

Automated Brain Tumor Detection and Segmentation from MRI Images using Adaptive Connected Component Pixel Segmentation



J. Martin Sahayaraj, N.Subash, S.Jaya Pratha, N. Tamilarasan

Abstract- Magnetic resource imaging (MRI) images are used in examining the soft tissues which include brain tumors, ligament and tendon injury, spinal cord injury. Gray scale image processing is good for basic segmentation application. The exact location of brain tumor and its length is hard to find. This paper proposes an efficient method to segment the brain tumor. The result shows good segmentation accuracy.

Keywords- Connected component, Pixel Segmentation, Image morphology, Brain tumor, Brain cancer, Medical images, MRI images

I. INTRODUCTION

The unnatural growth of tissues in the brain is called brain cancer. Malignant euplastic disease is the term reserved for malignant tumors. Two types of cancers are primary and metastatic. Both Primary and metastatic brain cancer occurs in the body. But it will affect the brain. This is the second biggest cancer to death. Secondary (metastatic) brain tumors are cancer that has spread (metastasizes) to the brain that begins elsewhere in the torso. People with malignant euplastic disease often have the chance of getting secondary tumors. In very rare cases, the first signal of cancer may be a metastatic brain tumor which initiate elsewhere in the body. Compared to the primary brain neoplasm, a secondary brain tumor is found to be more common.

II. LITERATURE SURVEY

Image processing helps in extracting beneficial information by transferring image in to digital form. The most commonly used medical imaging method is MRI.

A. Brain MR Images

Brain tissues are one such type of soft tissue, and hence MRI can be used for brain segmentation, whenever delineation of soft tissue is necessary. Image segmentation in medical modalities helps to differentiate various tissue types for the purpose of visualization and volume measurement.

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There are three types of tissue in a normal healthy brain, such as cerebral-spinal fluid, white matter and gray matter. In a good quality image, these three regions can be classified manually by a simple selection of image pixel intensity values. But the choice of threshold for this intensity value selection is highly complex.

There are several non-invasive methods like MRI, computed tomography (CT), x-ray technique etc. are used in imaging the inner anatomy for screening the breasts for tumors, and the anatomy of the organs under examination provides an effective means for noninvasive mapping by using the other imaging modalities. By the development of these techniques the diagnosis and treatment for several deadly diseases can be done easily. There are several image segmentation algorithms which help in quantity tissue volume and features.

III. RELATED WORKS

Radiologist's diagnostic with Computer-Aided Diagnosis (CAD) enhance the recognition of basic disease [1]. In order to locate a bounding box around the brain abnormality in an MR image, this paper proposes a clear-cut, real-time method. This algorithm utilizes left-to-right dimension of the head structure. Pre-processing, labelled image data and training image registration are non-indispensable. It uses only two user-defined elements and can be acted as a real-time. The proposed systems can play a major part in indexing and storage of massive MRI data and provide the primary step to help algorithms designed to locate precise tumor boundaries.

All the same, the setback of the suggested algorithm is that it supposes the irregularity to be confined to the left or right side of the head and does not cross the LOS. So, the algorithm is likely to identify only the significant part of the irregularity if the tumor is split into several factions [2]. Classification of MRI brain images with the help of an automated system having diverse pathological disorders is shown in another report [3].

The method discussed in this work shows that the irregularity is categorized into malignant and benign in an unattended method. An uncomplicated categorization process using feed forward neural network is employed in this system and the rough set theory is applied to estimate the texture features.

Thus, the regularity of brain tumors is efficiently categorized by the proposed system. Another paper [4] proposes a variation method based on the propagation of intensity possibility distribution and region appearance. This helps to concentrate along the object regardless of the complexity of the uninterested background.



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A distinct confined contouring algorithm is combined with the modified K-means segmentation method for segmentation and during this process the computerized tomography image frames; five different neighbourhoods are differentiated to split the image. This method gives quick and precise segmentation and 3-D rendering define tumor parts with least user interaction.

Both anatomical and pathological information are provided by MRI images for pathological and clinical ratings. Images are segmented based on certain anatomic features by the process called division [5]. These segmented regions are assigned certain unique labels to identify each class of segmented objects.

Segments provide categorical classification results like volume size, distance between region surface and so on [6].

Binary segmentation algorithm with hybrid feature of using multiple intensity distributions to segment various images with normal and abnormal tissue came into existence [7].

Similarly, the probabilistic segmentation method is depending upon the voxels.

The contrasting features among soft tissues and diseased tissues are also discussed. Comparison of several image segmentation methods is also analysed. [8]

IV. SEGMENTATION OF IMAGE:

The splitting of an image into a set of non-overlapping region based upon certain common features is called an image segmentation [9]. Typically the image is converted into two regions, namely background and foreground. The combination of foreground and background region should give the entire image.

For an automated segmentation of image using a computer, it is a complex task to program the computer. The program is coded in such a way that the region is split under distinct boundary. Also, the pixels inside the segmentation and outside the segmentation should be distinct with certain varying features. They are

1. An image segmentation should be uniform and analogous with respect to some characteristics, e.g. grey level or texture.
2. The interior regions should be simple and without many holes.
3. It should have significantly varying values with respect to the characteristic or adjacent regions.
4. Each boundary segment should be simple, not ragged, and must be spatially accurate.

In the present work, two DCS metric is employed, i.e., (A) repeated binary segmentation of intraoperative 0.5T and preoperative 1.5T MRIs of the prostate's PZ composed during the segmentation and before brachytherapy for prostate cancer [10] and (B) composite voxel-wise gold standard uses three various types of brain tumors resulting from repeating images from expert manual segmentations [11]. Segmentations were performed for both the prostate and brain data sets and reported previously [12]. Here, the methodology is elaborated and a statistical validation review is shown using these existing databases $DSC(A, B) = 2(A \cap B) / (A + B)$

V. PROBLEM DEFINITION

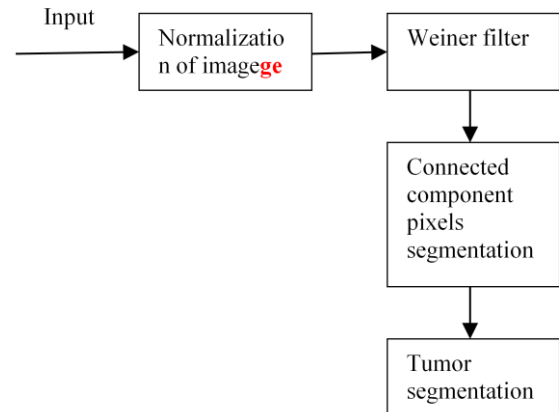
Normalized image undergoes the process of noise removed by means of Weiner filter. [13] After that the

noise removed image undergoes the process of image segmentation. Here we used two types segmentation. The first one is Region-based edge detection segmentation and the second one is Connected Component Pixels Segmentation. The first one gives the initial suspicion about the brain tumor, and the second gives the extraction of tumor cell from the given image with suitable color variation [14].

In the non-existence of better ground truth, processing of image segmentation methods is quite difficult. The results of so many users are obtainable and there is lack of better ground truth inter-observer variability is critical.

So, we planned to move to accurate segmentation of cancer cells with connected component pixel algorithm.

A. The Proposed architecture



B. Connected Component

Basics Pixel-Connectivity.

A pixel p consists of four direct neighbors, at coordinate (x, y) , four diagonal neighbors and $N_4(p)$, eight neighbors and

$N_D(p)$, $N_8(p)$ of pixel p consist of the union of $N_4(p)$ and $N_D(p)$ see [1] for a basic description [15]

The pixels p and q comprises three types of connectivity:

- i) If q lies in $N_4(p)$ it is termed as 4-connectivity;
- ii) If q lies in $N_8(p)$ it is termed as 8-connectivity;
- iii) If q lies in $N_4(p)$, or if q is in $N_D(p)$ and

$N_4(p) \cap N_4(q) = \emptyset$ it is termed as m-connectivity;

Table.I

A	1	2	3	4	5	6
1		1				1
2	1					
3				1		
4			1		1	
5				1		
6	1					

Table.II

b	1	2	3	4	5	6
1	1	1				1
2	1	1				1
3			1	1	1	
4			1	1	1	
5			1	1	1	
6	1	1				1

In this work novel computation is carried out using various dimensions of N the and the conclusion of the processing time is prepared and listed in Table1[16] for the picture with dimension of 2008K (e.g.,512*512 pixels). Fig 1 shows the different sizes of N as a function for CPU time. When N=1 division in the image do not occur and the algorithm is similar as the actual one evolved by Pfaults and Rosenfeld [17].

Table.III Original Image Divisions into 3*3Regions.

region[1]	region[2]	region[3]
region[4]	region[5]	region[6]
region[7]	region[8]	region[9]

With an I3 processor 4 GB RAM PC, it is not plausible to figure the associated segment progressively when N=1, 2 or 3. Our new calculation figures associated segment inside of 2 seconds for a picture size of 2008K with N=25. Table 4 demonstrates the examinations with different calculation with diverse size picture. As indicated by Zungia [18] a picture size of 973K can be figured in 78 second with their technique. With the quick associated part marking calculation, the picture size of 973K can be ascertained inside 0.82 seconds[19].

Fig.1showsthe next level segmentation and detection of cancer from the brain images.

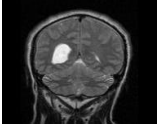


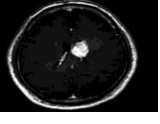
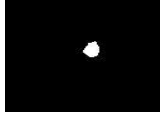
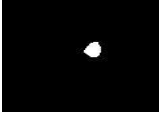
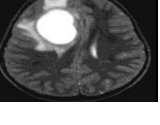


Input image	Ground truth	Output
		
		
		

Table.IV Comparison

Algorithm m	Computation time (Seconds)	DSC values
Canny	0.35	0.92
Sobel	0.30	0.90
Prewit	0.33	0.89
CCPS	0.27	0.88

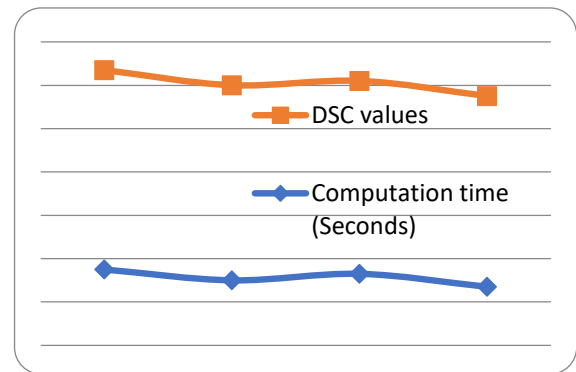


Fig.2Computation Vs DSC

VI. CONCLUSION

This segmentation is based on the connected component pixel. So the image clarity directly interacts with the output. The DSC values show that the segmentation algorithm reflects only minimum deviation from Ground Truth images. So this algorithm is acceptable one. Also this method is very fast. The early methods were designed to scan a maximum of 3 or 4 MRI images. But the proposed algorithm is designed to scan more than 100 MRI images for the detection of tumors. This tumor detection can be accomplished within 2 seconds. So the future work will move towards the classification of brain tumor affected images and normal images using suitable machine learning algorithm or neural network algorithms.

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Automated Brain Tumor Detection and Segmentation from MRI Images using Adaptive Connected Component Pixel Segmentation

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