

# Accuracy of Detection and Classification of DC Faults using Levenberg Marquardt Based Back Propagation Algorithm



Sujit Kumar, Neel Kamal, Pankaj Kumar, Aditya Gaur, Vikash Tiwari

**Abstract:** Vitality is seen as a prime administrator in the time of wealth and a vital figure budgetary headway. Obligated fossil resources and natural issues associated with them have underscored the necessity for new reasonable vitality supply choices that uses sustainable power sources. Among open developments for essentialness age from solar dependent sources, the photovoltaic system might give a gigantic pledge to develop a progressively feasible imperativeness structure. This paper presents accuracy of detecting DC faults in a photovoltaic (PV) framework based on Levenberg - Marquardt (LM) neural network. The result showed that this model based on LM neural network is effectual to grip doubts and nonlinearities of DC side faults in PV module without using mathematical model. All probable faults in DC side of PV system are obtained over 100 kW plant. It is discovered that the proposed framework has demonstrated its integrity for the pragmatic applications.

**Keywords:** Levenberg - Marquardt (LM) Neural Network, 100 Kw PV Array, 11 Kv Grid, DC Side Faults, Grid Connected PV System.

## I. INTRODUCTION

As of late, there is an unforeseen power concern appeared throughout the world. Regardless, experts found that using the sustainable power sources gives a key of answers for this issue. PV systems speak to a basic territory in the feasible power source. They supported in light of their clean and eco-accommodating for the earth. They have been adequately used for certain applications [1]. This advancement has been coordinated with investigation into increasingly proficient solar frameworks.

Revised Manuscript Received on April 30, 2020.

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Productivity is determined as the proportion of occurrence solar vitality towards the greatest achievable yield power, with the ongoing evidence being a proficiency of forty four % [2]. The suitability of sun panels normally goes all through the framework, since any misfortunes will intrude on the last skill of the entire framework. Fig. 1 displays a distinctive configuration of a grid-connected PV System (GCPV).

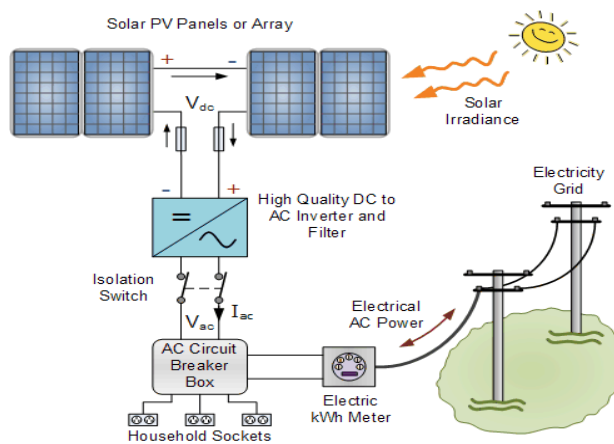


Fig. 1. Schematics of a generalized PV framework

Solar irradiance level and the temperature are the two output characteristics which decide the output of the panel and also force to employ a charger unit that pedals the PV output ( $V_{PV}$ ,  $I_{PV}$ ) and delivers the power to the load. Ensuring the high-quality routine action of the PV cells is extremely imperative job. But, due to faults the capability of the PV systems gets affected. PV cell faults in the panel causes two trouble: (1) results in reverse bias operation which may result in hot spots and cause more faulty PV cells, (2) reduction in the current [3]. Some of the fault detection techniques in PV systems have been developed which are shown in below Table 1. (GCPV). In this paper, detection and classification of every single conceivable fault in DC side GCPV system are introduced, where 100 kW array linked with an 11 kV network.

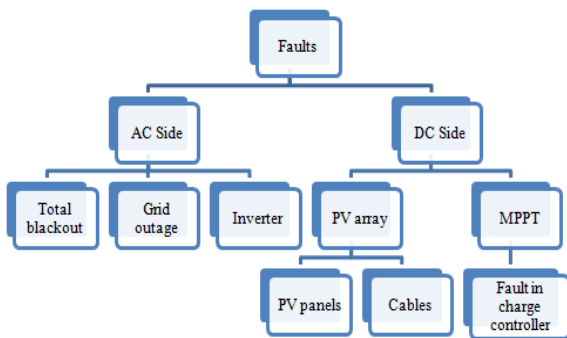


**Table- I: Fault detection techniques in PV systems**

S.No.	Methods Developed	Findings
1.	Earth capacitance measurement (ECM) [4]	Disconnection of PV module in a string is located by an electrical method.
2.	Time-domain reflectometry (TDR) [5]	Not only detection however measures the impedance varies owing to deprivation.
3.	Statistical method based on the ANOVA (Analysis of Variance) test and nonparametric Kruskale-Wallis test [6]	High level of accuracy and fast in fault diagnosis. [6]
4.	Remote monitoring and fault detection method [7]	Uses climate data from satellites observation [8].
5.	Learning techniques [10]	Observes system process and support of the PV framework, regardless of the possibility that it needs various inference sensors, which distinguish shading and inverter failure.
6.	Estimation sensors [11]	Can classify four types of faults: 1) supported zero efficacy faults, 2) brief zero efficacy faults, 3) shading, and 4) non-zero efficacy non-shading issues.
7.	Modest investigative method [12]	With a small number of sensors it can categorize the various faults.
8.	Blocking diode method [13]	Double line fault occurred beneath short light circumstances which were detected by the presence of blocking diode.
9.	Expanded relationship function and element module method [14]	Identifies the malfunction accurately and quickly.
10.	(- dI/dV) - V characteristic method [15]	Partial shadow phenomenon is distinguished in this method.
11.	Decision trees (DT) method [16]	Fault location and classification strategy has been shown with poor accuracy.
12.	Wavelet transform technique [17]	Identifies the fault occurring on the power conditioning system of the PV plant.
13.	Programmed based fault detection technique [18]	Four types of faults has been classified: 1) defective arrays in a cord, 2) broken cord, 3) forged alert and 4) deficient shadow, maturing, and MPPT fault.

**II. CATEGORIZATION OF GCPV FAULT**

It can be categorized as: DC side and AC side shown in Fig. 2 [19].



**Fig. 2. Fault Classification associated with PV array**

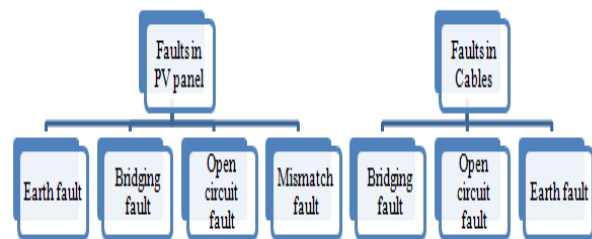
Here, in this we report only DC side faults.

**A. DC side Faults**

The faults arise in DC side of the GCPV system is categorized into two main types: PV array Fault and MPPT Fault [19].

*1. PV Array Faults*

PV array faults include two core groups [19] shown in Fig. 3.



**Fig. 3. Fault Classification associated with PV array**

*2. Maximum Power Point Tracking (MPPT) Faults*

The presentation of this fault reduces when the breakdown happens in charge modules. When fault occur in MPPT the output voltage and the output power reduces.

**III. MODELING OF PROPOSED SYSTEM**

The performance of nervous system in the brains of human is largely replicated by artificial neural network (ANN) [20]. ANNs have been functionalized productively in numerous areas presented in [21].

Usually, these methods have three fundamental processes; information compilation, information preparation (or knowledge) development and output justification.

These methods have various preparation algorithms like back propagation (BP), Levenberg Marquardt (LM), radial basis function (RBF), etc. LM algorithm is higher to other algorithms because of it's a lesser amount of end time and precision [22]. Fig. 4 [22] shows the architecture of proposed model.

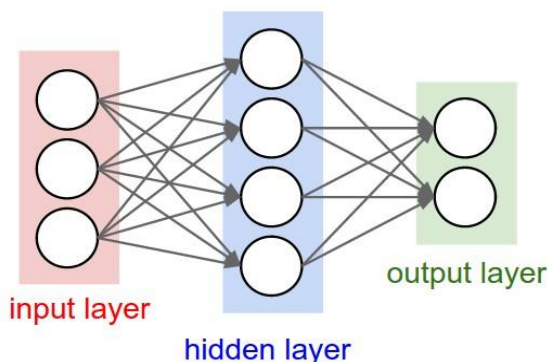


Fig. 4. Architecture of ANN

Here, PV current, voltage, module temperature, solar irradiance and power in normal bright days have been measured shown in Table 2.

There are five inputs fed to the ANN; PV voltages (V<sub>pv</sub>), currents (I<sub>pv</sub>) and power (P), irradiance (G) and module temperature (T). 5-types of the faults were trained in the projected model. There were five output numbers (1 – 5) which represents the DC faults in PV system, O1: signifies the deprivation condition, O2: signifies the SC condition, O3: signifies the OC condition, O4: signifies the fractional darkness. O5: signifies the charge controller collapse condition.

From table 2 we have taken two data; module temperature and irradiance value as 39<sup>o</sup>, 45<sup>o</sup> and 270, 750 Watt/m<sup>2</sup> respectively for simulation results.

IV. RESULTS AND DISCUSSION

Every probable fault of GCPV (DC) is simulated with 100 kW array connected to an 11 kV grid, and the measured data has been fed to ANN by MATLAB model.. The greatest selection consists of 5 – 40 – 6 illustrated in Fig. 5.

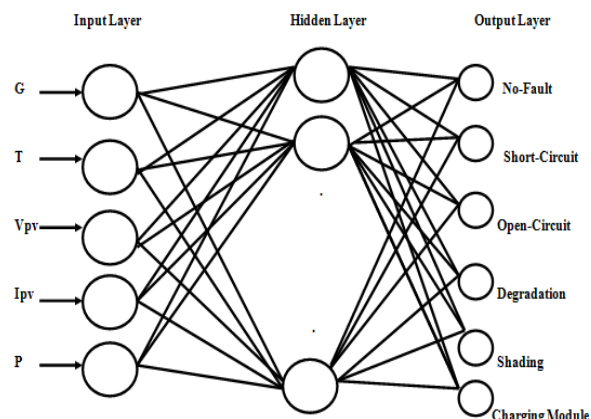


Fig. 5. Proposed ANN Network

Table- II: Measured data from solar panel

Occasion (a.m/p.m)	Voltage (V)	Currents (A)	Power (Watts)	Solar irradiance (Watt/m <sup>2</sup> )	Module temperature
9:30 a.m	10.97	2.80	30.72	276	39.40 <sup>o</sup>
10:30 a.m	11.01	2.95	38.72	340	40.40 <sup>o</sup>
11:30 a.m	13.85	6.6	91.47	465	43.10 <sup>o</sup>
12:30 p.m	18.71	7.6	142.2	764	48.68 <sup>o</sup>
1:00 p.m	22.83	8.1	185	997	57.50 <sup>o</sup>
1:30 p.m	20.83	7.1	180	985	54.50 <sup>o</sup>
9:30 a.m	10.87	2.89	34.72	283	40.40 <sup>o</sup>
10:30 a.m	11.21	2.99	39.72	348	41.40 <sup>o</sup>
11:30 a.m	12.6	4.5	56.72	276	44.20
12:30 p.m	1971	7.9	162.2	802	50.68 <sup>o</sup>
1:00 p.m	22.93	8.5	196	992	55.50 <sup>o</sup>
1:30 p.m	20.43	6.9	175	979	52.50 <sup>o</sup>

For preparation mean squared error (MSE) is used as presentation purpose and is given by [23] revealed in equation (1):

$$E = \frac{1}{n} \left( \gamma \sum_{i=1}^n e^2 + (1 - \gamma) \sum_{j=1}^n w_j^2 \right) \tag{1}$$

For updating the weights and biases of the network we use equation (1) for Levenberg Marquardt (LM) programming [23], broadly utilized in an extroverted area.

Parameters trained for ANN programming:

- Teaching pattern = 5295
- Knowledge tempo = 0.001

Point error set = 0.01

Valid rate = 1000

Thrust = 0.95

Three miscellaneous accurate markers were utilized toward justification of the system. These are shown in equations 2, 3 and 4:

$$MAE = \frac{1}{n} \sum_{i=1}^n |Y_{predicted} - Y_{true}| \tag{2}$$

$$MSE = \frac{1}{n} \sum_{i=1}^n (Y_{predicted} - Y_{true})^2 \quad (3)$$

$$MAPE = \frac{1}{n} \sum_{i=1}^n \left| \frac{Y_{predicted} - Y_{true}}{Y_{true}} \right| \quad (4)$$

where  $Y_{predicted}$  and  $Y_{true}$  are probable and actual fault values over panels respectively. From the three markers MAPE and MSE are used whose output have less fluctuation when deals with sample to sample variation [22].

MSE achieved is  $9.99 \times 10^{-3}$  which is fine under the point error in 1000 valid rates as revealed in Fig. 6. Accurateness of

training was proved by validation means the data which were not included in the training were also validated properly and the MSE obtained from validation found  $8.3857 \times 10^{-3}$ . Table 3 represents the simulated results obtained from the proposed artificial neural network system.

Table- III: Simulated results obtained from an ANN

Surrounding Circumstances			Replication Results	
Fault Type	Warm °C	Radiation Level (W/m <sup>2</sup> )	ANN System	
			Accuracy	Time (sec.)
No-Fault	39	270	99.3	5.6
	45	750	99.01	5.3
Short-Circuit	39	270	99.1	6.1
	45	750	98.9	6.2
Open-Circuit	39	270	99.5	5.8
	45	750	99.1	5.9
Degradation	39	270	99.6	5.5
	45	750	99.3	5.3
Shading	39	270	99.7	6.4
	45	750	99.2	5.9
Charging Module	39	270	98	6.7
	45	750	98.7	5.9

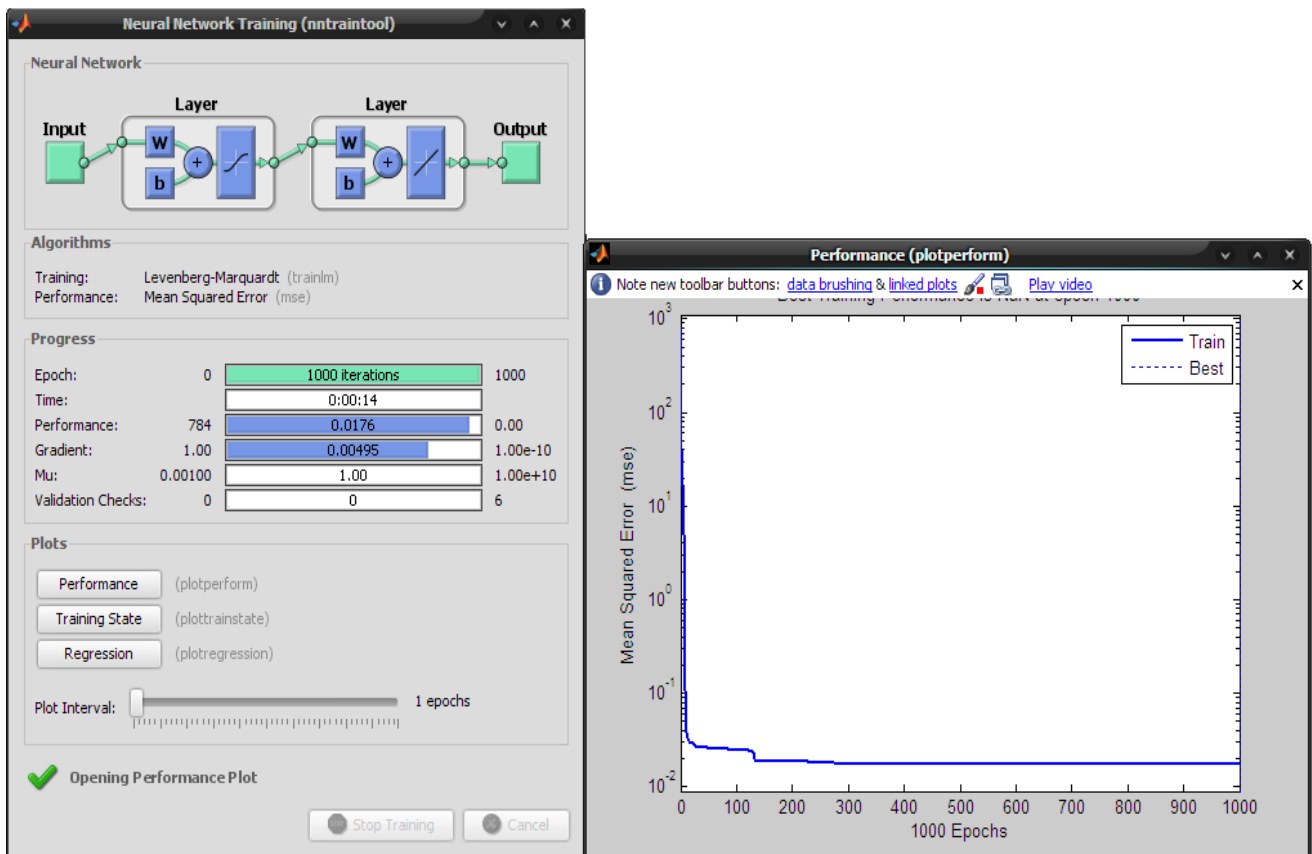


Fig. 6. Training results of ANN in Matlab Simulink and evolution of the performance error



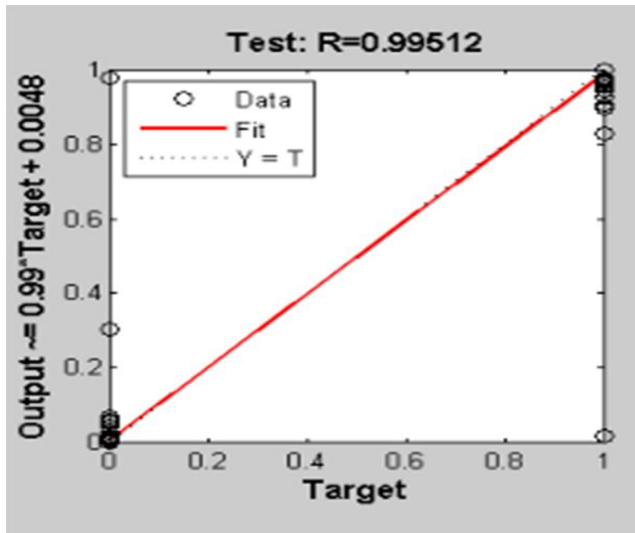


Fig. 7. Test phase performance of ANN model

The overall data set and results were shown in Fig. 7. Network test error obtained as 1.02023e-3 and regression coefficient (R) obtained as 9.8401e-1.

MAPE for the proposed model found to be 0.5% also, Fig. 8 shows the confusion matrix which tells that the faults are accurately classified and tested with the other fault samples which were not trained in the training period. (O1 – O5, explained in section 3)

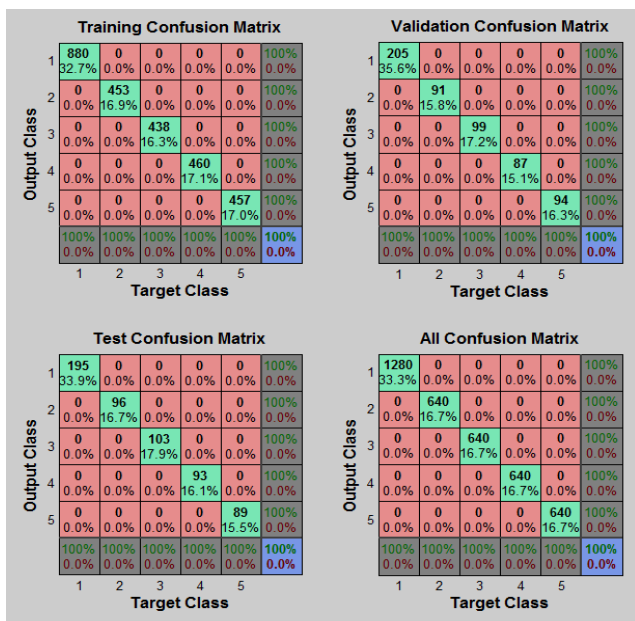


Fig. 8. Confusion Matrix with proper classification of all DC faults

V. CONCLUSION

The detection, classification, simulation and discussion of all possible faults in DC side of a GCPV system have been presented. Different fault conditions with their output power waveforms are plotted. The fault can be effortlessly recognized by relating the output powers with no fault condition. Trouble free ANN model has been developed that detect and classify the fault on solar panel of 250 Wp. The results show that ANN has potential to effectively detect the fault information with a precision of 100%.

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