

An Adaptation of Kernel Density Estimation for Population Abundance using Line Transect Sampling When the Shoulder Condition is Violated



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Abstract: Kernel estimation is a commonly used method to estimate the population density in line transect sampling. In general, the classical kernel estimator of $f_X(0)$, which is the probability density function at perpendicular distance x=0, inclines to be underestimated. In this study, a power transformation of perpendicular distance is proposed for the kernel estimator when the shoulder condition is violated. The mathematical properties of the proposed estimator are derived. A simulation study is also carried out for comparing the proposed estimator with the classical kernel estimators.

Keywords: line transect, power-transformation, kernel estimator, shoulder condition.

I. INTRODUCTION

Line transect technique is an easy approach that is used in practice to estimate population abundance, D, in line transect sampling. The study area under the line transect sampling is distributed as non-overlapping strips of total length L, in which the transect line is randomly placed on the strip. In each transect line, an observer follows the line to detect and count objects, and also to assign perpendicular distances (x) between the transect line and each detected object. An advantage of the method is that it is adequate to record only the perpendicular distances of the detected objects. At the end, the recorded distances $x_1, x_2, \dots x_n$ are used for estimating the probability density function of the random variable X at x=0. It should be noted that the population abundance parameter, $D=nf\left(0\right)/2L$, can be estimated using $\hat{D}=n\hat{f}\left(0\right)/2L$ [1].

Let g(x) be a non-increasing conditional probability function of detecting an object given that it is placed at a perpendicular distance x.

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Given that the random sample distances are $x_1, x_2, ... x_n$, the relation between the probability density function f(x)g(x)detection function the $f(x) = g(x)/\int g(u)du$, which indicates that the functions f(x) and g(x) have the same shape [1].In general, the shape of the detection function is related to the distribution shape at x = 0, and can be categorized into two groups; the distribution that has a shoulder at x = 0(meaning that the detection objects are closer to the transect line), and the distribution that do not have a shoulder at x = 0 (see [1], [2]). Mathematically, the shoulder condition is equivalent to f'(0) = 0. Numerically, several approaches can be used to test the data whether it belongs to the first or the second category (see [3]). However, in real data set, several studies show that the shoulder condition is violated for the line transect data of specific wildlife society (see [4], [5]). Many approaches were proposed to estimate f(0) in the literature. The most common non-parametric approach is the kernel method which allows the data to make an inference about themselves regardless of the distribution shape. An extended description of the Rosenblatt-Parzen kernel estimation method is originated by [6]. The classical kernel estimator is given by:

$$\hat{f}_X(x) = \frac{1}{nh} \sum_{i=1}^n K\left(\frac{x - x_i}{h}\right), -\infty < x < \infty$$
 (1)

where h is the bandwidth, and K(.) is the kernel function.

Let $x_1, x_2, ..., x_n$ be a random sample of non-negative perpendicular distances. Assuming that the kernel function is symmetric, the usual reflection of kernel estimator of $f_X(0)$ for these data is [7]:

$$\hat{f}_X(0) = \frac{2}{nh} \sum_{i=1}^n K\left(\frac{x_i}{h}\right)$$
 (2)



(3)

The bias and variance of estimator (2) are:

$$Bias \left[\hat{f}_X (0) \right] = 2f_X'(0) h \int_0^\infty u K(u) du + O(h^2)$$

$$Var\left[\hat{f}_{X}\left(0\right)\right] = \frac{4}{nh} f_{X}\left(0\right) \int_{0}^{\infty} K^{2}\left(u\right) duf + o\left(\frac{1}{nh}\right)$$
(4)

By ignoring the small terms o(.) and O(.); the asymptotic mean squared error (AMSE) of $\hat{f}_{X}(0)$ is:

$$AMSE\left[\hat{f}_{X}\left(0\right)\right] = \frac{4}{nh} f_{X}\left(0\right) \int_{0}^{\infty} K^{2}\left(u\right) du + \left(2f_{X}'\left(0\right)h \int_{0}^{\infty} u K\left(u\right) du\right)^{2}$$
(5)

The kernel density estimator is often used in past studies to make a good estimate of $f_X(0)$. As examples, [6] provided a full description of the method, [7] suggested the bias and variance of the estimator in equation (2), [8] proposed several bias reduction techniques for $f_X(0)$, [9] suggested a transformation method of boundary correction in the kernel density, estimation of [10] suggested semi-parametric transformation kernel density estimator, and [11] derived a new kernel estimator of $f_X(0)$ when the shoulder condition is not valid. Recently, [12] proposed several kernel estimators for $f_X(0)$, and [13] proposed a generalized form for the kernel function which is adaptive to the population density estimation. The objective of this study is to propose a power transformation of perpendicular distance for kernel estimator when the shoulder condition is violated. The mathematical properties of the proposed estimator are derived. A simulation study is also carried out for comparing the proposed estimator with the classical kernel estimators. The reminder of this paper is organized as follows. In section II we propose a new kernel estimator based on power transformation that can be applied when the shoulder condition is violated. In Section III we carry out simulation study for testing and comparing the proposed estimator with the kernel estimator. Finally, we conclude in Section IV.

II. METHODOLOGY

The classical kernel estimator in line transect sampling as shown in equation (2) provides underestimated values in some cases, and produces estimates with large negative bias (see [14]). In this paper, we propose a new kernel estimator based on power transformation that can be applied when the shoulder condition is violated. It should be noted that the

kernel estimation based on transformed data were proposed in several studies. Examples of kernel density based on transformation can be found in [15]–[17].

We propose the transformation: $Y = e^{X/w} - 1$, where $0 \le X \le w$. We apply this non-decreasing transformation function to our data. Let $f_X(x)$ be the original density function and $f_Y(y)$ be the transformed one. The original density value of $f_X(0)$ is obtained through back-transformation of $f_Y(0)$ such that

$$f_{Y}(y) = f_{X}(e^{y} - 1) \left| \frac{dx}{dy} \right|$$

$$= f_{X}(w \ln(y + 1)) \frac{w}{y + 1}, w, y \ge 0$$
(6)

so that $f_Y(0) = wf_X(0)$ when x = 0, y = 0.

The estimation of $f_X(0)$ requires $f_Y(0)/w$ to be substituted with $\hat{f}_Y(0)/w$. Using the kernel estimator shown in equation (2), the transformed kernel estimator $\hat{f}_Y(0)$ is:

$$\hat{f}_{Y}(0) = \frac{2}{nh} \sum_{i=1}^{n} K\left(\frac{y_{i}}{h}\right), \ y_{i} = e^{x_{i}/w} - 1$$
 (7)

If the Gaussian kernel function $K\left(u\right)$ is used, the values obtained from estimator (2) and estimator (7) converge to zero for x>w, considering that w is sufficiently large (such as $w\geq \max\left(x_i\right)+4h$). It can be seen that when $\left|x\operatorname{mx}_i\right|>4h$, the corresponding value of $K\left(\frac{x\operatorname{mx}_i}{h}\right)$ is

Assuming K(u) is a symmetric function, the bias and variance of $\hat{f}_{Y}(0)$ are:

$$Bias\left[\hat{f}_{Y}(0)\right] = 2hf_{Y}(0)\int_{0}^{\infty}uK(u)du$$
(8)

$$=2h\left(-wf_{X}\left(0\right)+w^{2}f_{X}^{'}\left(0\right)\right)\int_{0}^{\infty}uK\left(u\right)du$$

$$+O\left(h^{2}\right)$$
(9)

 $+h^{2}f_{Y}^{"}(0)\int_{0}^{\infty}u^{2}K(u)du+o(h^{2})$





$$Var\left[\hat{f}_{Y}(0)\right] = \frac{4}{nh} f_{Y}(0) \int_{0}^{\infty} K^{2}(u) du + o\left(\frac{1}{nh}\right)$$
(10)

$$= \frac{4}{nh} w f_X(0) \int_0^\infty K^2(u) du + o\left(\frac{1}{nh}\right)$$
(11)

If the small terms o(.) and O(.) are ignored, the asymptotic mean squared error of $\hat{f}_{Y}(0)$ is:

$$AMSE\left[\hat{f}_{Y}\left(0\right)\right] = \frac{4}{nh} w f_{X}\left(0\right) \int_{0}^{\infty} K^{2}\left(u\right) du + \left(2h\left(-w f_{X}\left(0\right) + w^{2} f_{X}^{'}\left(0\right)\right) \int_{0}^{\infty} u K\left(u\right) du\right)^{2}$$

$$(12)$$

III. SIMULATION STUDY

The $AMSE[\hat{f}_Y(0)]$ shown in (12) assumes that the sample size is large. We carry out simulation study for comparing and testing the proposed estimator with the kernel estimator using different sample sizes, which are n = 50, 100, and 200. The relative bias (RB) and the relative mean error (RME) respectively are $RB = \left\{ E[\hat{f}(0) - f(0)] \right\} / f(0)$ and $RME = \sqrt{MSE[\hat{f}(0)]} / f(0)$.

We use random samples from two density families that are commonly suggested for line transect method when the shoulder condition is violated. Four detection functions are considered for each density group to cover more possible cases. Altogether there are 8 detection functions. The two density families are:

- Beta (BE) model [18] The detection function is $g(x) = (1-x)^{\beta}$, $0 \le x \le w$, $\beta \ge 1$, and $f(x) = (1+\beta)(1-x)^{\beta}$, $0 \le x \le w$, $\beta \ge 1$. We use parameter values $\beta = 3.0, 4.0, 5.0$ and 6.0, and truncation point w = 1 for the four models.
- Negative exponential model [19] The detection function is $g(x) = e^{-\beta x}, \beta > 0, \ 0 \le x \le w \text{ , and}$ $f(x) = \beta e^{-\beta x}, \ 0 \le x \le w \text{ . We use}$

 $\beta = 1.0, 1.5, 2.0, \text{ and } 2.5 \text{ and } w = 3.0 \text{ for the four models.}$

Bandwidth selection

The choice of bandwidth h is critical in the kernel method. Several approaches were suggested in the literature to find the 'optimum' value. One of the leader method is the one that minimizes $AMSE \left[\hat{f}_Y(0) \right]$ by

(11)
$$\frac{d}{dh} AMSE \left[\hat{f}_{Y} \left(0 \right) \right] = 0$$
, which is:

$$h = \left(\frac{wf_{X}(0)\int_{0}^{\infty}K^{2}(u)du}{2n(-wf_{X}(0)+w^{2}f_{X}'(0))^{2}(\int_{0}^{\infty}uK(u)du)^{2}}\right)^{1/3}$$
(13)

The performances of the kernel estimator in equation (2) are approximately the same when the symmetric kernel functions based on the mean squared error are used [20]. Therefore, the estimation results using the common kernel functions (Gaussian, biweight, and Epanechnikov) are approximately the same. Therefore, we consider the Gaussian kernel function and use the following estimators for comparison purposes:

• Estimator 1 (Est1): The classical kernel estimator in equation (2) is applied to the original data without transformation using the bandwidth recommended

by [6]:
$$h = 1.06 \, \text{bh}^{-\frac{1}{5}}$$
, where $\hat{\sigma} = \sqrt{\sum_{i=1}^{n} x_i^2 / n}$.

• Estimator 2 (Est2): The proposed kernel estimator in equation (7) is applied to the transformed data using the bandwidth from equation (13). The kernel function K(u) is assumed to be Gaussian distributed, and the unknown values of $f_X(0)$ and $f_X(0)$ are estimated using a suitable reference density function (see [2], [6], [21]–[23]). When the shoulder condition is violated, the suitable reference distribution model for $f_X(x)$ is the negative exponential model. Using maximum likelihood estimators $(\hat{f}_X(0) = \frac{1}{r})$ and

$$\left(\hat{f}_X'\left(0\right) = \frac{-1}{\overline{x}^2}\right)$$
, the bandwidth is

$$h = \left(\frac{w\left(\frac{1}{\overline{x}}\right)\left(\frac{1}{4\sqrt{\pi}}\right)}{2n\left(-w\left(\frac{1}{\overline{x}}\right) + w^2\left(\frac{-1}{\overline{x}^2}\right)\right)^2\left(\frac{1}{\sqrt{2\pi}}\right)^2}\right)^{1/3}$$



$$= \left(\frac{\left(\sqrt{\pi}\right)\left(\overline{x}\right)^3}{4nw\left(\overline{x}+w\right)^2}\right)^{1/3}$$

Table 1 and Table 2 show that the transformed estimator (Est2) has smaller absolute RB and RME than the original kernel estimator (Est1) under each density families.

Moreover, the RME of (Est2) decrease as the sample sizes increase. Therefore it is concluded that (Est2) is asymptotically more consistent. The results are illustrated in Figure 1.

Table 1. Simulation results of beta model

		n=50		n=100		n=200	
	Estimator	RB	RME	RB	RME	RB	RME
β=3	Est1	-0.2487	0.2703	-0.2288	0.2433	-0.1986	0.2082
	Est2	-0.0970	0.2625	-0.0904	0.2148	-0.0656	0.1640
β=4	Est1	-0.2681	0.2867	-0.2430	0.2550	-0.2189	0.2276
	Est2	-0.1030	0.2531	-0.0789	0.2093	-0.0638	0.1689
β=5	Est1	-0.2911	0.3090	-0.2614	0.2725	-0.2292	0.2366
	Est2	-0.1247	0.2652	-0.0973	0.2081	-0.0793	0.1709
β=6	Est1	-0.2953	0.3122	-0.2672	0.2783	-0.2428	0.2498
	Est2	-0.1095	0.2578	-0.0937	0.2094	-0.0750	0.1634

Table 2. Simulation results of negative exponential model

		n=50		n=100		n=200	
	Estimator	RB	RME	RB	RME	RB	RME
β=1.0	Est1	-0.2823	0.3014	-0.2439	0.2561	-0.2135	0.2218
	Est2	-0.1106	0.2658	-0.0644	0.2068	-0.0386	0.1619
β=1.5	Est1	-0.3390	0.3515	-0.3133	0.3216	-0.2788	0.2845
	Est2	-0.1289	0.2614	-0.1054	0.2099	-0.0916	0.1708
β=2.0	Est1	-0.3631	0.3755	-0.3257	0.3333	-0.2982	0.3029
	Est2	-0.1511	0.2670	-0.1096	0.2007	-0.0883	0.1606
β=2.5	Est1	-0.3669	0.3781	-0.3347	0.3418	-0.3078	0.3126
ρ=2.5	Est2	-0.1512	0.2624	-0.1177	0.2049	-0.1046	0.1730

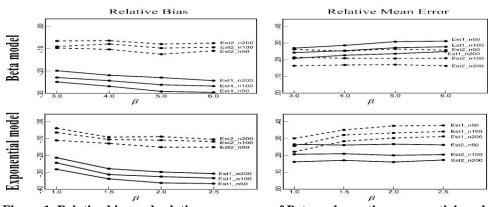


Figure 1. Relative bias and relative mean error of Beta and negative exponential models

IV. CONCLUSION

This study proposed an adaptation of the kernel estimator for population abundance (density) using line transect sampling. The adapted kernel estimator is a power-transformation which is applied to the perpendicular distances. When the shoulder condition is violated, the proposed kernel estimator is shown to be more efficient and consistent than the classical kernel estimator. The asymptotic properties (bias, variance and AMSE) were derived for the

proposed estimator. The results of simulation study show that the proposed estimator has superior performance than the classical reflection of kernel estimators, in terms of relative bias, relative mean error for each density family.

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