second issue is the marginal gap between the high-level image and low-level image in case of the bus, home, furniture and others. Hence, it is required to design an efficient method for large image datasets.

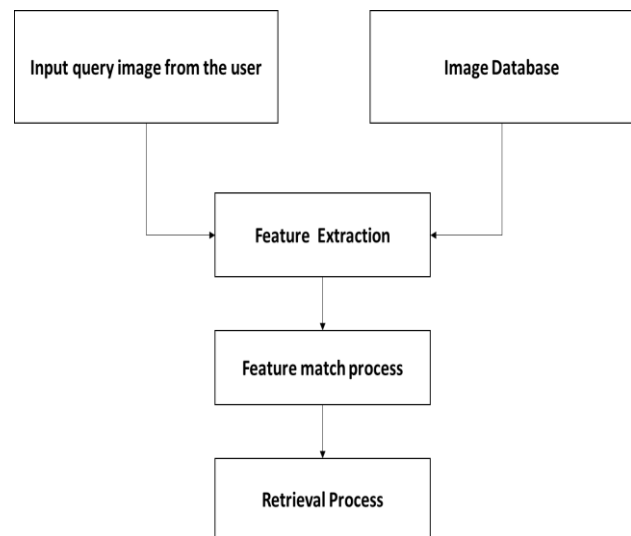


Figure 1 Typical CBIR structure

The above figure shows the typical architecture of CBIR model, where there are two primary stages that are involved namely Feature extraction and feature matching.[6] Moreover feature extraction involves in extracting the feature and in feature matching, features are compared to match. Moreover, the image feature of each image is stored in the available image dataset. If it is found that the distance between the images available in the database and FV (Feature Vector) of particular query is small then it is said that the query image matches from the image datasets. Later these matched images are ranked according to the similarity index. Moreover, in past several algorithm has been proposed and it focuses on the iteration-based scheme however, they have failed miserably to answer few scenarios such as how many rounds of iterations are required or about the manifold structure. Hence, to unfold that we have proposed a model, which is known as DKA (Domain Knowledge Acquisition) which is regularization, based model. Moreover, with the help of regularization DKA process obtains the similarity index. Moreover, to make the computation more feasible we have used iteration. Moreover, later we have used the context where the size of the domain no longer matters.

Revised Manuscript Received on November 08, 2019.

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II. LITERATURE SURVEY

[7] presented a corresponding high-level query language, PICQUERY, [8] described an approach where local statistics (texture energy measures) are estimated at the output of an equivalent filter bank by means of a nonlinear transformation (absolute value) followed by an iterative Gaussian smoothing algorithm. An integrating system of faces and fingerprints was developed by developed by Anil Jain and Lin Hong [9] which overcomes the limitations of both face and fingerprint recognition systems. [10] Attempted to capture high-level concepts from low-level image features under the constraint that the test image does belong to one of the classes.[11] presented their work in the area of image organization and retrieval in Image Databases using global color features and spatial color distribution of images. They suggested extending the use of image histograms to characterize the global and local color properties of an image, moreover here the artificial neural network were used.

[12] Proposed a method for concept-based medical image retrieval that is a superset of existing semantic-based image retrieval methods. They conceive of a concept as an incremental and interactive formalization of the user's conception of an object in an image. [13] Propose a hybrid image descriptor that is rotation and scale-invariant to make image retrieval efficient. The quantization based on the RGB color space is used to extract the color features, whereas the patterns generated from locally structuring element are assembled to extract the texture features. The color and texture features are integrated together to build the hybrid feature descriptor known as rotation and scale-invariant hybrid descriptor (RSHD). The RSHD descriptor is robust in case of rotation and scaling. [14] Proposes an innovative image descriptor to extract the color and texture features of the image. This descriptor is known as global correlation descriptor (GCD). The color feature is characterized using global correlation vector (GCV), whereas the texture feature is characterized using directional global correlation vector (DGCV). Experimental results show that the performance of the GCD outperforms as compared with the recent CBIR techniques. [15] Propose a framework that uses affine image moment invariants as a feature descriptor for image retrieval. The moments are fed into the BoW model to produce feature vectors. The novelty of this work is that the affine moment invariants are used as local features and are extracted using SURF feature descriptor. Similarly in [16] meta-heuristic approach were used such as iterative local search and genetic algorithm and the methodology was evaluated with investigation of number of images.

Zeng et al. [17] propose an image representation technique in which Gaussian mixture models (GMMs) are employed to characterize an image as a spectrogram (i.e. general histogram of colors). The expectation-maximization (EM) technique is employed to determine quantized color space from the training data set. Gaussian components, that is, the number of color bins, are characterized according to the

Bayesian information criterion (BIC). Spatiogram is modified and incorporated into a quantized Gaussian mixture color model. Finally, a comparative analysis of two spectrograms is done and a new measurement adopting technique is suggested known as Jensen–Shannon divergence (JSD) to make image retrieval more efficient. Zhao et al. [18] propose a descriptor based on the local and multi-trend structure for feature representation called multi-trend structure descriptor (MTSD). This descriptor integrates features like color, edge orientation, and shape and intensity information for robust image representation. It also represents the local spatial structure information to extract image features. The experimental results demonstrated that MTSD produced discriminative results for effective CBIR. a hybrid method was presented by integrating local and global features The local features are extracted by applying SIFT descriptor, while the global features are extracted by applying upper-lower of LBP (UL-LBP) descriptor based on LBP. Then, features are quantized into the BoW model to improve image retrieval performance. Although LBP is not suitable for color images, it is not suitable for capturing similarity between color images. LBP only captures textual information from the images. Liu et al. [19] overcame this problem by proposing a descriptor with an additional color feature called color information feature (CIF) incorporated with LBP for image retrieval. Experimental results show that combining these two features yields good performance in a retrieval system. [20] Propose a CBIR method that combines LBP and wavelet transform. In this method, the texture features of the image are extracted by computing LBP codes using the coefficients of discrete wavelet transform (DWT). Then, shape features are extracted from texture features by computing Legendre moments using these LBP codes to construct a feature vector. The experimental results show improved performance on small image databases as compared with the large image databases. Bala and Kaur [21] propose a novel descriptor for CBIR called local texton XOR patterns (LTxXORP). Then, the LTxXORP feature vector is integrated with the feature vector of the HSV colour space-based colour histogram to improve CBIR performance. A novel method using a low-level feature called composite moment (CoMo) for image retrieval is proposed by Vassou et al. [22]. This method combines moment invariants and colour unit of the colour and edge directivity descriptor (CEDD). This method improves CBIR performance by overcoming rotation, translation and scaling issues.

III. PROPOSED METHODOLOGY

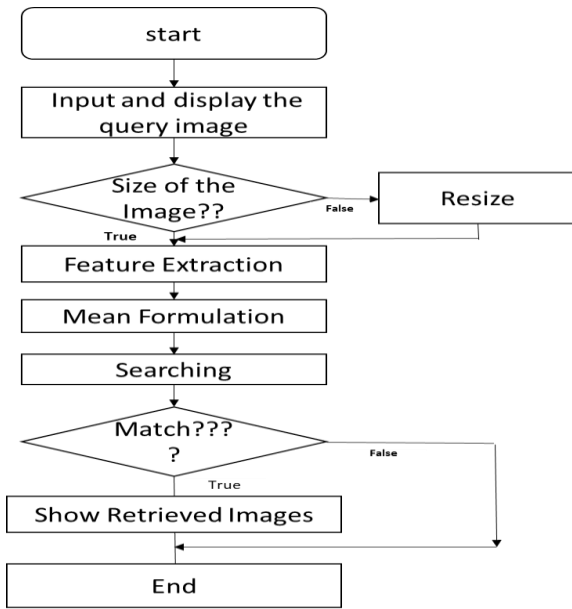


Figure 2 Proposed flow-work.

The above diagram i.e. fig 2 shows the flow of our process, at first user inputs the query in the form of image, this image is displayed. The displayed image is checked for the size, if the size is compatible then it goes to the FE (Feature Extraction) phase, in here the initial feature of the image is used as CFV (Compact feature Vector). Once the feature extraction is done mean is formulated, this in terms helps in searching the image. If the image is matched then show the desired images else displayed as error

Shape Feature

Let there be any two datasets of 2D shape $D = D_z, z = 1, Y \subset M^2$ and $A = a_i, i = 1, \dots, B \subset M^2$, here the main intention is to choose the best spatial deformation among others i.e. $s^*: M^2 \rightarrow M^2$ along with that the best correspondence is also chosen between the two given two dataset.

$$(C, df) = \sum_{k=1}^B \sum_{z=1}^Y c_{z,k} \|A_k - s(d_z)\|^2 + \lambda \|DS\|^2 \quad (1)$$

$$+ Temp \sum_{k=1}^B \sum_{z=1}^Y c_{z,k} \log c_{z,k}$$

$$- \zeta \sum_{k=1}^B \sum_{z=1}^Y c_{z,k}$$

Here $C = (c_{z,k})_Y$ is Responsibility Accountability Matrix, this matrix describes the occurrence of correspondence between the given datasets, this in terms satisfies the following two scenarios i.e.

$$\sum_{k=1}^{B+1} c_{z,k} = 1 \quad (2)$$

And

$$\sum_{z=1}^{Y+1} c_{z,k} = 1 \quad (3)$$

For all $c_{z,k}$ which belongs to the boundary of $[0,1]$. Later, in order to handle the various outliers extra rows and columns

are added. In equation 1, D be the laplacian operator and s be the SD (spatial deformation). Similarly, in order to assure the deformation smoothness the regularity term is used and it is denoted by using the $\|DS\|^2$. Temperature is denoted by degree of correspondence is controlled by the parameter temperature and denoted by $Temp$. Moreover for balancing the accuracy along with the smoothness is denoted by the parameter λ, ζ is used for restricting the outliers.

$$\|DS\|^2 = \iint \left[\left(\frac{\partial^2 s}{\partial x^2} \right) + 2 \left(\frac{\partial^2 s}{\partial x \partial y} \right) + \left(\frac{\partial^2 s}{\partial y^2} \right) \right] dx dy \quad (4)$$

Hence, our algorithm can be written through updating the correspondence, which is done by calculating $c_{z,k}$

$$c_{z,k} = \begin{cases} \frac{1}{Temp} \exp \left(- \frac{(A_i - s(d_z))^{Temp} (A_i - s(d_z))}{2Temp} \right) & \forall z \neq Y() + 1 \\ \frac{1}{Temp_0} \exp \left(- \frac{(A_k - d_{z+1})^{Temp} (A_k - d_{y+1})}{2Temp_0} \right) & a = K + 1; \\ \frac{1}{Temp_0} \exp \left(- \frac{(A_{B+1} - s(d_z))^{Temp} (A_{B+1} - s(d_z))}{2Temp} \right) & i = N + 1; \end{cases} \quad (5)$$

Here, v_{K+1} and χ_{N+1} are said to be the cluster center of the given outliers, then the norms of M through rows and column is given by below equation. Once the rows and column are update we tend to update the transformation, the reduction in energy is given by the below equation.

$$c_{z,k} = \frac{c_{z,k}}{\sum_{l=1}^{Y+1} c_{l,k}}, \quad k = 1, 2, \dots, B, \quad (6)$$

$$c_{z,k} = \frac{c_{z,k}}{\sum_{o=1}^{B+1} m_{a,j}}, \quad k = 1, 2, \dots, Y,$$

$$E_{TPS}(f) = \sum_{k=1}^B \sum_{z=1}^Y c_{z,k} \left\| \frac{A_k}{-S(d_z)} \right\|^2 + \lambda \|DS\|^2, \quad (7)$$

$$S(d_z, e, F) = \phi(d_z) \times \omega + d_z \times e \quad (8)$$

In the above Energy equation, there exist two matrices, which is decomposed by deformation S . In here, d is said to be the affine matrix and ω is non-affine matrix, this clearly indicates the updation of S deformation by updating the S and s . Deformation is decomposed into two parts i.e. s_1 and s_2 , the relation between A and g can be represented by $s = s_1 \oplus s_2$. Here, s_1 and s_2 are the nonlinear and linear transformation respectively, between the given data sets. Similarly the mean of these two transformation is given as $s_1(d_z) = s_1 d_z$ and $s_2(s_1(s_2(d_z))) = (s_2(s_1(d_z)))$

$$G(C, s_1, s_2) = \sum_{k=1}^B \sum_{z=1}^Y c_{z,k} \|A_k - s_1(d_z) - s_2(d_z)\|^2 + \lambda \|DS_2\|^2 \quad (9)$$

$$+ Temp \sum_{i=1}^N \sum_{a=1}^K c_{z,k} \log c_{z,k}$$

$$- \zeta \sum_{i=1}^N \sum_{a=1}^K c_{z,k}$$

From the above equation, it is clear that the local nonlinear deformation g and affine transformation A can be easily decoupled and when it is reduced, the reduction can be formed in tow sub-problems, which can be represented in the two sub-problems.

$$s_1^{y+1} = \arg \min_{s_1} G(C^y, s_1, s_2^y) \quad (10)$$

$$= \sum_{k=1}^B \sum_{z=1}^Y c_{z,k}^z \|A_k - s_1^y(s_1(d_z)) - s_1(d_z)\|^2$$

$$(C^{y+1}, s_2^{y+1}) = \arg \min_{C, s_2} G(C^y, s_1^{y+1}, s_2)$$

$$= \sum_{k=1}^B \sum_{z=1}^Y c_{z,k} \|\widetilde{A}_k^{y+1} - s_2(s_1^{y+1}(s_1(d_z)))\|^2 \quad (11)$$

$$+ \lambda \|Ds_2\|^2$$

$$+ Temp \sum_{k=1}^B \sum_{z=1}^Y c_{z,k} \log c_{z,k}$$

$$- \varsigma \sum_{k=1}^B \sum_{z=1}^Y c_{z,k}$$

SIFT

SIFT is one of the feature detection algorithm for detecting as well as describing the local features in the given images. In a given feature point, the descriptor of SIFT formulates and calculates the GV (Gradient Vector) and later it creates the normalized histogram of the GD (Gradient Directions). This is achieved by using the partition process, i.e. SIFT Descriptor is divided into the particular resolutions of the given pixels. In case of each pixel, gradient vector of that particular pixel is added to the gradient directions. This is achieved through the process of quantization. Furthermore, the gradient direction is weighed using the Gaussian scale, later these weighted values are shared to the neighboring bins this helps in minimizing the BE (Boundary effects) between the orientation and positions.

DKA (Domain Knowledge Acquisition) Process

Domain knowledge acquisition can be used for retrieving the images; the main aim of algorithm is to get the novel *sim*(similarity matching). Similarity matching is the term, which is used, for how much both the objects are similar, comparison is done and the image retrieved are ranked based. Let us consider any weighted graph $WG = (G, H)$ that models the data manifold .here graph vertices represents the data points $G = \{g_1, g_2, \dots, g_M\}$ and $H \in A^{M \times M}$ is the matrix of adjacent graph. H_{tu} is the *sim* between the h_l and h_m defined as given in the below equations. Moreover, our

intention is to identify the novel similarity, which is denoted by *NSim*. Initially model learns the similarity on the direct product graph. In DPG (Direct Product Graph), *DPG* each edge describes the four vertices whereas each of the vertex shows the relations between the given two vertices. In this research work the direct product graph is used and it is denoted by $(GXH).DPG = (K, L)$ Can be defined as $K = GXG, L = H \otimes H$. Moreover the main aim is to learn the novel similarity measure i.e. $sim = \{sim\}_{1 \leq l, m \leq M}$.

Problem Definition

The problem definition of the particular research work is presented through the below equation, here the intention is to present the novel similarity index measurement.

$$\min_{NSim} 0.5 \sum_{a,b,c,d=1}^M H_{bc} H_{cd} \left(\frac{NSim_{ca}}{(DM_{aa} DM_{cc})^{\frac{1}{2}}} - \frac{NSim_{db}}{(DM_{bb} DM_{dd})^{\frac{1}{2}}} \right)^2 \quad (12)$$

$$+ \mu \sum_{ca=1}^B (NSim_{ca} - DV_{ca})^2$$

In order to achieve the novel similarity below optimization can be used and the below equation represents it .Here μ is regularized parameter, along with its elements $DM_{gg} = \sum_{u=1}^B H_{ab}$ diagonal matrix is represented by using DM . Whereas domain values are denoted by using the DV which belongs to $Z^{M \times M}$. Equation presents problem definition, moreover our methodology i.e. DKA process mainly contain two process, in first process influence of matching P on the given matching *sim* is described. Moreover, this phenomenon is called *h proc* . *Smooth proc* Is described as if the g_k matches to x_l then probability of them falling in same category should have the negligible difference and the similarities M_{tt} and M_{tt} remains similar. Moreover, the individual object. GRK (Graph based Ranking) model helps in data ranking with res Second term is known as the fitting term shown in equation 1 this gives the difference from the initial . Moreover achieving the finite solution for the equation is very difficult hence two distinctive operators are used namely *Vectorization(V)* and *inverse vectorization(IV)*. Two product of Cartesian coordinate model i.e. γ and δ where these two can be computed by the below equation.

$$\alpha = M(e-1) + j \quad (13)$$

$$\delta = M(g-1) + l \quad (14)$$

Moreover the *smooth proc* is written as

$$\begin{aligned}
 & \frac{1}{2} \sum_{\alpha, \delta=1}^{M^2} H_{\alpha\beta} \left(\frac{\overrightarrow{NSim}_\alpha}{\sqrt{DM_{\alpha\alpha}}} - \frac{\overrightarrow{NSim}_\delta}{\sqrt{DM_{\delta\delta}}} \right)^2 \\
 &= \sum_{\alpha, \delta=1}^{M^2} L_{\alpha\delta} \frac{\overrightarrow{NSim}_\alpha^2}{DM_{\alpha\alpha}} \\
 & - \sum_{\alpha, \delta=1}^{N^2} \overrightarrow{NSim}_\alpha \frac{L_{\alpha\beta}}{(DM_{\alpha\alpha} DM_{\delta\delta})^{1/2}} \overrightarrow{NSim}_\delta \\
 &= \sum_{\alpha=1}^{M^2} \overrightarrow{NSim}_\alpha^2 - \overrightarrow{NSim}^T DM^{-1/2} L DM^{-1/2} \vec{V} \\
 &= \overrightarrow{NSim}^T (UM - DM^{-1/2} DM^{1/2}) \vec{V} \\
 &= \overrightarrow{NSim}^T (UM - B) \overrightarrow{NSim},
 \end{aligned} \quad (15)$$

Where UM is the unit matrix.

$$L = G \otimes G \in Z^{M^2 \times M^2} \quad (16)$$

$$\begin{aligned}
 DMD &= DM \otimes DM \in Z^{M^2 \times M^2} \\
 B &= E \otimes E \in Z^{M^2 \times M^2}
 \end{aligned}$$

$$B = DMD^{-1/2} DMD^{-1/2} \quad (17)$$

Moreover, there are three sub-stages are applied when the transformation takes place, first is if W is symmetric then W can also be symmetric, second process is depicted through below equations

Moreover the objective functions are given through the below equation

$$of = \overrightarrow{NSim}^T (um - B) \overrightarrow{NSim} + \mu \|\overrightarrow{NSim} - \vec{F}\|^2 \quad (18)$$

Partial derivative of the above equation i.e. eq.5 is taken with respect to \overrightarrow{NSim} , which is shown in the below equation (eq6), $um - B$ is the normalized direct product graph

$$\frac{\partial of}{\partial \overrightarrow{NSim}} = 2(um - B) \overrightarrow{NSim} + 2\mu(\overrightarrow{NSim} - \vec{F}) \quad (19)$$

The above equation is considered as zero then we get below equation. Later we applying the vectorization to both side of equation we get the equation 18. \vec{V} is a function that has a real value and provides to the each vertex which describes the relationship. Henceforth DKA takes admittance matrix as the smooth operator that helps in securing the structure. Moreover, our intention is to utilize the direct product graph

$$\overrightarrow{NSim} = \frac{\mu}{\mu + 1} \left(um - \frac{1}{\mu + 1} B \right)^{-1} \vec{F}. \quad (20)$$

$$\begin{aligned}
 NSim^* &= (1 - \alpha) 1 \\
 & / vector(1) \\
 & / (T - \alpha E \otimes E) vector(B),
 \end{aligned} \quad (21)$$

$$= (1 - \alpha) 1 / vector(1 / (I - \alpha B) \vec{F})$$

$NSim^*$ is the feasible solution,

DKA Iteration based

Since the computation of DKA using the certain number is complex, hence we apply the iteration-based approach, in order to perform the iteration we initialize the $A^{(1)}$. In here the similarity values

Limit

$$\sum_{a=1}^{\infty} (\alpha E)^i = (um - \alpha B)^i \quad (22)$$

$$B^* = \sum_{i=1}^{\infty} (\alpha B)^i \quad (23)$$

$B^* \in Z^{M^2 \times M^2}$ Moreover our intention is to learn a novel similarity index $NSim^* \in Z^{M^2 \times M^2}$ hence it is required to collect the few portion and place it to the $NSim^*$ and this can be achieved through below equation.

$$NSim^* = vec^{-1}(B * \vec{F}) \quad (24)$$

Here Y depicts the indices of particular elements in B^*

IV. Measuring based interpretation

$$B_i = [E_{i1}, E_{i2}, \dots, E_{iN}] \in Z^{1 \times M}$$

$$\langle E_c, E_d \rangle = \sum_{a,b=1}^M NSim_{ab}^{(t)} B_{ca} B_{da} \quad (25)$$

Moreover E_c and E_d norms are omitted.

Variants

Learning on heterogeneous graph

Two data domains are considered namely WG_1 and WG_2 and given as $WG_1 = (G_1, H_1)$ and (G_2, H_1) where G_i is the data-points in the given particular domain, similarity is derived through $NSim \in Z^{M_1 \times M_2}$, it measures the matching of objects between two different domain. Let g_c and g_d be the two objects in the first domain and the g_a and g_b be the two objects in another domain. Moreover, the objective is given as:

$$\begin{aligned}
 \min \quad & 1/2 \sum_{a,b=1}^{M_2} \sum_{c,d=1}^{M_1} H_{ab}^2 H_{cd} \left(\frac{NSim_{ca}}{(DM_{ab}^2 DM_{cc}^1)^{1/2}} \right. \\
 & \left. - \frac{NSim_{db}}{(DM_{bb}^2 DM_{dd}^1)^{1/2}} \right) \\
 & + \mu \sum_{i=1}^{M_2} \sum_{k=1}^{M_1} (NSim_{ca} - F_{ca})^2
 \end{aligned} \quad (26)$$



Here μ is the RP (Regularization Parameter) and Y is the CM (Cross-Model) similarity, moreover by applying g the co-ordinate transformation the above equation can be written as

$$NSim^{(t+1)} = \alpha SNSim^{(t)} E^{(t)} + (1 - \alpha) F \quad (30)$$

Moreover the above scenario is suitable only for the inside domain retrieval, Moreover cross model domain is retrieved though the below process.

Learning on Direct product Graph

Let $WG = (G, H)$ be the hypergraph with Ed hyperactive edges and M vertices, the graph of the vertices are denoted with the M hyper edges and M vertices. Moreover the graph vertices denotes the given data points $G = \{g_1, g_2, g_3, \dots, g_M\}$. In here every Hyper edges ϵ in WG holds some weight and these weights are stored in the matrix $H \in Z^{M \times Ed}$ these graphs are denoted through the incidence matrix i.e. $IMAT_{\epsilon} \in Z^{N \times M}$ as

$$IMAT(a, \epsilon) = \begin{cases} 1, & \text{if } g_a \in \epsilon \\ 0 & \text{if } g_a \notin \epsilon \end{cases} \quad (27)$$

Vertex Degree is given in below figure

$$DMD_{ii} = \sum_{\epsilon=1}^{Ed} G_{\epsilon\epsilon} IMAT_{i\epsilon} \quad (28)$$

Moreover Edge degree is given as in the below equation and EDEG

$$EDEG_{\epsilon\epsilon} = \sum_{i=1}^M IMAT_{i\epsilon} \quad (29)$$

Let $DMDE \in Z^{M \times M}$ be the similarity matrix hence the objective is to optimize the process.

$$\min_{\epsilon \in \{1, \dots, Ed\}} \frac{1}{2} \sum_{a,b,c,d=1}^M \frac{H_{\epsilon\epsilon} IMAT_{a\epsilon} IMAT_{a\epsilon} IMAT_{b\epsilon} IMAT_{b\epsilon} IMAT_{c\epsilon} IMAT_{c\epsilon} IMAT_{d\epsilon} IMAT_{d\epsilon}}{EDEG_{\epsilon\epsilon} EDEG_{\epsilon\epsilon}} \quad (30)$$

Moreover, in order to solve the above equation three co-ordinate transform that are identical which are presented in the below three equation.

$$\begin{aligned} \alpha &= M(a - 1) + c \\ \beta &= M(j - 1) + l \\ \gamma &= Ed(\epsilon - 1) + \epsilon \end{aligned} \quad (31)$$

Moreover in the above equation the transformation utilization takes place by substituting though following

$$\begin{aligned} H_{\epsilon\epsilon} H_{\epsilon\epsilon} &= L_{\gamma\gamma} \\ IMAT_{a\epsilon} IMAT_{c\epsilon} &= IMAT_{\alpha\gamma} \\ IMAT_{b\epsilon} IMAT_{d\epsilon} &= IMAT_{\beta\gamma} \\ EDEG_{\epsilon\epsilon} EDEG_{\epsilon\epsilon} &= W_{\gamma\gamma} \\ B_{\gamma\gamma} &= \sum_{\beta=1}^{M^2} IMAT_{\beta\gamma} \end{aligned} \quad (32)$$

$$DMD_{\alpha\alpha} = \sum_{\gamma=1}^{Ed^2} L_{\gamma\gamma} IMAT_{\alpha\gamma}$$

Moreover the above equation helps in achieving the smooth procedure and given through the below equation

$$\overrightarrow{NSim} \left(um - DMD^{-\frac{1}{2}} (IMAT) L (EDEG)^T DMD^{-\frac{1}{2}} \right) \overrightarrow{NSim} \quad (33)$$

V. PERFORMANCE EVALUATION

DKA method are coded in MATLAB on the i7 processor packed with 2 GB Nvidia Graphics and 8 GB RAM through windows10 to evaluate the algorithm. The evaluation is done in two part first part depicts the Query and response of image retrieval another part is comparison based on the precision.

Datasets

In this research work we have used the Corel1k Datasets, CD1K is the integration of ten different natural scene these are: African, Bus, Beach, Food, Flowers, Dinosaurs, Elephants, Horses, Buildings and Mountains. These images have the same size of 384X256 and each image categories consists of 100 images, hence the CD1K contains the total number of images are 1000.

Comparative analysis

In order to evaluate the DKA process we have used the precision parameter, precision which is as positive predictive value is defined as relevant instances fraction in retrieved instance. moreover in other words we can say that precision is relevance measure. Precision is calculated by using the below formula.

$$\text{Precision} = \frac{\text{relevant image retrieved}}{\text{Total images retrieved}}$$

Below table 1 shows the comparative analysis of various existing methods, moreover the comparison is done on the 10 different natural scene and average value of precision is tabulated in the last row of table 1. Moreover, our methodology i.e. DKA is compared against the several state-of-art technique namely MTH [23], MSD [24], CDH [25], SED [26], GCD [27], MCMCM [28] and the existing methodology CPV-THF [29]. The average precision value of each methodology is calculated and tabulated in the last row. We observe that precision value of MTH is 68.25%, MSD is 72.167, CDH is 65.75%, SED is 61.58%, GCD is 72.5% and the existing system i.e. CPV-THF is 80.79% whereas proposed system has the precision value of 94.611%. This indicates that our method has marginal improvisation in terms of precision value.

Table 1: comparison of various methods with proposed methodology

Image_Category	Precision value (in %)							
	MTH [23]	MSD [24]	CDH [25]	SED [26]	GCD [27]	MCMCM [28]	CPV- THF[29]	P roposed Model
African	69.17	83.33	77.5	82.5	87.5	69.75	91.66	93.1
Beach	61.67	43.33	56.67	28.33	68.33	54.25	54.58	93.1
Building	45.83	63.33	47.5	47.5	61.67	63.95	78.75	98.08
Bus	68.33	76.67	71.67	73.33	80	89.65	86.25	91.67
Dinosaur	100	100	100	90	100	100	98.7	98.08
Elephant	70.83	65	62.5	55	67.5	48.8	65.83	96.3
Flower	75	86.67	60.83	72.5	88.33	92.3	95.41	100
Horse	100	97.5	91.67	62.5	100	89.45	93.33	100
Mountain	39.17	29.17	44.17	40	55	47.3	56.25	87.98
Food	52.5	76.67	45	64.17	74.17	70.9	85.83	87.88
Average	68.25	72.167	65.75	61.58	72.85	72.5	80.79	94.61

Performance evaluation on Corel1K dataset

In order to prove the robustness of DKA methodology is proved through retrieving the image, moreover we have used the Corel1K dataset, which consist of 10 different nature scene each containing 100 images. Moreover, here we have presented the top 5 response of the query, In the below figure we see that in case of African category the Figure 3 represents the query image of African category and figure 4a, 4b, 4c, 4d and 4e are the response of input query. Similarly, Figure 5 represents the query image of beach and Figure 6a, 6b, 6c, 6d and 6e are the response image of beach. Figure 7 is the query image of building and Figure 8a, 8b, 8c, 8d and 8e are response of the image.

Category: African**Query image: 1****Figure 3 query image****Image Response:**

Figure 9 is query image of Bus and Figure 10a, 10b, 10c, 10d and 10e are the response of the image. Figure 11 is the query image of dinosaur and figure 12a, 12b, 12c, 12d and 12e are the response of the image. Figure 13 is the query image of elephant and the figure 14a, 14b, 14c, 14d and 14e are response image. Figure 15 is the query image of flower and Figure 16a, 16b, 16c, 16d and 16e are the image response of flower. Figure 17 is the query image of horse and the 18a, 18b, 18c, 18d and 18e are the image response. Figure 19 is the query image of mountain and figure 20a, 20b, 20c, 20d and 20e are the image response of same, Figure 21 is the query image of food and the top response of the image response is figured in 22a, 22b, 22c, 22d and 22e.

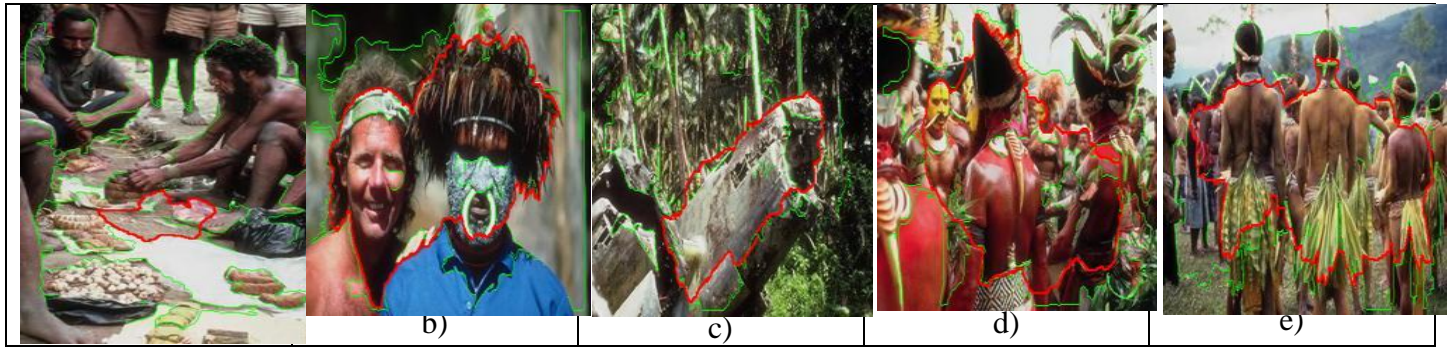


Figure 4 Response Image from datasets

Quary image:2

Category: Beach



Figure 5: Query image

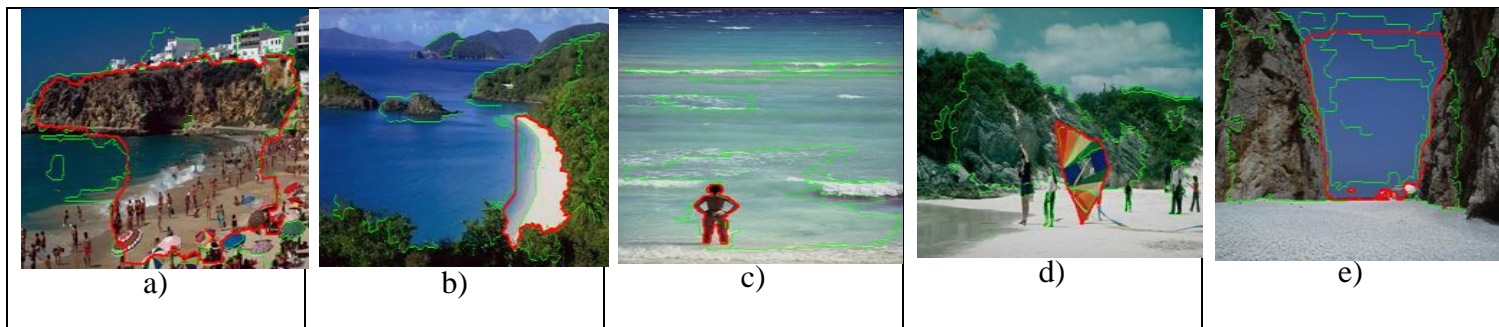


Figure 6 Top 5 response of beach images

Category: Building

Query image:3

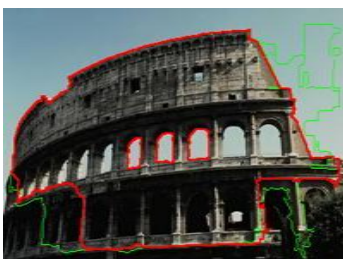


Figure 7 Query image of building Images

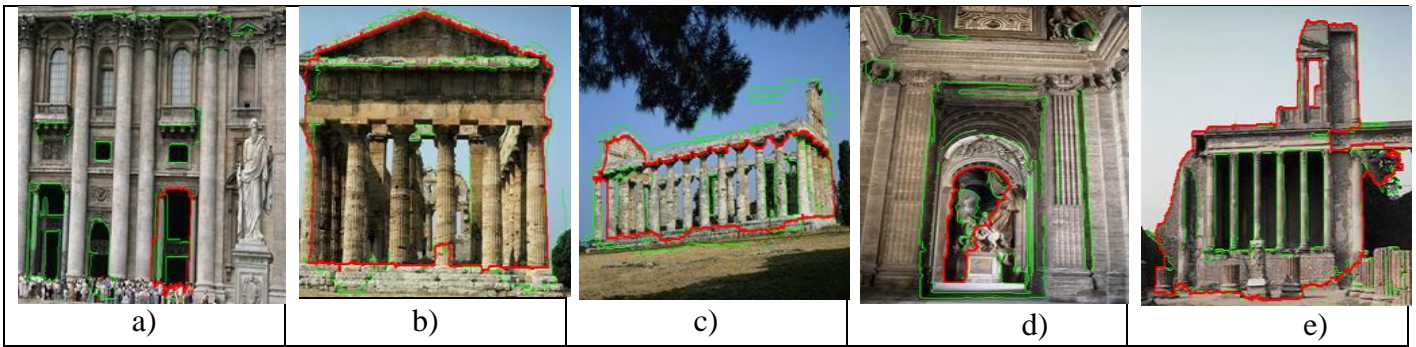


Figure 8 Top 5 response image of building category

Query image 4:



Figure 9 query image of bus category

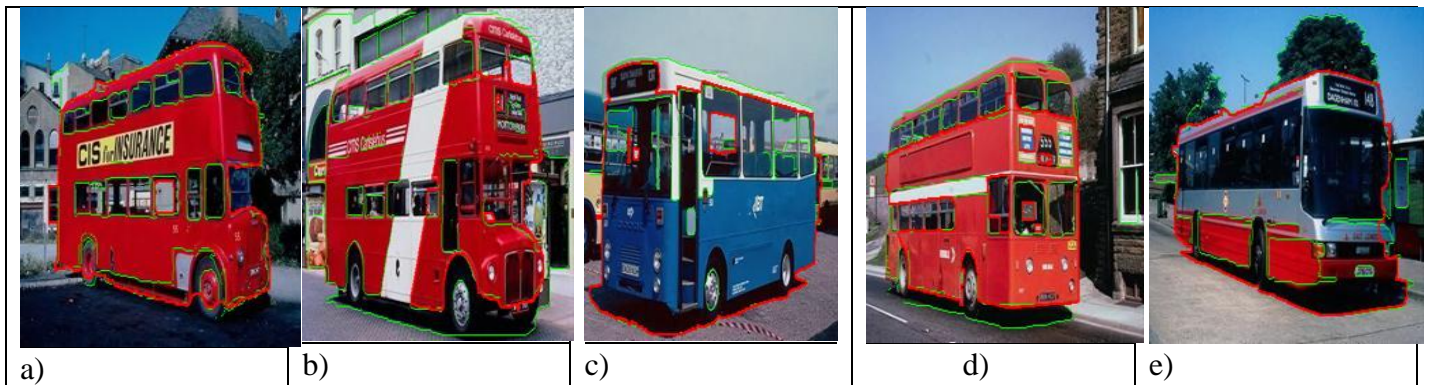


Figure 10 Top 5 response image of Bus Category

Query image 5



Figure 11 Query Images for dinosaur

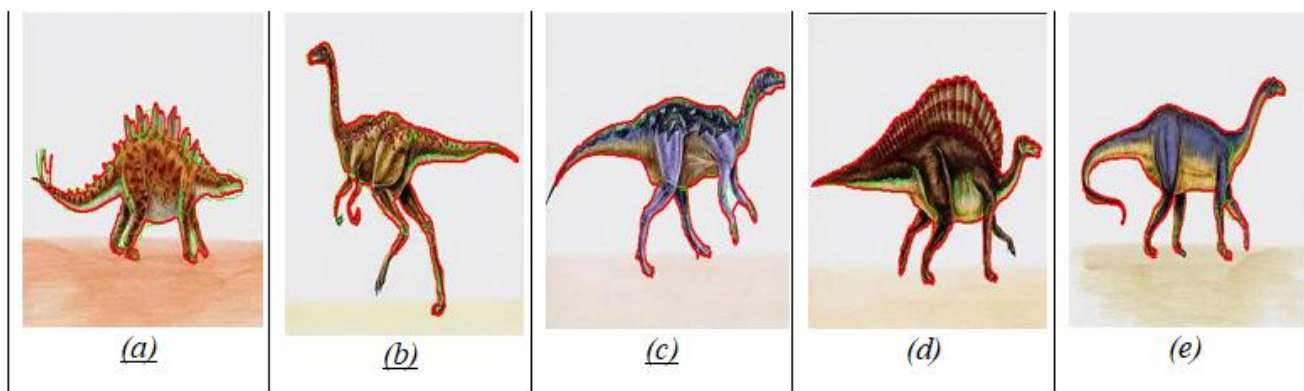


Figure 12 top 5 response images of dinosaur

Query image 6



Figure 13 query image for elephant category

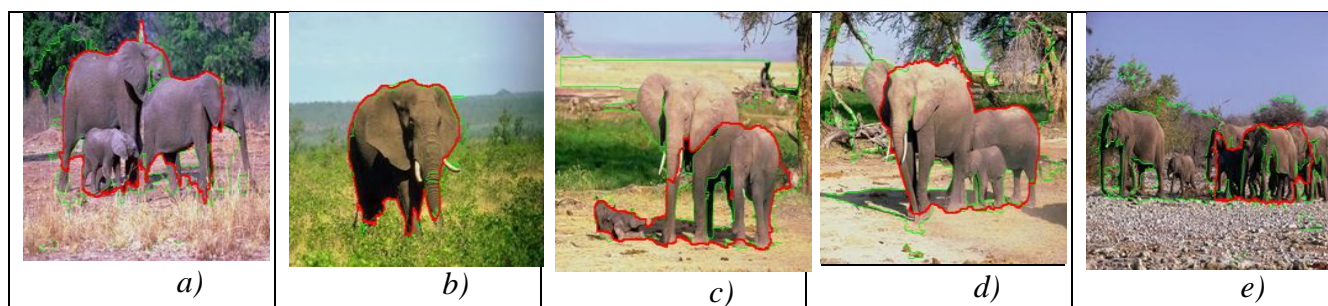


Figure 14 Response images of Elephants category

Query image 7



Figure 15 Query image of flower

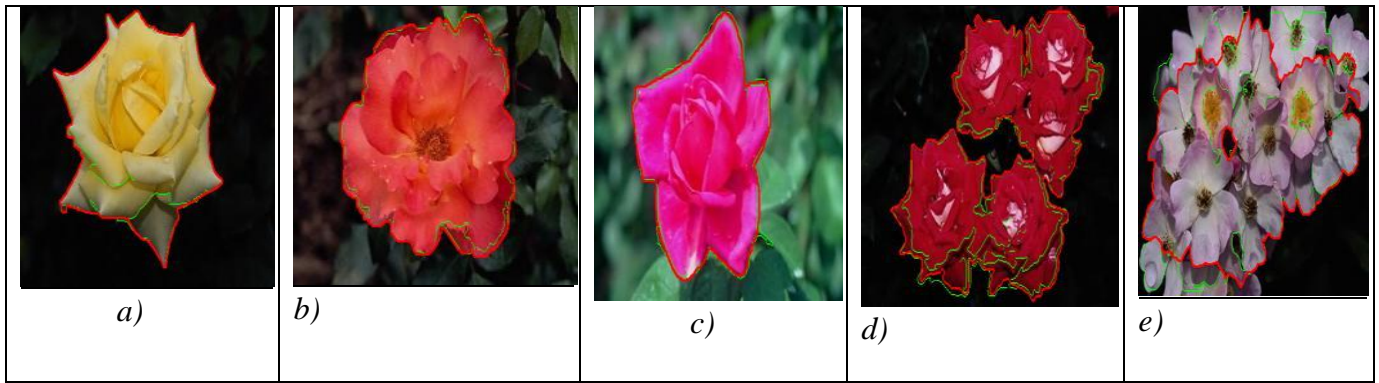


Figure 16 Response image of Flower

Query image 8



Figure 17 Query Image of Horse

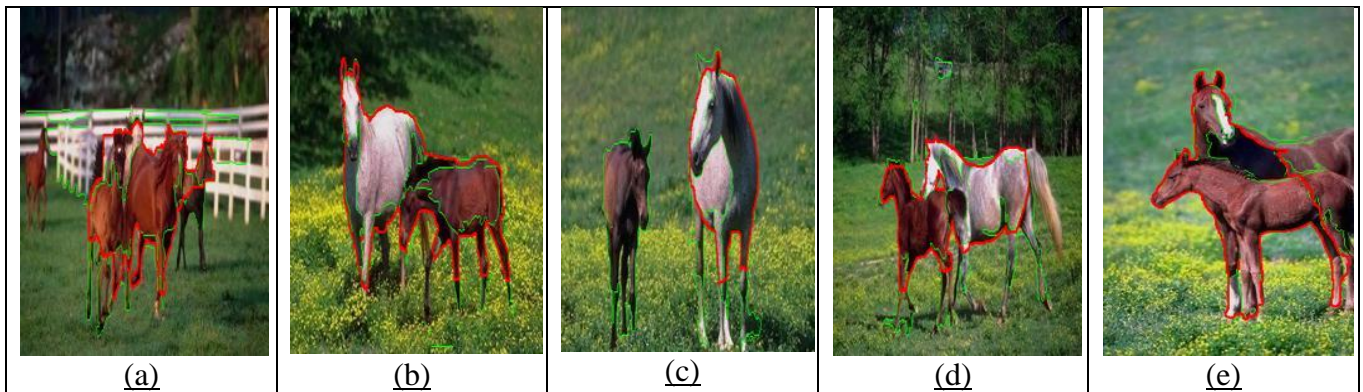


Figure 18 Response Image of Horse Category

Query Image 9

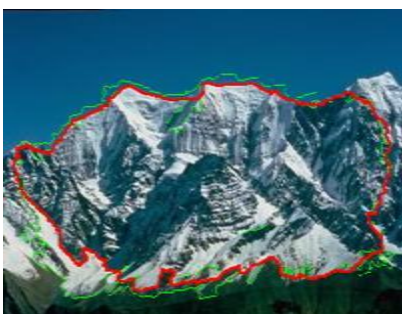


Figure 19 Query Image of Mountain

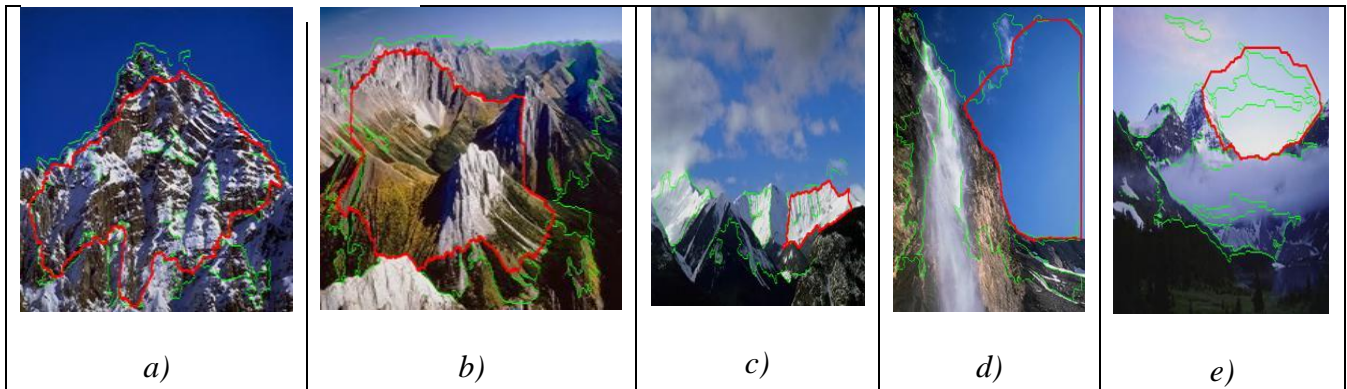


Figure 20 Response Image of Mountain Category

Query Image: 10



Figure 21 Query Image of Food

Figure 22 Response image of Food Category



VI. CONCLUSION

Over the last few years, CBIR has drawn the fine attention in the research area to retrieve the image. In this paper, we have presented a novel methodology named as Domain Knowledge Acquisition, which helps in achieving the new similarity measure. Moreover DKA methodology not only helps in achieving the similarity matching in domain but cross domain model. In order to evaluate the DKA methodology extensive simulation was done by using the Corellk Dataset. In evaluation first we have retrieved the top 5 response of the given query image, furthermore

comparative analysis is done with several state-of-art technique and existing method CPV-THF. Moreover precision is considered as the comparing parameter and we observe that average precision value of existing method is less than the proposed.

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